AN12919

Introduction to Boundary Scan of i.MX RT Series

Rev. 1 — March 2, 2021 Application Note

1 Overview

This document focuses on the procedure of entering boundary scan mode for board-level test. It provides the setup sequence and script examples to ensure first-pass success.

Engineers should understand the standard for test access port and boundary scan architecture from IEEE 1149.1.

1.1 Boundary Scan

Boundary scan is a method for testing interconnects on PCBs and internal IC sub-blocks. It is defined in the IEEE 1149.1 standard.

In boundary scan test, each primary input and output signal on a device is supplemented with a multi-purpose memory element called a boundary scan cell. These cells are connected to a shift register, which is referred to as the boundary scan register. This register can be used to read and write port states.

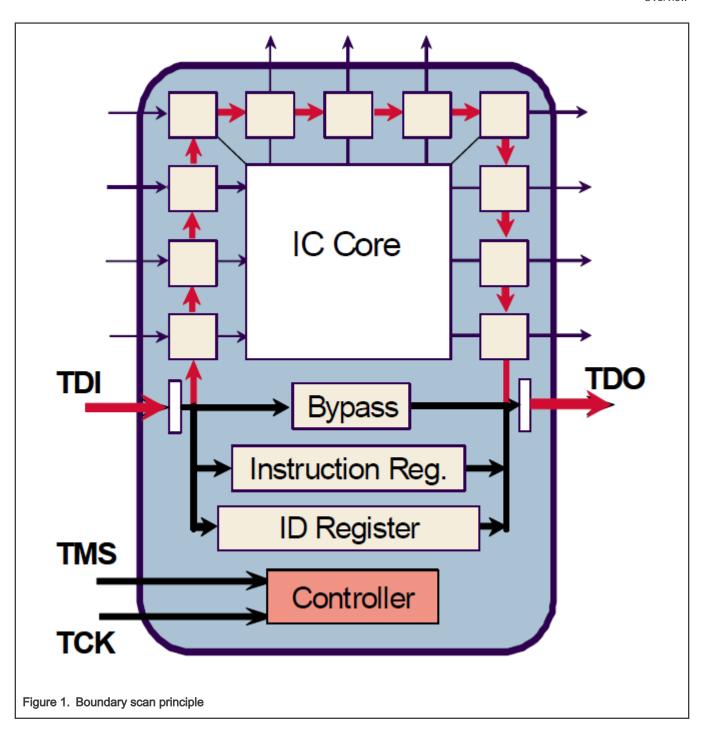
In normal mode, these cells are transparent and the core is connected to the ports. In boundary scan mode, the core is isolated from the ports and the port signals are controlled by the JTAG interface.

Figure 1 shows the principle of boundary scan chain.

Contents

1	Overview 1	
1.1	Boundary Scan1	
1.2	Test Access Port (TAP) JTAG 2	
2	Installing software3	
3	Hardware connection diagram 3	
4	BSDL file validation using Lauterbach	
	JTAG debugger8	
5	Introduction to other EVK board of	
	i.MX RT series13	
6	Revision history14	





1.2 Test Access Port (TAP) JTAG

The TAP is a general-purpose port and it can provide access to many test support functions built into the component. It has four or five signals, as described in Table 1.

Table 1. JTAG pin signal description

Signal name	I/O type	Description
TCK	Input	The test clock input provides the clock for the test logic.
TMS	Input	The value of the signal present at TMS at the time of a rising edge at TCK determines the next state of the TAP controller.
TDI	Input	Serial test instructions and data are received by the test logic.
TDO	Output	Serial output for test instructions and data from the test logic.
TRST_N	Input	Optional active low signal to reset the TAP controller.

2 Installing software

The TRACE32 installation package can be found on the Lauterbach page.

Download the TRACE32_201909.7z to the computer and install it.

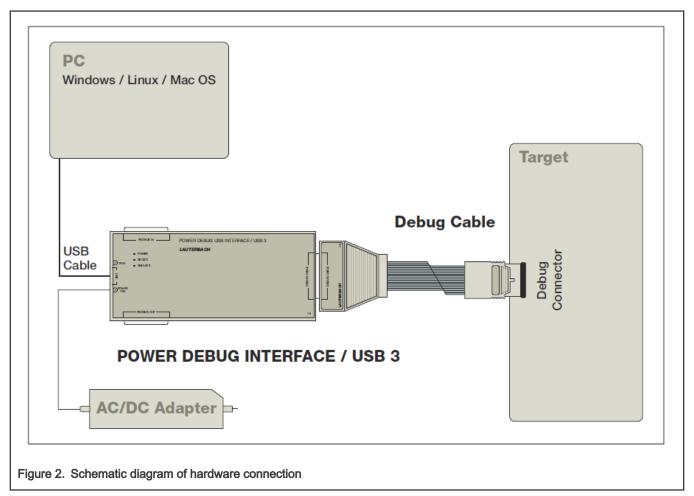
- 1. Because the installation package is relatively large, you can install software components according to the target processor to save hard disk space.
- 2. You can find installed driver at C:\T32\bin\windows64\drivers.

3 Hardware connection diagram

The TRACE32 debugger hardware always consists of:

- · Universal debugger hardware
- · Debug cable specific to the processor architecture

Figure 2 is a schematic diagram of hardware connection.



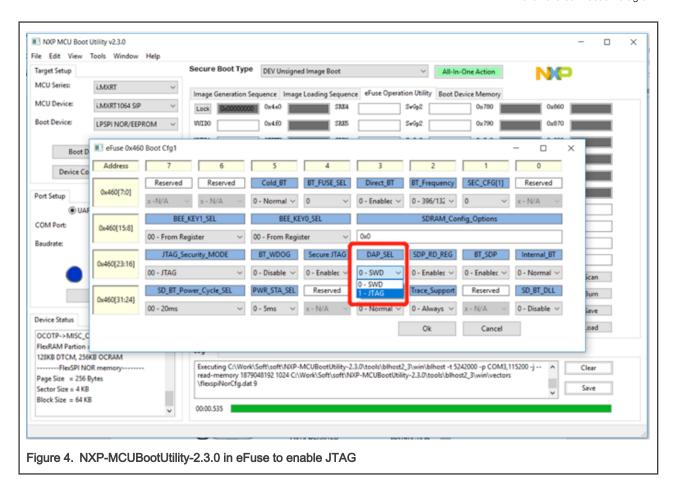
Suggestions for users include:

- To prevent the debuggers or target being damaged, it is forbidden to plug or unplug the debugger while target is powered on. The recommended sequence for powering on or off is as follow:
 - Power on: debugger >target
 - Power off: target >debugger
- The debugger interface has pin1. Please double check the direction to prevent damages to the debugger or target.
- It is recommended to press F1 to enter the on-line help system to get familiar with debugger.
- 1. Taking RT1064 EVK board as an example, the hardware connection is as shown in Figure 3.
 - a. Connect Lauterbach JTAG debugger to the EVK board by the 20pin JTAG interface.
 - b. Connect to the PC through the USB cable, and then power on the debugger with a 5 V power adapter.
 - c. Connect the EVK USB port to the PC.



Figure 3. RT1064 EVK board hardware connection

2. Apply the NXP-MCUBootUtility-2.3.0 to burn one bit, 0x460 Boot Cfg1, in eFuse to enable JTAG. It can't go back to SWD after eFuse burn. Figure 4 shows the setup information.



3. Check the signals of three pins, TEST_MODE, GPIO_AD_BO_08, POR_B, according to the settings corresponding to the COMPLIANCE_PATTERN part of the BSDL file. They should have the same status, 011, on the EVK board. Figure 5 is compliance patterns part of the BSDL file. Figure 6 shows test mode and the por b connection.

attribute COMPLIANCE PATTERNS of MX6RT: entity is "(TEST_MODE, GPIO_AD_BO_08, POR_B) (011)";

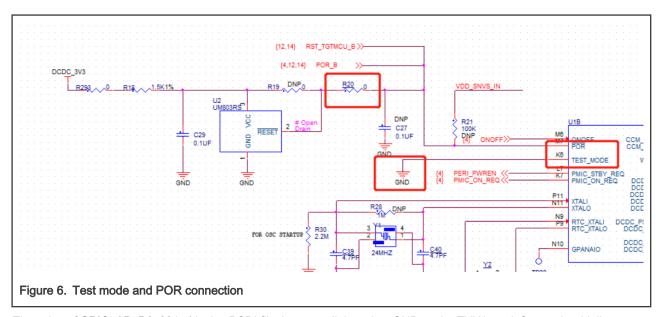
(011) 0 means low level, 1 means high level

Figure 5. COMPLIANCE_PATTERN PART OF BSDL FILE

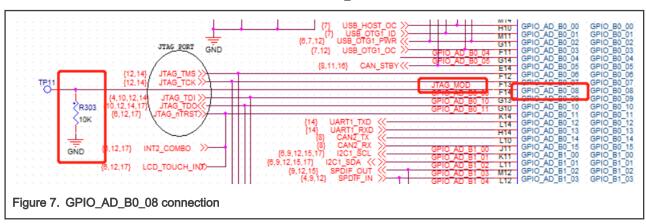
Introduction to Boundary Scan of i.MX RT Series, Rev. 1, March 2, 2021

Application Note

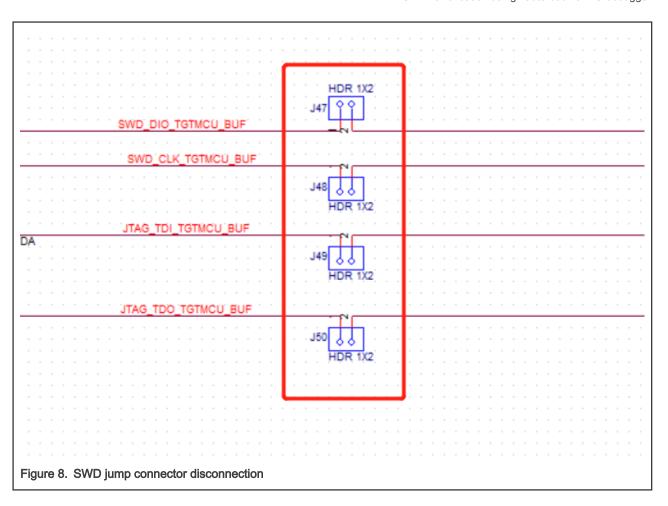
7 / 15



4. The value of **GPIO_AD_B0_08** is **1** in the *BSDL* file, but we pull down it to GND on the EVK board. So we should disconnect the resistor R303 ground terminal, and pull up this pin with DCDC 3V3.



5. We used OPENSDA circuit on the RT1064 EVK board, which will affect the JTAG signal level during the Boundary Scan test. So we should disconnect the SWD jump connectors, **J47**, **J48**, **J49**, and **J50**. Figure 8 shows SWD jump connector disconnection.



4 BSDL file validation using Lauterbach JTAG debugger

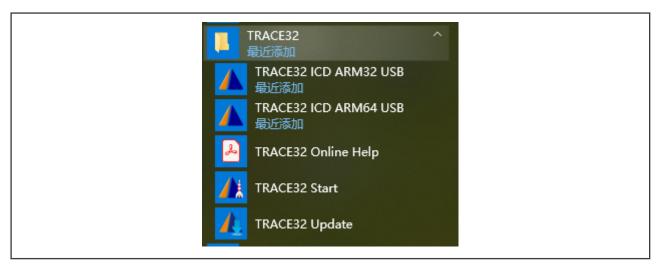
1. Trace32 Devices should appear in the Device Manager.



NOTE

Lauterbach JTAG debugger recommended is LA-4533 Debug-USB3, with LA-7960/4513. Related information can be found on the lauterbach page.

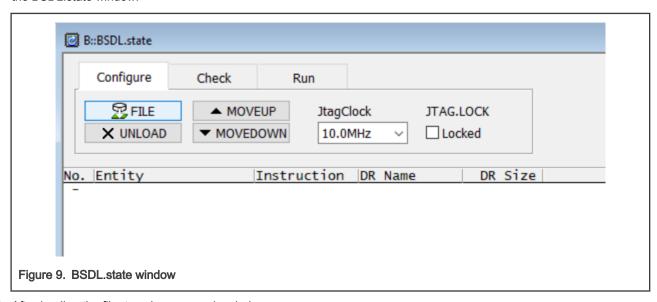
2. Open the TRACE32 software and choose ARM32 USB.



3. Type in below commands, with each command followed by entering:

```
SYStem.Down
BSDL.RESet
BSDL.ParkState Select-DR-Scan
BSDL.state
```

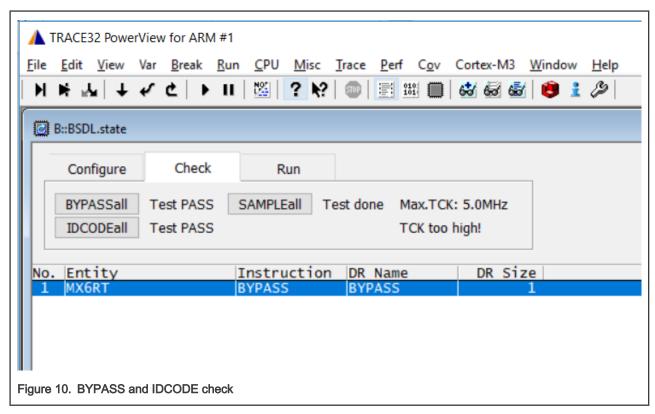
4. BSDL.state window should now appear. Click the FILE button and load the BSDL file you want to validate. Figure 9 shows the BSDL.state window.



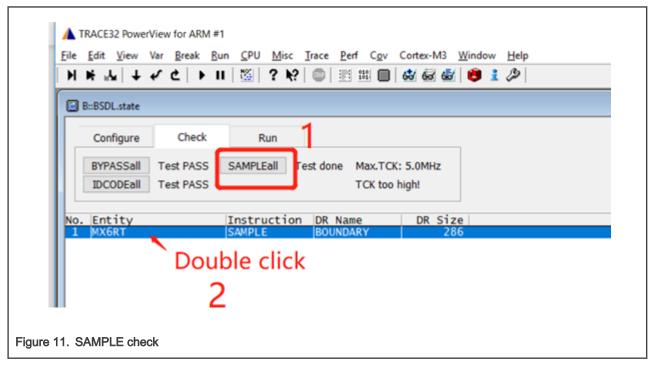
5. After loading the file, type in command as below:

BSDL.SOFTRESET

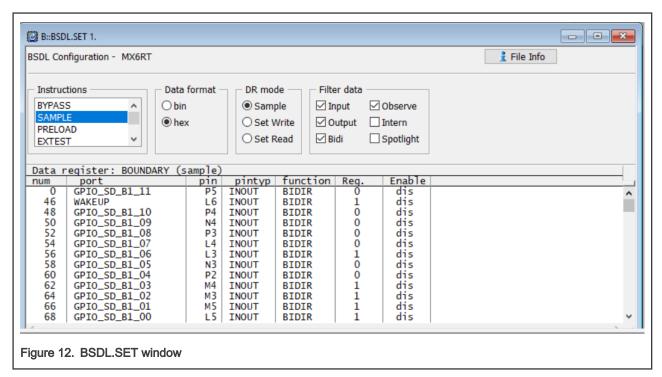
6. Switch to the Check tab of the BSDL.state window. Click BYPASSall and IDCODEall button to see if both results can pass. The BYPASS/CLAMP/HIGHZ check pass, as shown in Figure 10.



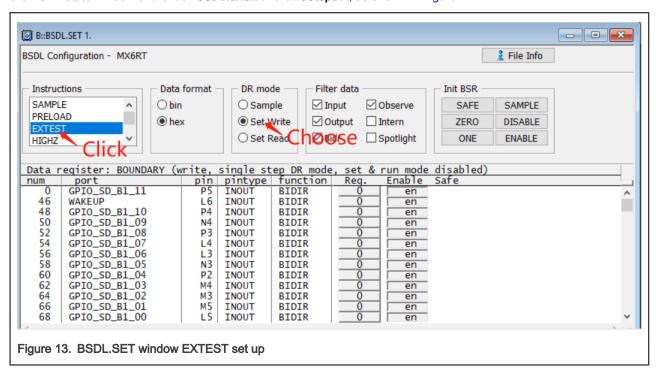
7. Click the **SAMPLEall** button, and you will see **No result** becomes **Test done**. Double click the entity name, and the BSDL.SET window appears, as shown in Figure 11.

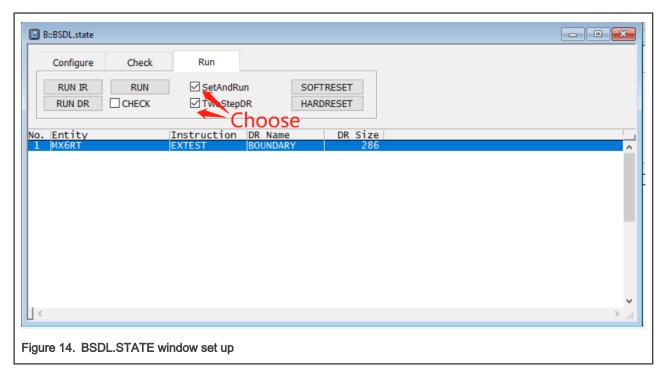


8. In the BSDL.SET window, uncheck **Intern** to filter out the internal registers. The remaining contents are the sampled value on each signal pins. Use a multimeter to measure voltage of at least three signal pins, and see if the logic state matches the sampled value. SAMPLE check pass, Figure 12 shows BSDL.SET window.

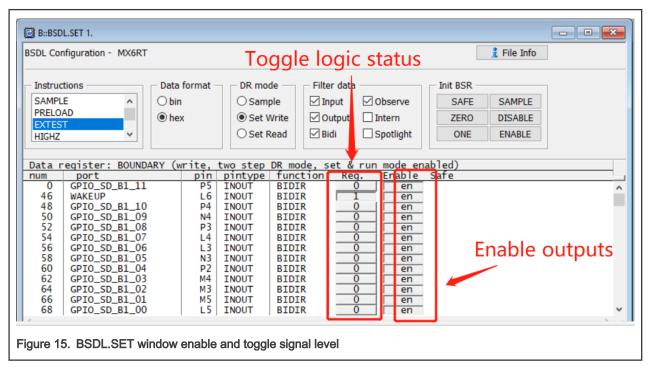


9. In the **Instructions** field, click **EXTEST** and in the **DR mode** field, choose **Set Write** as shown in Figure 13. Then switch to the BSDL.state window and check **SetAndRun** and **TwoStepDR**, as shown in Figure 14.

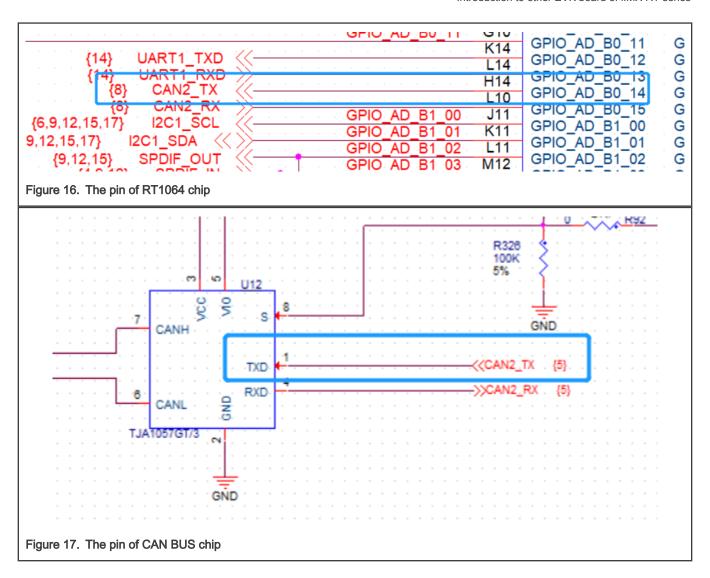




10. Switch back to BSDL.SET window, click the buttons in the **Enable** column to enable output of corresponding signal pins and click the buttons in "Reg." column to toggle their output logic state 0 or 1. Use a multimeter to measure if the logic state really toggles on those signal pins. At least three signal pins need to be verified. Then RELOAD/EXTEST check pass other pins, as shown in Figure 15.



The following uses **GPIO_AD_B0_14** as an example. It connects U1.H14 (RT1064 chip, as shown in Figure 16) and U12.1 (CAN BUS chip, as shown in Figure 17) with the net name of CAN2_TX. When **Reg.** is set to **0**, the corresponding level of above two pins are 0 V. When **Reg.** is set to **1**, the corresponding level of above two pins are 3.3 V.



5 Introduction to other EVK board of i.MX RT series

For the boundary scan test, follow steps as below:

- · RT1010-EVK board
 - 1. Change to JTAG mode by burning eFuse.
 - 2. Check the BSDL file to confirm the status of three pins in COMPLIANCE_PATTERN, as shown below:

```
(TEST_MODE, GPIO_AD_11, POR_B) (011)
```

Similar to RT1060-EVK, remove the pull-down resistor, R303, of the <code>JTAG_MOD</code> pin and connect it to the <code>DCDC_3V3</code> power supply.

- 3. Ensure independent JTAG topology, avoid level interference of other multiplexed signals, and disconnect the headers, **J61**, **J62**, **J63**, and **J64**.
- 4. Use the Lauterbach debugger to test. For details, see the introduction above.
- RT1020 includes two package types, LQFP144 and LQFP100, corresponding to two boards, RT1020-EVK and RT1020-EVK100.
 - RT1020-EVK board (LQFP144)

- 1. Change to JTAG mode by burning eFuse.
- 2. Check the BSDL file to confirm the status of three pins in COMPLIANCE_PATTERN, shown as below:

```
(TEST_MODE, GPIO_AD_B0_02, POR_B) (011)
```

Similar to RT1060-EVK, remove the pull-down resistor, **R57**, of the <code>JTAG_MOD</code> pin, and connect it to the <code>DCDC_3V3</code> power supply.

- 3. As the PMIC_ON_REQ signal will affect the boundary scan test, delete the **R41** resistor and mount **R39** with 100 K resistor.
- Ensure independent JTAG topology, avoid level interference of other multiplexed signals, delete the R116 resistor, and disconnect the headers, J47, J48, J49, and J50.
- 5. Use the Lauterbach debugger to test. For details, see the introduction above.
- RT1020-EVK100 board (LQFP100)
 - 1. Change to JTAG mode by burning eFuse.
 - 2. Check the BSDL file to confirm the status of three pins in COMPLIANCE PATTERN, shown as below:

```
(TEST_MODE, GPIO_AD_B0_02, POR_B) (011)
```

Similar to RT1060-EVK, remove the pull-down resistor, R41, of the JTAG_MOD pin, and connect it to the DCDC_3V3 power supply.

- As the PMIC_ON_REQ signal will affect the boundary scan test, delete the R21 resistor and mount R16 with 100 K resistor.
- Ensure independent JTAG topology, avoid level interference of other multiplexed signals, disconnect the headers, J35, J36, J37, and J38.
- 5. Use the Lauterbach debugger to test. For details, see the introduction above.

· RT1170-EVK board

- 1. No need to change to JTAG mode by burning eFuse.
- 2. Check the BSDL file to confirm the status of three pins in COMPLIANCE_PATTERN, shown as below:

```
(TEST_MODE, GPIO_LPSR_13, POR_B, ONOFF) (0011)
```

Different from the RT1060-EVK, keep the pull-down resistor, R403, of the $\mathtt{JTAG_MOD}$ pin.

- As the PMIC_ON_REQ signal will affect the boundary scan test, delete the R266 resistor and mount R421 with 100 K resistor.
- 4. Ensure independent JTAG topology, avoid level interference of other multiplexed signals, delete the resistors R187, R208, R195, R78, and disconnect the headers J6, J7, J8, and J9.
- 5. Use the Lauterbach debugger to test. For details, see the introduction above.

6 Revision history

Table 2. Revision history

Rev.	Date	Description
0	June, 2020	Initial release
1	March, 2021	Added Introduction to other EVK board of i.MX RT series

Application Note 14 / 15

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