# TEA2226AT

## Digital configurable LLC controller

Rev. 1.1 — 2 November 2023

Product data sheet



## 1 General description

The TEA2226AT is a digital configurable controller for high-efficiency resonant power supplies. The power supply is easy to design and has a very low component count. It meets the efficiency regulations of Energy Star, the Department of Energy (DoE), the Eco-design directive of the European Union, the European Code of Conduct, and other guidelines. So, no auxiliary low-power supply is required.

To increase the efficiency of a low-voltage supply output, the TEA2095T dual SR controller can be added on the secondary side.

In contrast to traditional resonant topologies, the TEA2226AT achieves a high efficiency at low loads due to the low-power mode. This mode operates in the power region between continuous switching (also called high-power mode) and burst mode.

Because the TEA2226AT is regulated via the primary capacitor voltage, it has accurate information about the power delivered to the output. The measured output power defines the mode of operation (burst mode, low-power mode, or high-power mode).

The TEA2226AT contains a low-voltage die with a fully digital controller for output power control, start-up, initializations, and protections. These protections include overcurrent protection (OCP), overvoltage protection (OVP), and capacitive mode regulation (CMR). The TEA2226AT also contains a high-voltage silicon-on-insulator (SOI) controller for high-voltage start-up, integrated drivers, level shifter, protections, and circuitry that ensures zero-voltage switching.

The TEA2226AT LLC controller enables the building of an easy to design, highly efficient, and reliable power supply. The power supply can provide 90 W to 1000 W output power with a minimum of external components. It has a very low no-load input power (< 75 mW) and a high efficiency from minimum to maximum load. So, no additional low-power supply is required, which ensures a significant system cost saving and a highly simplified power supply design, while meeting the latest power supply guidelines and regulations.



Digital configurable LLC controller

## 2 Features and benefits

#### 2.1 Distinctive features

- · LLC controller in a single small-size SO16 package
- · Integrated high-voltage start-up
- Integrated drivers and high-voltage level shifter (LS)
- · High-side driver directly supplied from the low-side driver output
- Integrated X-capacitor discharge without additional external components
- · Power good function
- Several parameters can easily be configured during evaluation with use of the graphical user interface (GUI), like:
  - Operating frequencies to be outside the audible area at all operating modes
  - Soft start and soft stop in burst mode, reducing the audible noise
  - Accurate transition levels between operation modes (high-power mode/low-power mode/burst mode)
  - Enabling/disabling the lower power mode

#### 2.2 Green features

- · Zero voltage switching for minimum switching losses
- · Extremely high efficiency from low load to high load
- · Compliant with latest energy-saving standards and directives (Energy Star, EuP)
- Excellent no-load input power (< 75 mW for TEA2226AT/TEA2095T combination)

## 2.3 Protection features

- · Independently configurable levels and timers
- Many protections can independently be set to latched, safe restart, or latched after several attempts to restart
- Supply undervoltage protection (UVP)
- Overpower protection (OPP)
- Internal and external overtemperature protection (OTP)
- Capacitive mode regulation (CMR)
- · Accurate overvoltage protection (OVP)
- Overcurrent protection (OCP)
- Brownin/brownout protection
- · Disable input
- · Input to reset all protections

Digital configurable LLC controller

# 3 Applications

- Printers
- Desktop and all-in-one PCs
- Gaming power supplies
- · LCD television
- Notebook adapters and general-purpose adapters
- Server
- 5G supplies
- UHD LED television

## 4 Ordering information

## Table 1. Ordering information

Type number	Package			
	Name	Description	Version	
TEA2226AT/1	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1	

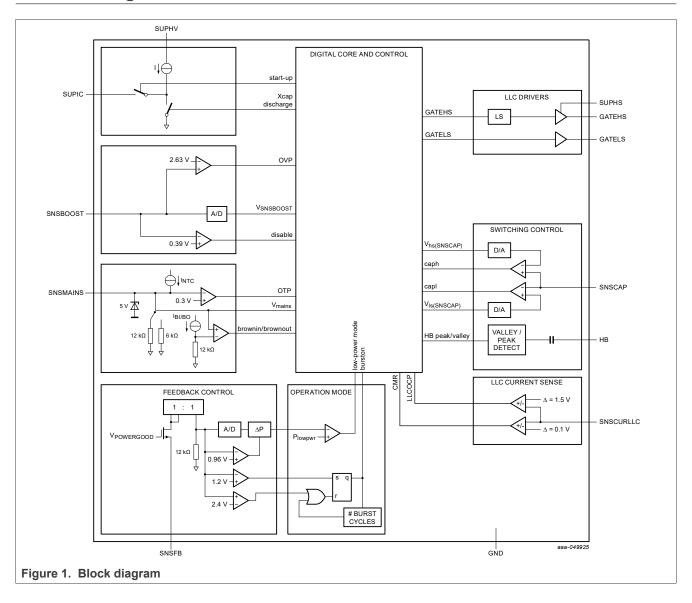
## 5 Marking

## Table 2. Marking codes

Type number	Marking code
TEA2226AT/1	TEA2226AT

Digital configurable LLC controller

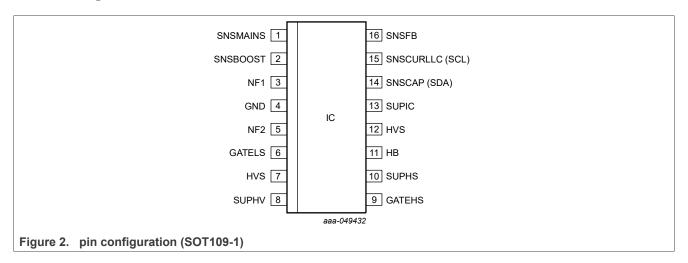
# 6 Block diagram



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# 7 Pinning information

## 7.1 Pinning



## 7.2 Pin description

Table 3. Pin description

Symbol	Pin	Description
SNSMAINS	1	sense input for mains voltage
SNSBOOST	2	sense input for boost voltage; externally connected to resistive-divided boost voltage
NF1	3	not functional; must be connected to pin 4 (GND)
GND	4	ground
NF2	5	not functional; not to be connected.
GATELS	6	LLC low-side MOSFET gate driver output and supply for bootstrap capacitor
HVS	7	high-voltage spacer. Not to be connected.
SUPHV	8	internal HV start-up source also used for X- capacitor discharge; connect to anode of bridge rectifier
GATEHS	9	LLC high-side MOSFET gate driver output
SUPHS	10	high-side driver supply input; externally connected to bootstrap capacitor (C <sub>SUPHS</sub> )
НВ	11	low-level reference for high-side driver and input for half-bridge slope detection; externally connected to half-bridge node HB between the LLC MOSFETs
HVS	12	high-voltage spacer. Not to be connected.
SUPIC	13	input supply voltage and output of internal HV start-up source; externally connected to an auxiliary winding of the LLC via a diode or to an external DC supply
SNSCAP	14	LLC capacitor voltage sense input; externally connected to divider across LLC capacitor
SNSCURLLC	15	LLC current sense input; externally connected to the resonant current sense resistor
SNSFB	16	output voltage regulation feedback sense input; externally connected to an optocoupler. Output for power good function.

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## 8 Functional description

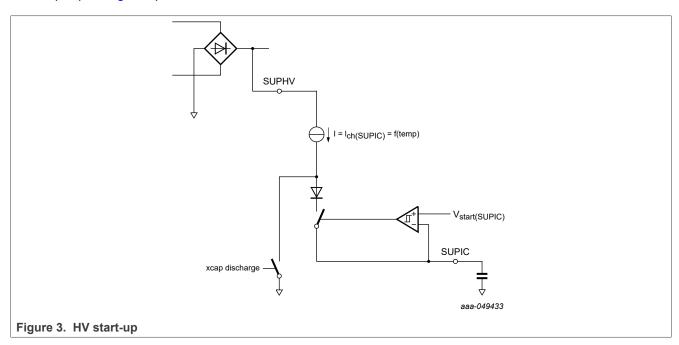
## 8.1 Supply voltages

The TEA2226AT includes:

- A high-voltage supply pin for start-up and X-capacitor discharge (SUPHV pin)
- · A general supply to be connected to an external auxiliary winding (SUPIC pin)
- A floating supply for the high-side driver (SUPHS pin)

## 8.1.1 Start-up and supply voltage

Initially, the capacitor on the SUPIC pin is charged via the SUPHV pin. The SUPHV pin is connected to the anode of the bridge rectifier. Internally, a high-voltage current source is located between the SUPHV pin and the SUPIC pin (see Figure 3).



The maximum current of the internal current source is limited to  $I_{ch(SUPIC)}$ . To limit the IC dissipation, the charge current is reduced when the current source exceeds its maximum temperature.

At start-up, when the SUPIC reaches the  $V_{\text{start}(SUPIC)}$  level, it is continuously regulated to this start level with a hysteresis ( $V_{\text{start}(hys)SUPIC}$ ).

When the start level is reached, it reads the internal MTP (multi-time programmable memory) and defines the settings.

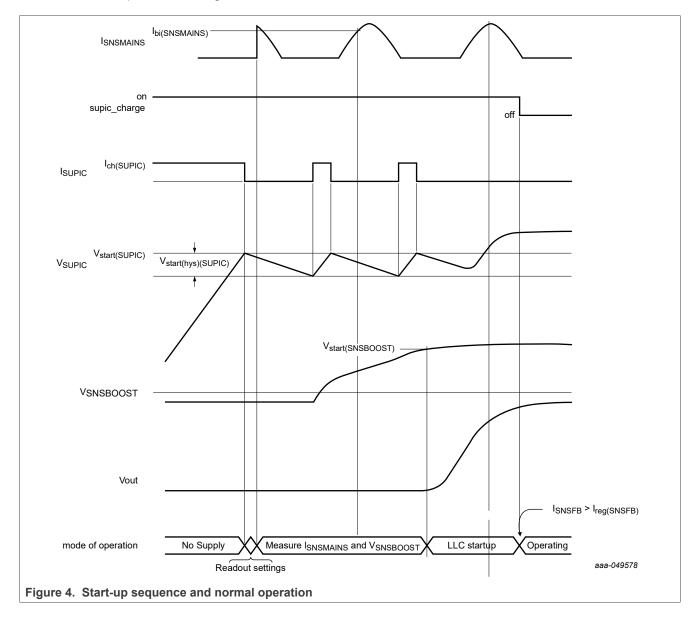
When the SNSBOOST reaches the minimum level  $V_{\text{start}(\text{SNSBOOST})}$ , the LLC starts switching (see <u>Figure 4</u> and <u>Figure 5</u>).

When start-up is complete and the LLC controller is operating, the LLC transformer auxiliary winding supplies the SUPIC pin. In this operational state, the HV start-up source is disabled.

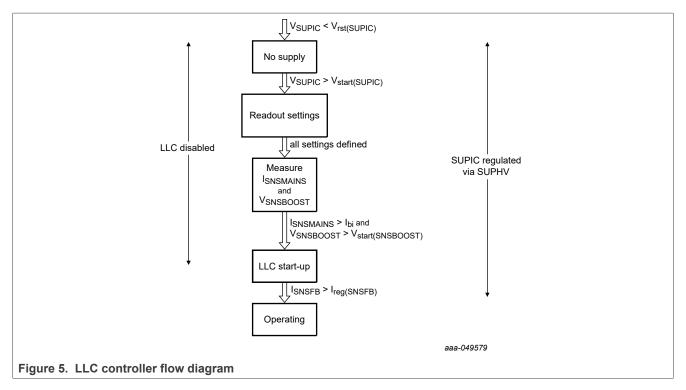
When the system enters the protection mode, it cannot be supplied via the auxiliary winding. So, the SUPIC pin is regulated to  $V_{\text{start}(\text{SUPIC})}$  via the SUPHV pin.

Digital configurable LLC controller

During the non-switching period of the burst mode, the SUPIC is regulated to the  $V_{low(SUPIC)}$  when SUPIC drops to below this level. It regulates the voltage with a hysteresis of  $V_{low(hys)SUPIC}$ . In this way, the system avoids that the SUPIC undervoltage protection ( $V_{uvp(SUPIC)}$ ) is triggered because of a long non-switching period in burst mode. However, the system must be designed such that the internal current source at the SUPHV pin is only active at start-up and extreme output voltage overshoots, followed by a long time of non-switching. Continuous use of this current source increases the input power and affects the lifetime of the product. The SUPHV pin is also used for X-capacitor discharge.



## Digital configurable LLC controller



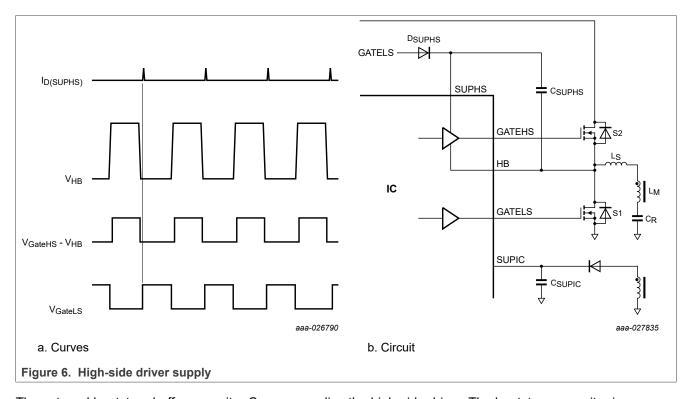
When the SUPIC voltage drops to below V<sub>rst(SUPIC)</sub>, the TEA2226AT restarts.

## 8.1.2 High-side driver floating supply (SUPHS pin)

As the voltage range on the SUPIC pin exceeds that of the maximum external MOSFETs gate-source voltage, the external bootstrap capacitor  $C_{\text{SUPHS}}$  cannot directly be supplied from the SUPIC.

To provide an external supply for the high-side driver without the need of additional external components, the GateLS output is designed such that it can drive the low-side MOSFET and supply the high-side MOSFET (see Figure 6).

Digital configurable LLC controller



The external bootstrap buffer capacitor  $C_{SUPHS}$  supplies the high-side driver. The bootstrap capacitor is connected to the low-side driver supply, the GATELS pin, and the half-bridge node (HB) via an external diode (D<sub>SUPHS</sub>). When GATELS is active high and the HB node is pulled low,  $C_{SUPHS}$  is charged.

Careful selection of the appropriate diode minimizes the voltage drop between the GATELS and SUPHS pins, especially when large MOSFETs and high switching frequencies are used. A great voltage drop across the diode reduces the gate drive of the high-side MOSFET.

## 8.2 LLC system regulation

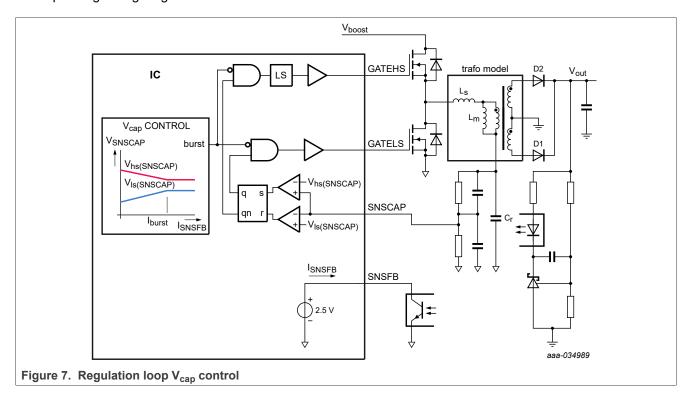
The TEA2226AT regulates the output power by adjusting the voltage across the primary capacitor. Compared to a standard frequency control loop, it has the advantage that the control loop has a constant gain and the IC has information about the output power. So, the operation mode transition levels are derived from the output power.

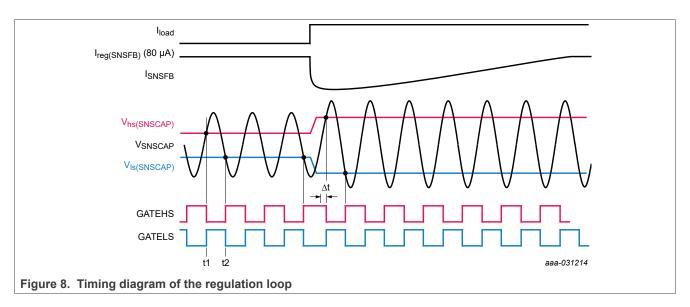
Although the TEA2226AT uses the primary capacitor voltage as a regulation parameter, all application values, like the resonant inductances, resonant capacitor, and primary MOSFETs remain unchanged compared to a frequency-controlled LLC converter. A secondary TL431 circuitry with an optocoupler connected to the primary SNSFB pin continuously regulates the output voltage.

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## 8.2.1 Output power regulation loop

<u>Figure 7</u> shows the output power regulation loop of  $V_{cap}$  control as used by the TEA2226AT. <u>Figure 8</u> shows a corresponding timing diagram.





When the divided resonant capacitor voltage ( $V_{SNSCAP}$ ) exceeds the capacitor voltage high level ( $V_{hs(SNSCAP)}$ ), the high-side MOSFET is switched off (see <u>Figure 8</u> (t1)). After a short delay, the low-side MOSFET is switched on. Because of the resonant current, the resonant capacitor voltage initially increases further but eventually drops.

Digital configurable LLC controller

When the divided capacitor voltage ( $V_{SNSCAP}$ ) drops to below the capacitor voltage low level ( $V_{Is(SNSCAP)}$ ), the low-side MOSFET is switched off (see <u>Figure 8</u> (t2)). After a short delay, the high-side MOSFET is switched on. <u>Figure 8</u> shows that the switching frequency is a result of this switching behavior. In a frequency-controlled system, the frequency is a control parameter and the output power is a result. The TEA2226AT regulates the power and the frequency is a result.

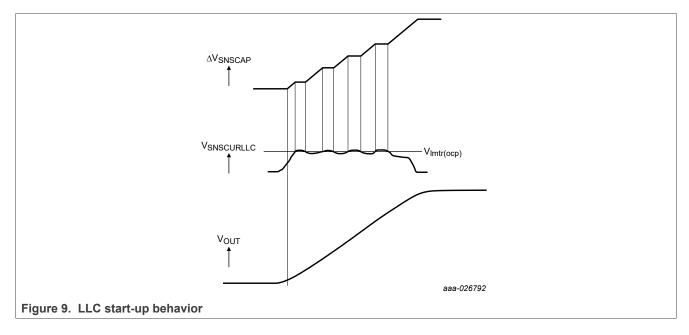
The difference between the high and low capacitor voltage level is a measure of the delivered output power. The value of the primary optocurrent, defined by the secondary TL431 circuitry, determines the difference between the high and low capacitor voltages.

<u>Figure 8</u> also shows the behavior at a transient. If the output load increases, the current pulled out of the SNSFB pin decreases. The result is that the TEA2226AT increases the high-level capacitor voltage and lowers the low-level capacitor voltage. The output power increases and eventually the output voltage increases to its regulation level.

To minimize no-load input power of the system, the primary current into the optocoupler is continuously regulated to  $I_{reg(SNSFB)}$  (see Section 8.4).

## 8.2.2 Output voltage start-up

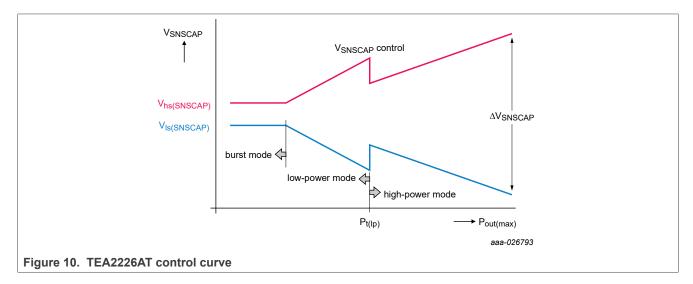
At start-up, when the system slowly increases the  $\Delta V_{SNSCAP}$ , it continuously monitors the primary current via the SNSCURLLC pin. When the voltage at this pin exceeds the  $V_{Imtr(ocp)}$  level, increasing the  $\Delta V_{SNSCAP}$  is on hold until the voltage at the SNSCURLLC pin drops to below the  $V_{Imtr(ocp)}$  level again (see Figure 9). The output current is regulated and its voltage shows a nice ramp during start-up. It also avoids that during startup the OCP (overcurrent protection) is triggered. In this way, the LLC converter behaves like a limited current source during start-up.



Digital configurable LLC controller

## 8.3 Modes of operation

<u>Figure 10</u> shows the control curve between the output power and the voltage difference between the high and low capacitor voltage levels.



When the output power ( $P_{out}$ ) is at its maximum, the low capacitor voltage level ( $V_{Is(SNSCAP)}$ ) is at its minimum, and the high capacitor voltage ( $V_{hs(SNSCAP)}$ ) is at its maximum level. The maximum  $\Delta V_{SNSCAP}$  ( $V_{hs(SNSCAP)} - V_{Is(SNSCAP)}$ ), which is the divided  $\Delta V_{Cr}$  voltage, corresponds to the maximum output power.

When the output load decreases, the  $\Delta V_{SNSCAP}$  voltage decreases. As a result, the output power decreases and the output voltage is regulated. This mode is called high-power mode. Figure 8 shows a timing diagram of the system operating in high-power mode.

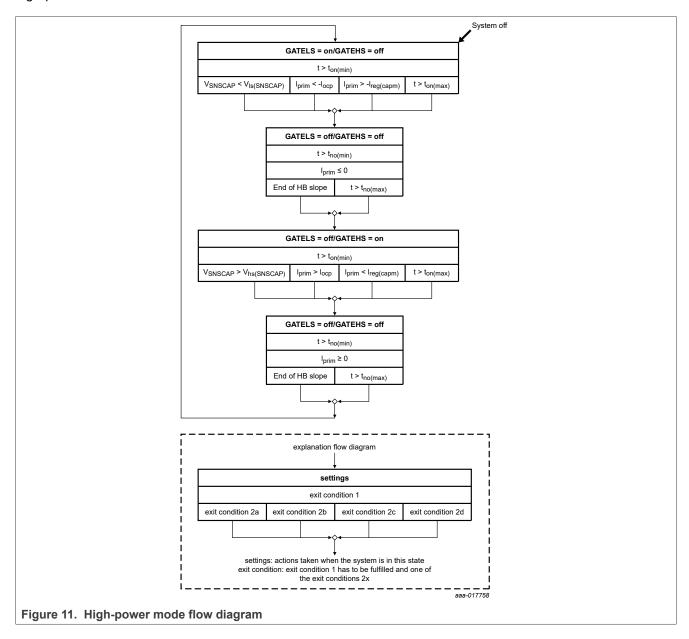
When the output power drops to below the transition level  $(P_{t(lp)})$ , the system enters the low-power mode. The  $P_{t(lp)}$  level can be initialized via the MTP.

To compensate for the non-switching period in low-power mode, also called hold period,  $\Delta V_{SNSCAP}$  is initially increased at entering the low-power mode (see <u>Section 8.3.2</u>). In low-power mode, the output power is regulated by adapting  $\Delta V_{SNSCAP}$ , until it reaches a minimum. The system then enters the burst mode (see <u>Section 8.3.3</u>).

Digital configurable LLC controller

## 8.3.1 High-power mode

In high-power mode, the system operates as described in <u>Section 8.2.1</u>. <u>Figure 11</u> shows a flow diagram of the high-power mode.



Digital configurable LLC controller

Initially, GATELS is on and GATEHS is off. The external bootstrap buffer capacitor ( $C_{SUPHS}$ ) is charged via the GATELS pin and an external diode. The system remains in this state for at least the minimum on-time ( $t_{on(min)}$ ) of GATELS. Before entering the next state, one of the following conditions must be fulfilled:

- The V<sub>SNSCAP</sub> voltage drops to below the minimum V<sub>SNSCAP</sub> voltage (V<sub>Is(SNSCAP)</sub>)
- The measured current exceeds the OCP level (see Section 8.6.12)
- The system is close to capacitive mode (see Section 8.6.11)
- The maximum on-time (t<sub>on(max)</sub>), a protection that maximizes the time the high-side or low-side MOSFET is kept on, is exceeded.

To avoid false detection of the HB peak voltage, the system remains in this state until the minimum non-overlap time  $(t_{no(min)})$  is exceeded. When this time is exceeded and it detects the peak of the HB node and the measured resonant current is negative (or zero), it enters the next state.

If the system does not detect a peak at the HB node, it also enters the next state when the maximum non-overlap time  $(t_{no(max)})$  is exceeded under the condition of a negative (or zero) resonant current.

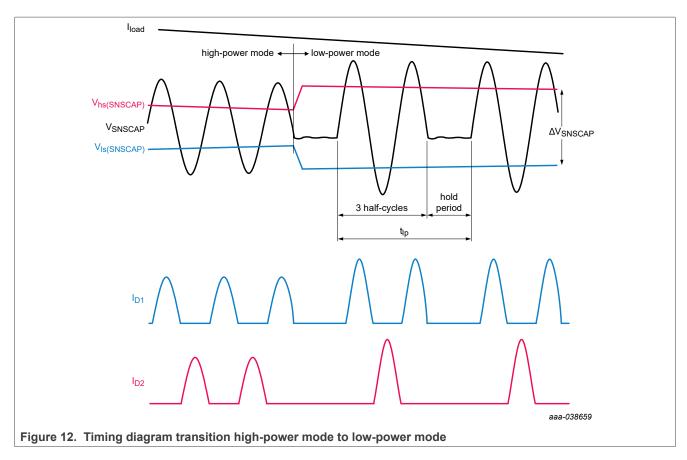
Finally, the third and fourth states (see <u>Figure 11</u>) describe the GATEHS and GATEHS to GATELS transition criteria which are the inverse of the first two states.

## 8.3.2 Low-power mode

At low loads, the efficiency of a resonant converter drops as the magnetization and the switching losses become dominant. A low-power mode ensures high efficiency at lower loads because it reduces the magnetization and switching losses.

When the output power drops to below the  $P_{t(lp)}$  level, the system enters the low-power mode (see <u>Figure 10</u> and <u>Figure 12</u>). It continues switching for 3 half-cycles (low-side, high-side, low-side) with an MTP selectable duty cycle. To ensure a constant output power level, it increases the energy per cycle ( $V_{hs(SNSCAP)} - V_{ls(SNSCAP)}$ ) at the same time.

Digital configurable LLC controller

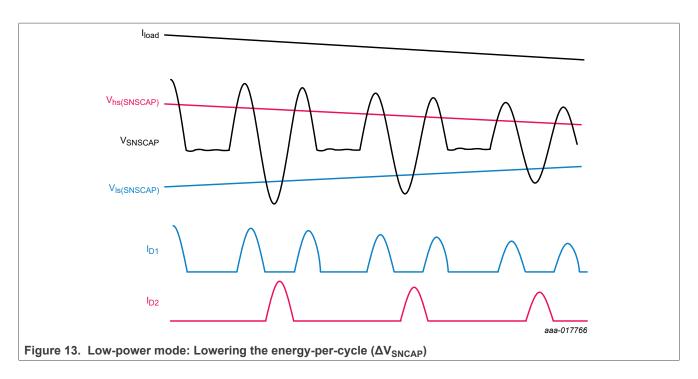


As the system continuously tracks the primary capacitor voltage, it knows exactly when to enter the "hold" period. It can also continue again at exactly the correct voltage and current levels of the resonant converter. In this way, a "hold" period can be introduced which reduces the magnetization and switching losses without any additional losses. The currents  $I_{D1}$  and  $I_{D2}$  (see Figure 12) are the secondary currents through diodes D1 and D2 (see Figure 7).

When in low-power mode the output power is further reduced, the amount of energy per cycle (=  $\Delta V_{SNSCAP}$ ) is reduced and the duty cycle remains the same (see <u>Figure 13</u>).

When in low-power mode the system reaches the programmable minimum energy per cycle (=  $\Delta V_{SNSCAP}$ ), it enters burst mode.

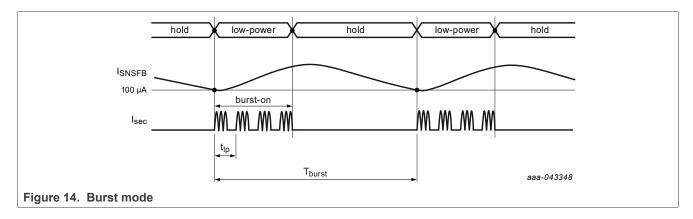
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#### 8.3.3 Burst mode

In burst mode, the system alternates between operating in low-power mode and an extended hold state (see <u>Figure 14</u>). Because of this additional extended hold period, the magnetization and switching losses are further reduced. So, the efficiency of the system is increased.

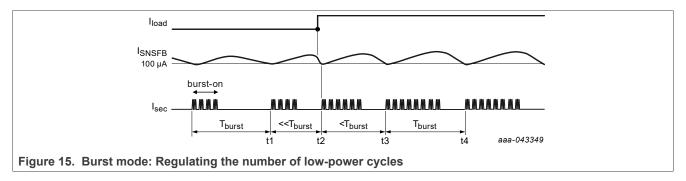
<u>Figure 14</u> shows that all operating frequencies are outside the audible area. The minimum low-power frequency can be set with a parameter. Within a low-power period, the system is switching at the resonant frequency of the converter, which is typically between 50 kHz and 200 kHz. The burst frequency (1/T<sub>burst</sub>) can be programmed out side the audible noise area.



Digital configurable LLC controller

## 8.3.3.1 Frequency regulation

When the primary optocurrent ( $I_{SNSFB}$ ) drops to below  $I_{start(burst)}$  (100  $\mu$ A typical), a new burst-on period is started. The end of the burst-on period depends on the calculated number of low-power cycles. The number of low-power cycles within a burst-on period is continuously adjusted so that the total burst period ( $T_{burst}$ ) is at least the period defined by the setting (see <u>Figure 15</u>).



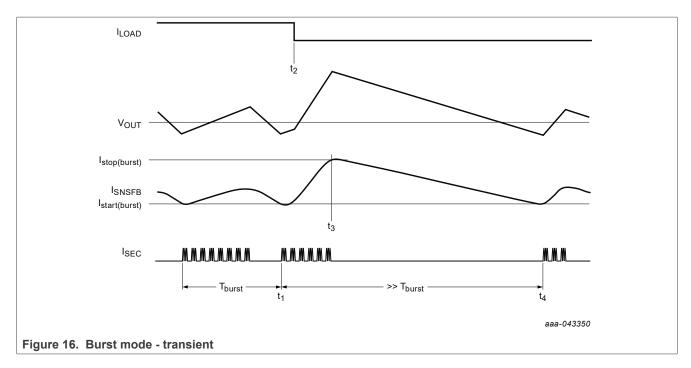
The system continuously measures the burst period from the start of the previous burst-on period to a new burst-on period. At t1, the measured burst period ( $T_{burst}$ ) equals the required  $T_{burst}$ . So, the next number of low-power cycles equals the number of previous low-power cycles. At a constant output power, the system expects that when the next burst-on period has the same number of low-power cycles as the previous burst-on period, the burst period ( $T_{burst}$ ) remains constant.

At a positive transient (t2), a new low-power cycle is started immediately to minimize the drop in output voltage. The measured time period, at time t2, is below the targeted burst period. The system increases the number of burst cycles. At t3, it measures the burst period again. In this example, the burst period is still below the targeted burst period. So, the system increases the number of low-power cycles again and again until the measured burst period equals the target burst period, which occurs at t4.

### 8.3.3.2 Negative transient response

When the system operates in burst mode, it defines the new number of cycles at the start of a new burst cycle. If the output load is reduced just after the start of a new burst cycle, the output voltage shows an overshoot (see <u>Figure 16</u>).

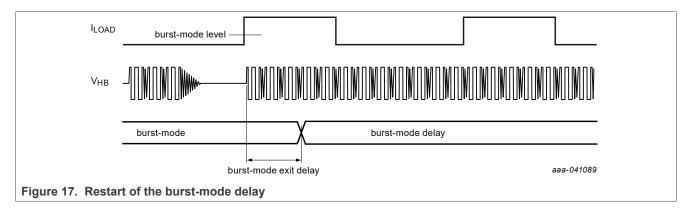
Digital configurable LLC controller



At t1, the system starts with a new burst cycle period. Shortly later at t2, the output load is reduced. As a result the output voltage shows an overshoot and the optocoupler current increases. To limit the overshoot, the system also ends the burst cycle when the optocoupler current exceeds the I<sub>stop(burst)</sub> level.

### 8.3.3.3 Burst-mode exit delay function

When the system is in burst mode and a positive transient occurs, it may be preferred to leave the burst mode and restart the burst-mode delay function (see Figure 17).



When the LLC is switching for a time that exceeds the burst-mode exit delay time and the output load exceeds the burst-mode level, the system leaves the burst mode. The burst-mode delay function is activated again. The burst-mode exit delay time can be set with a parameter.

In this way, the transient response is improved at a variable load while the system was initially in burst mode.

## 8.4 Optobias regulation

In a typical application, the output voltage is sensed using a TL431 and connected to the SNSFB pin of the TEA2226AT via an optocoupler (see <u>Figure 23</u>). Because of the behavior of the TL431, the current through the

TEA2226A

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Digital configurable LLC controller

optocoupler is at the maximum level when the output power is at the minimum level. It is therefore one of the most critical parameters to achieve the required no-load input power. To achieve maximum efficiency at low load/no load, the TEA2226AT continuously regulates the optocurrent to a low level that is independent of the output load.

Because of the parasitic capacitance at the optocoupler collector, a very low optocurrent reduces the transient response of the system. So, the TEA2226AT applies a fixed voltage at the SNSFB pin. It measures the current through the optocoupler which defines the required output power. Via an additional internal circuitry, which adds an offset to the required output power, the optocurrent is continuously (slowly) regulated to the I<sub>reg(SNSFB)</sub> level (= 80 µA typical). This level is independent of the output power.

At a positive load transient, the optocurrent initially decreases (see <u>Figure 8</u>;  $I_{SNSFB}$ ). The TEA2226AT immediately increases the  $\Delta V_{SNSCAP}$  which again increases the output power.

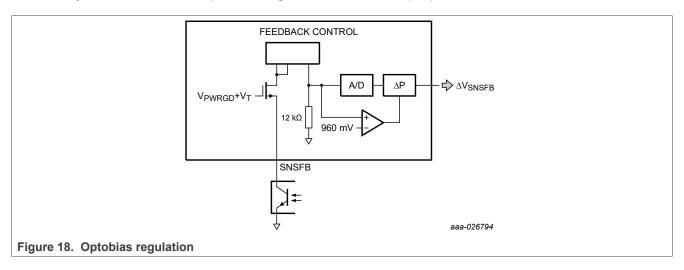


Figure 18 shows that when the optocurrent decreases, the internal voltage across the 12 kΩ resistor drops to below the targeted level of 960 mV (= 80 μA (typical) × 12 kΩ). The TEA2226AT then slowly increases an additional offset at the power level ( $\Delta$ P). It continues to increase the additional offset until the optocurrent reaches the target of 80 μA (typical). When the optocurrent increases due to a transient, the additional offset to the power level is decreased. As a result, the output voltage decreases which again decreases the optocurrent. In this way, the optocurrent is continuously regulated to the I<sub>red(SNSFB)</sub> level.

The behavior of the internal circuitry connected to the SNSFB pin is the same as the behavior of the traditional circuitry. The fixed voltage at the SNSFB pin and the continuous regulation of the optocurrent level does not influence the regulation level. The advantage, however, is a reduction in no-load input power and an optimization of the transient response.

When the system operates in low-power mode at the minimum energy per cycle and at minimum duty cycle, it can no longer reduce the optocurrent level to the  $I_{reg(SNSFB)}$  target (» 80  $\mu$ A typical). If the output power decreases further and the optocurrent increases to above the level of Istart(burst) (» 100  $\mu$ A typical), the burst mode is triggered. When the output power drops to below this level again, a new burst cycle is started (see Figure 14 and Figure 15).

## 8.5 Active X-capacitor discharge

The TEA2226AT provides an active X-capacitor discharge after the mains voltage is disconnected. When the mains input voltage (and so also the measured current into the SNSMAINS pin) increases, the system assumes the presence of a mains voltage. When the mains voltage does not increase for a minimum period of  $t_{d(dch)}$ , the X-capacitor is discharged via the SUPHV pin. When the mains is reconnected, the discharge current is disabled again.

Digital configurable LLC controller

## 8.6 Protections

Table 4 gives an overview of the available protections.

Table 4. Protections overview

Protection	Description	Action	LLC	Protection register
General protectio	ns		1	
UVP SUPIC	undervoltage protection SUPIC pins	recharge via SUPHV; restart when V <sub>SUPIC</sub> > V <sub>start(SUPIC)</sub>	off	-
MTPfail	reading of the internal MTP failed	continue reading until the data is valid; only checked once at start-up	off	Y
OTPint	internal overtemperature protection	latched or safe restart [1]	off	Y
OTPext	external overtemperature protection	latched or safe restart [1]	off	Y
SCP SNSBOOST/ fast disable	short-circuit protection/ disable LLC	restart when V <sub>SNSBOOST</sub> > V <sub>scp(start)</sub>	off	Y
brownout mains	undervoltage protection mains	restart when the mains voltage exceeds the brownin level	on/off <sup>[1]</sup>	-
LLC protections				
UVP SUPHS	undervoltage protection SUPHS pin	GATEHS = off	off	-
UVP SNSBOOST	undervoltage protection boost	restart when V <sub>SNSBOOST</sub> > V <sub>start(SNSBOOST)</sub>	off	-
OVP SUPIC	output overvoltage protection; measured via the SUPIC pin	latched or safe restart [1]	off	Y
OVP SNSBOOST	overvoltage protection boost voltage	restart when V <sub>SNSBOOST</sub> < V <sub>stop(ovp)</sub>	on/off <sup>[1]</sup>	Y
maximum on-time	maximum on- time of the LLC MOSFET	LLC MOSFET switched off; continue operation	-	Y
CMR	capacitive mode regulation	system ensures that mode of operation is inductive	-	Υ
OCP	overcurrent protection	switch off cycle-by-cycle; After several consecutive cycles, latched or safe restart <sup>[1]</sup>	off	Υ
STARTUP MAX	maximum start-up time	latched or safe restart [1]	off	Y

Digital configurable LLC controller

Table 4. Protections overview...continued

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Protection	Description	Action		Protection register
	overpower protection	latched or safe restart <sup>[1]</sup>	off	Υ

<sup>[1]</sup> Selectable via a parameter at the MTP.

When the system is in a latched or safe restart protection, the SUPIC voltage is regulated to its start level via the SUPHV pin.

## 8.6.1 Undervoltage protection SUPIC

When the voltage on the SUPIC pin is below its undervoltage level V<sub>uvp(SUPIC)</sub>, the LLC converter stops switching. The capacitors at the SUPIC pin are recharged via the SUPHV pin.

When the SUPIC supply voltage exceeds its start level, the system restarts.

#### 8.6.2 MTP fail

At start-up, when the SUPIC reaches 12 V, the system reads the parameters from the internal MTP. If reading the MTP failed, a protection is triggered. A mains reset is required before the system starts. During this time, the LLC remains off.

### 8.6.3 Internal overtemperature protection (OTP)

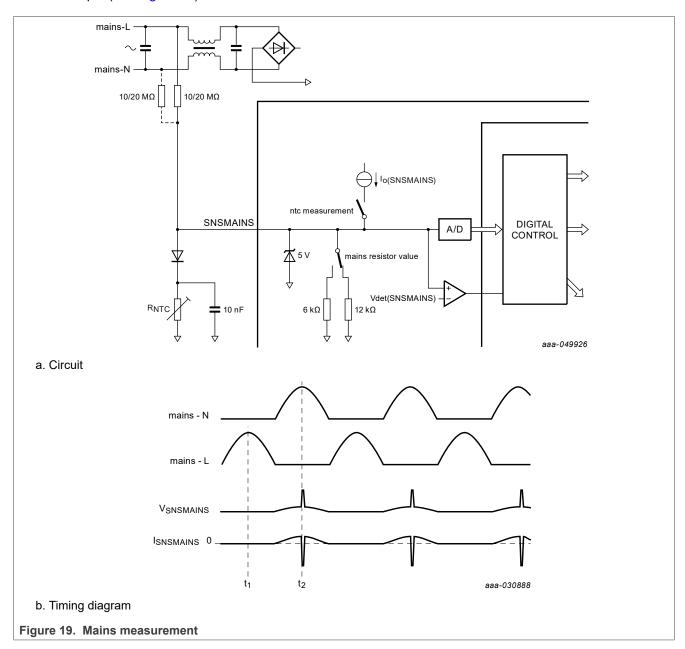
An accurate internal temperature protection is provided in the circuit. When the junction temperature exceeds the thermal shutdown temperature, the LLC stops switching.

The response of the internal OTP can be either latched or safe restart.

Digital configurable LLC controller

## 8.6.4 Brownin/brownout and external overtemperature protection

On the TEA2226AT, the mains measurement and external temperature measurement are combined at the SNSMAINS pin (see Figure 19).



The TEA2226AT continuously measures the SNSMAINS voltage via an A/D converter and waits until it detects a peak (t1). The output of the A/D converter is used for brownout/brownin detection.

During an NTC measurement, which is enabled during the peak of the mains, an internal current source of  $I_{o(SNSMAINS)}$  is switched on. With the external NTC and diode, the internal current source generates a voltage at the SNSMAINS pin. If this voltage remains below the  $V_{det(SNSMAINS)}$  level, the external OTP protection is triggered after  $t_{d(otp)}$ . The internal current source is turned on until the SNSMAINS voltage exceeds the  $V_{det(SNSMAINS)}$  level level or a maximum time of  $t_{det(max)NTC}$ .

Digital configurable LLC controller

The external resistor, which is connected between mains-L/mains-N and the SNSMAINS pin, can be either  $20~\text{M}\Omega$  or  $10~\text{M}\Omega$ . The number of mains resistors can either be one (only connected to the mains-L or mains-N) or two (one connected to the mains-L and the other to the mains-N). However, the selected parameter of the resistor value and number of resistors must correspond to the application.

### 8.6.5 Short-circuit protection/fast disable

The LLC does not start switching until the voltage on the SNSBOOST pin exceeds  $V_{\text{scp(start)}}$ . This function acts as short circuit protection for the boost voltage.

When the SNSBOOST pin is shorted to ground or the SNSBOOST pull-up resistor is disconnected, this protection inhibits switching.

This function can also be used as a fast disable. If this pin is shorted to ground via an external MOSFET, the system either stops switching or enters the protection mode followed by safe restart or latched protection. In this way, an additional external protection can be added.

When the fast disable function is selected to stop switching only, it can be combined with a reset of all protections. The MTP bit "fast disable FLR" must be enabled then. So, if any protection is triggered, it is reset when the SNSBOOST voltage drops to below the  $V_{\text{scp(stop)}}$  level for at least  $t_{\text{d(flr)}}$ . When the SNSBOOST voltage exceeds the  $V_{\text{start(SNSBOOST)}}$  level, the LLC resumes switching.

#### 8.6.6 Brownout mains

Due to the large bulk capacitor, the LLC can continue for a long period while the mains is already disconnected. So, the option to stop the LLC at a brownout after a given delay can be selected with a parameter.

## 8.6.7 Overvoltage protection (SNSBOOST pin)

When an OVP at the SNSBOOST is detected for a minimum period (can be set using a parameter), the LLC can be disabled.

### 8.6.8 Undervoltage protection SUPHS

To ensure a minimum drive voltage at the high-side driver output (GATEHS), this driver is turned off when its voltage is below the minimum level ( $V_{SUPHS} < V_{rst(SUPHS)}$ ).

#### 8.6.9 Undervoltage protection boost

The boost voltage is measured via a resistive divider connected to the SNSBOOST pin. The voltage at the SNSBOOST pin must exceed the start level ( $V_{SNSBOOST} > V_{start(SNSBOOST)}$ ) before the LLC converter is allowed to start switching.

When the system is operating and the voltage at the SNSBOOST pin drops to below the minimum level  $(V_{SNSBOOST} < V_{uvp(SNSBOOST}))$ , the LLC converter stops switching. When it exceeds the start level, it restarts.

### 8.6.10 Overvoltage protection (SUPIC pin)

When the voltage at the SUPIC pin exceeds the  $V_{O(ovp)SUPIC}$  level for  $t_{d(ovp)SUPIC}$ , the OVP protection is triggered. The voltage at the SUPIC pin is continuously monitored via an internal A/D converter.

The OVP protection level and the OVP delay time can be selected with a parameter.

The OVP function can also be disabled.

Digital configurable LLC controller

## 8.6.11 Capacitive mode regulation (CMR)

The TEA2226AT has a capacitive mode regulation (CMR) which ensures that the system is always operating in inductive mode and avoids operation in capacitive mode.

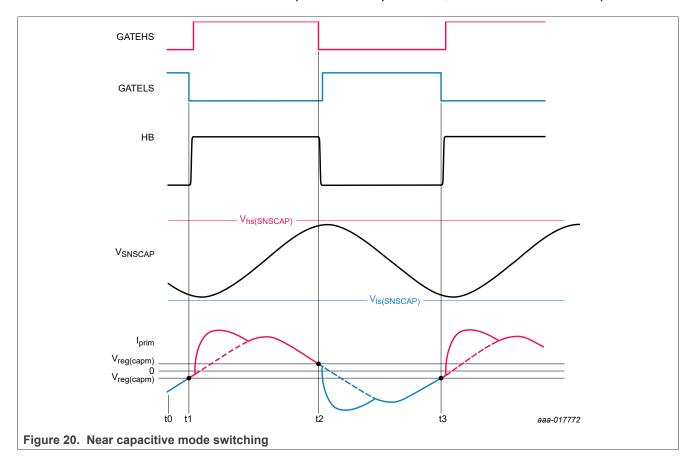
At lower input voltage or higher output power and depending on the resonant design, the resonant current can already approach zero before the capacitor voltage reaches the regulation level.

When the resonant current has changed polarity before the switches are turned off and the other switch is turned on, hard switching occurs. This event is called capacitive mode. To avoid that the LLC operates in capacitive mode, the system also switches off the high-side/low-side switch when the resonant current approaches zero.

Figure 20 shows the signals that occur when a resonant converter is switching in CMR mode. At t1 (and also at t3), the low-side switch is on while the resonant current approaches zero before  $V_{SNSCAP}$  reaches  $V_{Is(SNSCAP)}$ . At t2, the resonant current is also close to changing polarity while the divided capacitor voltage ( $V_{SNSCAP}$ ) has not reached the  $V_{hs(SNSCAP)}$  level yet. To avoid a turn-off of the high-side switch at a negative current or the low side at a positive current, the system also turns off the high-side/low-side switch when the primary current approaches zero. So at t2, the high-side switch is turned off because the primary current is close to zero. At t3 (and also at t1), the low-side switch is turned off, although  $V_{SNSCAP}$  did not reach the regulation level ( $V_{Is(SNSCAP)}$ ) yet. The primary current is measured via an external sense resistor connected to the SNSCURLLC pin. The capacitive mode protection levels are  $V_{reg(capm)}$  (-100 mV typical and +100 mV typical). These levels can be adjusted with a parameter.

In this mode, the amount of output power is reduced and the output voltage decreases.

The TEA2226AT does not enter a so-called "capacitive mode protection", but avoids this mode of operation.



Digital configurable LLC controller

## 8.6.12 Overcurrent protection

The system measures the LLC primary current continuously via a sense resistor connected to the SNSCURLLC pin. If the measured voltage exceeds the fixed overcurrent level ( $V_{ocp(LLC)}$ ), the corresponding switch (GATELS/GATEHS) is turned off, but the system continues to switch. In this way, the primary current is limited to the OCP level.

The OCP level can be adjusted via the external sense resistor.

If the OCP is continuously triggered for an adjustable time, the system enters the OCP protection state. The OCP protection state can also be disabled. However, the primary current is always limited to the OCP level cycle-by-cycle.

## 8.6.13 Maximum start-up time

If the output voltage of the LLC is not in regulation within an adjustable time after the LLC has started switching, the maximum start-up time protection is triggered.

The maximum start-up time ( $t_{startup(max)}$ ) can be set with the parameter "Maximum start-up time". If this protection is triggered, the system is latched, safe restart, or latched after safe restart, which follows the setting of the OPP.

## 8.6.14 Overpower protection

For the overpower protection, three levels can be set:

- Absolute maximum output power, which is the highest output power level.
  - When the output power exceeds this maximum level, it is limited cycle-by-cycle. If the output power exceeds this maximum, the output voltage decreases.
  - The maximum output power can be set to a percentage of the rated output power.
- A first overpower level, which is below the maximum output power level.
  - When the output power exceeds this power level, a timer is started. When this timer exceeds a predefined value, the system enters the protection state. The LLC is switched off.
  - This power level can be set to a predefined level below the selected maximum output power. So, if the maximum output power is set to 170 % and this first overpower level is set to -20 %, the timer is started at 150 % of the rated output power.
  - The timer of the first overpower level can also be set. The first overpower level can also be disabled.
- A second overpower level, which is typically below the first overpower level.
  - When the output power exceeds this power level, a timer is started. When this timer exceeds a predefined value, the system enters the protection state. The LLC is switched off.
  - This power level can be set to a predefined level below the selected maximum output power. So, if the output power is set to 170 % and this second overpower level is set to -50 %, the timer is started at 120 % of the rated output power.
  - The timer of the second overpower level can be set to a predefined level. The second overpower level can also be disabled.

The overpower function can be either latched, safe restart, or latched after safe restart. <u>Section 8.6.15</u> describes this function.

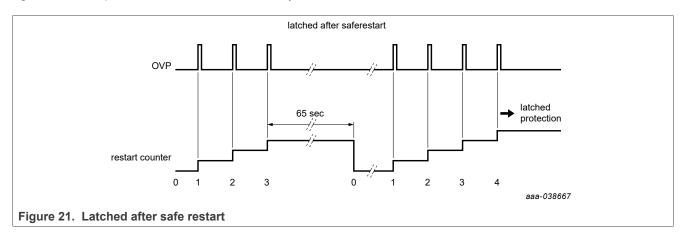
Digital configurable LLC controller

### 8.6.15 Latched, safe restart, or latched after safe restart

When a protection is selected to be latched, the system stops switching when this protection is triggered. The system only restarts after a fast latch reset (see <u>Section 8.6.16</u>) or when the SUPIC supply voltage drops below the UVP level.

When a protection is selected to be safe restart, the system continuously restarts after a predefined safe restart time. This safe restart time is the same for all protection functions. It can be set with a parameter.

When selecting "latched after safe restart", a protection is initially a safe restart protection. If the failure occurs again within a specific time, it latches eventually.



<u>Figure 21</u> shows an example of when the OVP is set to latched after safe restart. Initially at an OVP, the system restarts after the safe restart time. An internal counter is then set to '1'. If the protection is triggered again, the counter is increased. If the counter reaches the number as set with a parameter, the system latches. If no protection is triggered within 65 seconds, the counter is reset.

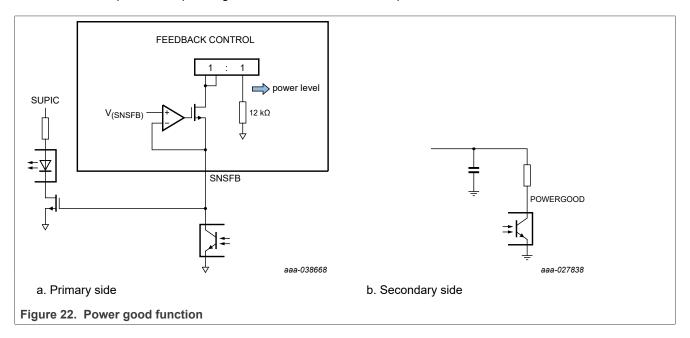
## 8.6.16 Fast latch reset

If a protection is triggered, the system enters the protection state. Especially when the protection is latched, this function is inconvenient during production tests. So, when the mains voltage is below the brownout level for a specified time, the system also restarts. This time can be set with a parameter. This function is called fast latch reset.

Digital configurable LLC controller

## 8.7 Power good function

The TEA2226AT provides a power good function via the SNSFB pin.



The primary function of the SNSFB pin is to regulate the output voltage via an optocoupler. So, it measures the current that is drawn from the SNSFB. Via an internal  $12 \text{ k}\Omega$  resistor, it regulates the output power. The output power regulation is independent of the voltage level of the SNSFB pin. So, the voltage level at the SNSFB pin is used to indicate if the system is about to stop operating, a so-called power good signal. The voltage at the SNSFB pin can be used to generate a secondary power good signal using an external MOSFET and an optocoupler.

At start-up, the SNSFB voltage is at a high level, pulling down the secondary power good signal. As soon as the system enters the operating state (see <u>Figure 4</u>), the SNSFB goes low. The external power good signal becomes active high.

The SNSFB voltage becomes active high, lowering the secondary power good signal when:

- The voltage on the SNSBOOST pin drops to below V<sub>det(SNSBOOST)</sub>
- The OPP counter is close to its end value
- The converter is about to stop due to an OTP protection
- When the LLC converter is about to stop due to an OVP on the SNSBOOST when this function is enabled
- · When the LLC converter is about to stop due to a mains brownout when this function is enabled

To avoid any disturbance of the regulation loop, the increase and decrease of the SNSFB voltage is in alignment with a predefined ramp.

When the system enters protection mode (OVP, OCP, or UVP), it pulls high the SNSFB pin and stops switching immediately.

Digital configurable LLC controller

## 8.8 Settings

The TEA2226AT has an internal MTP at which different settings can be programmed.

The TEA2226AT settings can be found in Section 13.

#### Disclaimer:

The MTP parameter settings can be changed using the "Ringo" GUI software of NXP Semiconductors. Before the user can change any MTP parameters using the GUI, the terms and conditions in the start-up pop-up screen must be accepted.

## 8.8.1 General settings

### 8.8.1.1 Protection register

When the TEA2226AT triggers a protection, it can be read which protection was triggered. Even when the root cause of the protection is solved and the converter continues switching, the information about the protection remains until the software program (Ringo GUI) clears it.

## 8.8.1.2 Supply start level

The SUPIC start level can be selected between 12 V and 19 V. Typically, a level of 19 V is selected. When the TEA2226AT is externally supplied, for instance via a standby supply, the lower start level of 12 V can be used.

After start-up, when the MTP is read and a 12 V start level is selected, charging via the SUPHV is disabled, as the system assumes that it is externally supplied.

#### 8.8.1.3 Read lock

Normally, the software tool can read all the programmed settings. This option can be used to verify the correct settings or for failure analyses.

However, once in production, enabling the "Read lock" bit protects the parameters. Then it is not possible anymore to read the MTP content. It can however still be reset to the default values and also clear the read lock parameter.

#### 8.8.1.4 Write lock

To avoid that the MTP content (accidentally) gets overwritten, a write-lock bit can be set. It can, however, still be reset to the default values and clear the write lock parameter.

#### 8.8.1.5 Reset to the default values

When the MTP is reset, it implies that all parameters are set to a default value. The default values normally do not correspond to the original MTP values. They are chosen such that a general application works properly.

When the MTP is reset, the MTP can be read and written again.

### 8.8.1.6 Customer MTP code

When in production, the content of the MTP can be hidden when the read lock bit is enabled. To get access to the content of the MTP, a unique customer code can be programmed. This customer code provides information about the MTP content.

This customer code can always be read, even when the read lock bit is enabled.

TEA2226A

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Digital configurable LLC controller

## 8.8.1.7 Active X-capacitor discharge

When the TEA2226AT detects that the mains is disconnected, the X-capacitor discharge is activated after a delay of  $t_{d(dch)}$ . The following delays can be selected: 100 ms, 200 ms, and 400 ms. This function can also be disabled.

## 8.8.1.8 Mains measurement impedance

To realize a low no-load input power level, the external resistor connected to the SNSMAINS pin for measuring the mains input voltage is typically 20 M $\Omega$ .

However, some applications request a maximum resistance of 10 M $\Omega$ . With this bit, 10 M $\Omega$  or 20 M $\Omega$  can be selected for the external resistor without affecting the mains voltage-related levels like brownin and brownout.

#### 8.8.1.9 Number of mains resistors

To achieve the lowest possible no-load input power, a single mains sense resistor can be used. If continuously measuring the mains voltage is necessary, two mains resistors can be used.

For proper functionality, the resistor value and number of resistors in the application are required to correspond to the IC settings.

## 8.8.2 LLC settings

#### 8.8.2.1 LLC disable

Especially for validation purposes, an option is available to disable the LLC. When the LLC is disabled, a restart is required.

### 8.8.2.2 Start-up

## Maximum (start-up) frequency

The maximum switching frequency of the LLC is limited to a value, which is defined using a parameter. This value also defines the maximum switching frequency during start-up. The maximum frequency can be set to different values ranging from 150 kHz to 800 kHz.

## LLC soft-start time

The LLC soft-start time defines the rate at which the converter lowers its switching frequency. This rate can be selected between 2 and 20 which leads to a start-up time of approximately between 1 ms and 10 ms. However, it depends on the LLC design. A higher speed lowers the start-up time. However, it can cause a high charge current and an overshoot at the output voltage.

## Maximum primary current during start-up

At start-up, the LLC starts switching at the maximum frequency and ramps down the frequency until the  $\Delta V_{SNSCAP}$  reaches the required level. If during this start-up time the primary current, which reflects the output current, reaches a predefined level, the frequency is temporarily not further reduced until the primary current drops to below the level again. This level is measured via the SNSCURLLC pin. The following values can be selected: 0.5 V, 0.75 V, 1.0 V, or 1.25 V.

Digital configurable LLC controller

## 8.8.2.3 LLC switching

### ΔV<sub>SNSCAP</sub> dump level

When the system is in low-power mode, a switching period is followed by a waiting period. The system ensures that it continues at the same stage as where it stopped. To reach the maximum efficiency, the end of the last switching cycle can be fine-tuned. For the  $\Delta V_{SNSCAP}$  dump level, values between 2.525 V and 2.7 V can be selected in steps of 25 mV.

### Minimum non-overlap time

To ensure that the GATEHS is properly turned off before the GATELS is turned on, and vice versa, there is a minimum non-overlap time. For the minimum non-overlap time, the following values can be selected: 100 ns, 230 ns, 350 ns, 500 ns.

### Maximum non-overlap time

When the system does not detect a valley at the HB node after turning off GATEHS, the system turns on the GATELS after the maximum non-overlap time. The same counts when a peak at the HB node is not detected after turning off the GATELS and turning on the GATEHS. For the maximum non-overlap time, the following values can be selected:  $0.5 \mu s$ ,  $0.7 \mu s$ ,  $0.9 \mu s$ , or  $1.1 \mu s$ .

#### Maximum on-time

When the on-time of the GATELS or GATEHS exceeds the maximum on-time, the switch is turned off, and the LLC converter starts the next cycle. For the maximum on-time, the following values can be selected: 10  $\mu$ s, 20  $\mu$ s, 30  $\mu$ s, or 38  $\mu$ s.

### Capacitive mode regulation

When the voltage at the SNSCURLLC pin, which reflects the resonant current, drops to below a predefined value, the LLC converter starts the next switching cycle. In this way, the TEA2226AT avoids that the converter operates in capacitive mode. For the capacitive mode regulation, the following values can be selected: 20 mV to 160 mV in steps of 20 mV.

### LLC maximum ringing time

When the LLC operates in LP mode, it counts the amount of ringings. If a ringing is not detected, it assumes a peak after the timeout. This timeout can be set to 3  $\mu$ s, 5  $\mu$ s, 7.5  $\mu$ s, or 10  $\mu$ s. The appropriate value depends on the application. It must be chosen just above the maximum ringing period.

## 8.8.2.4 Feedback

#### Optocoupler current

To achieve a low no-load input power, the current through the optocoupler must be set at a low level. However, depending on the selected optocoupler, a higher optocoupler current may be requested. So, the optocoupler current can be set to different values ranging from 80 μA to 1.2 mA.

### 8.8.2.5 Operation modes

#### **HP-LP** transition level

When the output power drops to below a predefined level, the system switches from the HP to the LP mode. The HP-LP transition level can be set to different values ranging from 10 % to 54 %.

#### **HP-LP transition hysteresis**

When the system operates in LP mode, it switches over to HP mode when the output power exceeds the selected HP-LP transition level plus a hysteresis. For the hysteresis, the following values can be selected: 10 %,

TEA2226A

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Digital configurable LLC controller

20 %, 30 %, or 40 % of the selected HP-LP transition level. So, if the rated output at 100 % is 100 W, the HP-LP transition level is set at 30 % and the hysteresis is set at 10 %. The eventual hysteresis is 3 W.

#### LP-BM transition level

When the output power drops below the LP-BM transition level, the system enters burst mode. The LP-BM transition level can be set to different values ranging from 1 % to 25 %.

The actual LP-BM transition level can deviate from the selected value due to delays in the system. The deviation is most noticeable at low LP-BM transition levels. In this case, the LP-BM transition level can be fine-tuned in steps of 1 %.

#### **BM-LP transition level**

When the system operates in burst mode and output power increases to exceed the LP-BM transition level plus a hysteresis level, the system enters low-power mode. For the hysteresis, levels in the range from 5 % to 50 % can be selected, which are related to the selected LP-BM transition level. So, if the rated output at 100 % is 100 W, the LP-BM transition is set at 10 %, and the hysteresis at 50 %, the system switches from burst mode to low-power mode at a level of 15 W.

#### **BM-LP transition level filter**

When the output power slowly increases, the system ensures a smooth transition when leaving burst mode and entering low-power mode by setting a burst-mode-to-low-power-mode transition filter. When the output power exceeds the BM-LP transition level plus hysteresis for 2, 4, 8, or 16 burst cycles, it leaves the burst mode and enters the low-power mode. At a large transient at the output, the system immediately leaves burst mode.

#### **BM** repetition frequency

When the system operates in burst mode, it is regulated to a fixed frequency. This frequency can be set to different values ranging from 20 Hz to 3.2 kHz.

## BM E/C (Energy-per-cycle) increase

As the TEA2226AT regulates the output via the primary capacitor voltage, it offers the ability to increase the output power per switching cycle when it enters burst mode. For the increase of output power per switching cycle, also called E/C (Energy-per-cycle), different values can be set ranging from 1 to 4. When, for instance, the E/C is set to 4, the system increases the E/C with a factor of 4 when it enters burst mode. The initial duty cycle is then 25 %. Increasing the E/C in burst mode increases the efficiency of the system, but at the cost of a higher output voltage ripple.

## **BM** minimum cycles

As additional soft-start and soft-stop cycles reduces the audible noise, it increases the switching losses. To optimize the number of normal switching cycles in relation to the added soft-start and soft-stop switching cycles, the minimum number of normal switching cycles that can be selected ranges from 1 to 12.

#### **Burst end SNSFB current**

When the system operates in burst mode, it adjusts the number of switching cycles such that burst frequency corresponds to the selected burst frequency. If during these switching cycles the output load decreases, the output voltage increases as the system has calculated the number of required switching cycles. If the measured optocoupler current at the SNSFB pin exceeds a certain level, the system ends the burst switching cycle. This level can be between a factor of 2.5, 3.75, 5, or 7.5 times the selected optocoupler current level.

### **Burst-mode exit delay**

When the LLC is switching for a time that exceeds the burst-mode exit delay time and the output load exceeds the burst-mode level, the system leaves the burst mode. The burst-mode exit delay time ( $t_{burst-exit}$ ) can be set from 160  $\mu$ s to 4 ms in 16 steps.

Digital configurable LLC controller

### Low-power frequency

The frequency of the low-power mode can be selected by defining the ringing number at which the next low-power cycle must be started. The selection options are from 1 to 8 in steps of 1.

#### **SNSBOOST** compensation

A ripple at the input voltage of an LLC converter normally results in a ripple in the output voltage. To minimize the ripple at the output voltage, the TEA2226AT measures the input voltage of the LLC via the SNSBOOST pin and compensates the SNSCAP voltage via a feed-forward compensation. As the required compensation depends on the external components, it can be set at 8 different compensation levels.

## 8.8.3 Protection settings

## 8.8.3.1 General protections

## Fast latch reset delay time

When the system does not detect a mains voltage for a programmed period, it assumes that the mains is disconnected and resets all protections. When the mains voltage exceeds the brownin level again, the system restarts. The delay between detecting a brownout (including the brownout delay time) and resetting all protections can be programmed to different values ranging from 0 s to 10 s.

#### Safe restart time

When the system is in protection mode and the triggered protection is programmed as safe restart, it restarts after a safe-restart time. This time can be set at different values ranging from 0.5 s to 10 s.

#### Fast disable

When the SNSBOOST voltage is pulled below the  $V_{\text{scp(stop)}}$  level, the system enters the protection state. The response can be set to on/off, latched, or safe restart.

## **External OTP level**

The external application temperature is measured via an NTC connected to the SNSMAINS pin. To be able to set the appropriate NTC value and OTP level, the internal current used to measure the external NTC value can be set between 150  $\mu$ A and 1050  $\mu$ A in steps of 150  $\mu$ A.

To avoid false triggering, an internal delay occurs before the system enters protection. This delay can be set to different values between 0.5 s and 8 s.

The response of the external OTP can be latched, safe restart, or latched after safe restart. The external OTP function can also be disabled.

### Internal OTP level

The internal OTP is fixed at 135 °C.

#### **Brownin/brownout level**

For the brownin level, several values can be selected ranging from 67 V (AC) to 185 V (AC). For the hysteresis between the brownin and brownout level, several values can be selected from 2 V (AC) to 17 V (AC). The given values depend on the resistor values in the application and their tolerances.

When the mains voltage is below the brownout period for a selectable amount of time, the system enters the brownout state. For this time, several values can be selected ranging from 25 ms to 1.2 s.

Digital configurable LLC controller

## 8.8.3.2 LLC general protections

#### Maximum start-up time

When the LLC starts switching, it expects that its output voltage reaches the regulation level within a maximum start-up time. For the maximum start-up time, the following values can be selected: 25 ms, 50 ms, 100 ms, and 200 ms.

## LLC brownout level (SNSBOOST)

When the voltage at the SNSBOOST drops below a predefined level, the LLC converter enters the protection state. When the SNSBOOST voltage exceeds the brownin level, the LLC converter starts switching again.

For the LLC brownout level at the SNSBOOST, a level in the range from 1.0 V to 2.05 V can be selected.

## LLC brownin level (SNSBOOST)

The LLC brownin level defines the minimum voltage at the SNSBOOST pin before the LLC starts switching. For this level, a value ranging from 1.5 V to 2.4 V can be selected.

## LLC brownout timer (SNSMAINS)

Normally, the LLC converter continues switching until the input voltage of the LLC drops to below a minimum  $(V_{uvp(SNSBOOST)})$  level. Especially at a minimum load at the output, the LLC dropping to the minimum level can take a long time.

A timer can be initialized that disables the LLC converter when a brownout is detected at the mains input. For this time, a value can be selected ranging from 125 ms to 6 s. The option that the LLC converter remains switching until its input voltage drops to below a minimum level can also be selected.

## LLC maximum input voltage (SNSBOOST)

When an OVP is detected on the SNSBOOST pin, the response of the LLC can be set to either continue operation or stop switching. A delay can be set to either 5 ms, 50 ms, or 1250 ms.

#### **Power limit**

The maximum output power of the converter is limited by the controller. The limitation ensures that the applied load is below the maximum rating-selected components. For the maximum output power, several levels between 100 % and 200 % of the rated power can be selected.

#### **OPP level 1**

When the output power exceeds a first OPP level, a first counter is started. When the output power continuously exceeds this OPP level for a selected period, the system enters protection state. For the OPP level, a level between 0 % and -50 % below the selected power limit can be selected.

For the time, a value between 50 ms to 40 s can be selected. The response of this protection can be latched, safe restart, or latched after safe restart. This OPP level can also be disabled.

#### **OPP level 2**

When the output power exceeds a second OPP level, a second counter is started. When the output power continuously exceeds this OPP level for a selected period, the system enters protection state. For the OPP level, a level in the range from -10 % to -50 % below the selected power limit can be selected.

For the time, a value ranging from 50 ms to 3 s can be selected. The response of this protection follows the selected response of the OPP level 1. This OPP level can also be disabled.

Digital configurable LLC controller

### **OPP** duty cycle

When the output power exceeds the OPP with a duty cycle of 50 %, the OPP may or may not be triggered. So, the duty cycle at which the OPP is triggered eventually can be set using a parameter to 11 %, 20 %, 33 %, or 50 %.

### **OVP** protection

In a resonant converter, the voltage at the SUPIC pin reflects the output voltage. When the SUPIC voltage exceeds a defined level, the OVP protection is triggered. The level can be set between 1 V and 16 V above the start level in steps of 1 V.

To avoid false triggering, a delay can be set at different values ranging from 10 µs to 800 µs. The response of this protection can be latched, safe restart, or latched after safe restart. This OVP function can also be disabled.

#### **OVP** duty cycle

To minimize the sensitivity of the OVP function, a duty cycle can be set at which the OVP is eventually triggered. This parameter can be set to 11 %, 20 %, 33 %, or 50 %. If, for example, the OVP delay is set to 800  $\mu$ s, the duty cycle to 50 %, and the SUPIC voltage exceeds the OVP level for 300  $\mu$ s and drops to below the OVP level for 500  $\mu$ s, the OVP is never triggered.

## **OCP** protection

The current in the resonant tank is measured at the SNSCURLLC pin. When the voltage at this pin exceeds the OCP level, the corresponding switch (GATELS or GATEHS) is turned off and the system starts the next cycle. So, the LLC current is limited cycle-by-cycle.

If the OCP occurs for a defined number of cycles, the OCP protection is triggered. The number of cycles can be set to different values between 5 and 1000.

The response of this protection can be latched, safe restart, or latched after safe restart. The OCP protection function can also be disabled. However, the LLC current remains limited cycle-by-cycle.

## 8.8.4 Power good settings

The power good function gives a prewarning to the load that the converter is switched off due to disconnected mains or a triggered protection.

#### Power good time

The power good time is the time between the power good signal indicating that the converter is about to be switched off and the time the converter eventually stops switching. This delay can be set to 4 ms, 6 ms, 8 ms, or 10 ms.

#### Power good at OTP

The power good signal can give a prewarning when the converter is switched off due to an OTP detection. The OTP can be either an internal or an external OTP.

This function can be enabled or disabled. The delay between the transition of the power good signal and the moment that the converter stops switching equals the power good time.

#### Power good at OPP

The power good signal can give a prewarning when the converter is switched off due to an OPP detection. The prewarning can be given when the output power exceeds the OPP level1 or OPP level2 for the defined time.

This function can be enabled or disabled. The delay between the transition of the power good signal and the moment that the converter stops switching equals the power good time.

Digital configurable LLC controller

## Power good at mains brownout

The power good signal can give a prewarning when the LLC converter is switched off due to a brownout detection at the mains input of the converter.

This function can be enabled or disabled. The delay between the transition of the power good signal and the moment that the converter stops switching equals the power good time.

### Power good at LLC brownout level (SNSBOOST)

When the measured voltage at the SNSBOOST pin drops to below the selected LLC brownout level, the LLC converter stops switching. It normally occurs due to a disconnected mains.

The power good signal can give a prewarning when the converter is switched off due to this LLC brownout detection. When the voltage at the SNSBOOST drops to below a selectable value, the power good feature is triggered. The level can be selected between 1 V and 2.05 V.

## Power good at OVP (SNSBOOST)

The TEA2226AT offers a setting option to stop the LLC operation at an SNSBOOST OVP. When the LLC converter is switched off due to an SNSBOOST OVP, the power good signal can give a prewarning. This function can be enabled or disabled. The delay between the transition of the power good signal and the moment the converter stops switching equals the power good time.

## Power good ready delay

When the output voltage is in regulation after start-up, power good indicates that the output voltage is in regulation. A delay can be set between the time the output voltage reaches the regulation level and the transition of the power good signal. This delay can be set at different values between 0 s and 1 s.

### Power good transition time

The power good function is combined with the feedback network connected at the SNSFB pin. To avoid that a trigger of the power good function disturbs the regulation loop, its transition time must have a predefined value. This time can be set at 0.85 ms, 1.8 ms, 2.6 ms, or 3.5 ms.

Digital configurable LLC controller

# 9 Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
Voltages	'				
V <sub>SUPHV</sub>	voltage on pin SUPHV	during mains surge t < 0.5 s; 10 times at a 0.1 Hz interval	-0.4	+685	V
SR <sub>SUPHV</sub>	slew rate on pin SUPHV		-50	+50	V/ns
V <sub>SUPIC</sub>	voltage on pin SUPIC		-0.4	+36	V
V <sub>SUPHS</sub>	voltage on pin SUPHS	during mains surge t < 0.5 s; 10 times at a 0.1 Hz interval	-0.3	+685	V
		regarding pin HB	-0.4	+13	V
V <sub>GATEHS</sub>	voltage on pin GATEHS		V <sub>HB</sub> - 0.4	V <sub>SUPHS</sub> + 0.4	V
$V_{HB}$	voltage on pin HB	during mains surge t < 0.5 s; 10 times at a 0.1 Hz interval	-0.3	+685	V
		t < 1 μs	-13	-	V
SR <sub>HB</sub>	slew rate on pin HB		-70	+70	V/ns
V <sub>GATELS</sub>	voltage on pin GATELS	[1]	-0.4	+14	V
V <sub>NF2</sub>	voltage on pin NF2		-0.4	+14	V
V <sub>SNSCAP</sub>	voltage on pin SNSCAP		-0.4	+12	V
V <sub>SNSCURLLC</sub>	voltage on pin SNSCURLLC		-0.4	+12	V
V <sub>NF1</sub>	voltage on pin NF1	DC; maximum	-0.4	+12	V
V <sub>SNSFB</sub>	voltage on pin SNSFB		-0.4	+12	V
V <sub>SNSBOOST</sub>	voltage on pin SNSBOOST		-0.4	+12	V
V <sub>SNSMAINS</sub>	voltage on pin SNSMAINS		-0.4	+12	V
General					'
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> < 75 °C	-	0.7	W
T <sub>j</sub>	junction temperature		-40	+150	°C
T <sub>stg</sub>	storage temperature		-55	+150	°C
Latch-up					•
l <sub>lu</sub>	latch-up current	all pins; according to JEDEC; standard 78D	-100	+100	mA

Digital configurable LLC controller

Table 5. Limiting values...continued

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
Electrostatic di	scharge				
V <sub>ESD</sub>	electrostatic discharge voltage	human body model			
		SUPHS, GATEHS, HB, , and SUPHV pins	-1000	+1000	V
		other pins	-2000	+2000	V
		charged device model			
		all pins	-500	+500	V

<sup>[1]</sup> Although the GATELS pin is an output pin, the maximum voltage of this pin must not exceed the maximum drive output voltage by 20 %.

## 10 Thermal characteristics

Table 6. Thermal characteristics

Symbol	Parameter	Conditions	Тур	Unit
R <sub>th(j-a)</sub>	thermal resistance from junction to ambient	In free air; JEDEC test board	107	K/W
R <sub>th(j-c)</sub>	thermal resistance from junction to case	In free air; JEDEC test board	60	K/W

Digital configurable LLC controller

### 11 Characteristics

#### Table 7. Characteristics

 $T_{amb}$  = 25 °C;  $V_{SUPIC}$  = 19.5 V; all voltages are measured with respect to GND; currents are positive when flowing into the IC; unless otherwise specified. Expected values for different MTP settings (min/typ/max) are provided in the documentation in the Ringo software.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
SUPHV pin				'		
I <sub>off(SUPHV)</sub>	off-state current on pin SUPHV	V <sub>SUPHV</sub> = 400 V; V <sub>SUPIC</sub> = 19 V	2	5	8	μΑ
V <sub>SUPHV</sub>	voltage on pin SUPHV	V <sub>SUPIC</sub> = 19 V; I <sub>SUPHV</sub> = 3 mA	22	26	30	V
I <sub>ch(SUPIC)</sub>	charge current on pin SUPIC	V <sub>SUPHV</sub> = 50 V; V <sub>SUPIC</sub> = 19 V	-10	-6.5	-3	mA
SUPIC pin	1	ı			I	
V <sub>start(SUPIC)</sub>	start voltage on pin SUPIC		18.2	19.0	19.7	V
V <sub>start(hys)</sub> SUPIC	start voltage hysteresis on pin SUPIC		-0.9	-0.7	-0.5	V
V <sub>low(hys)</sub> SUPIC	low voltage hysteresis on pin SUPIC		0.5	0.7	0.9	V
V <sub>low(SUPIC)</sub>	low voltage on pin SUPIC		11.5	12.0	12.5	V
V <sub>uvp(SUPIC)</sub>	undervoltage protection voltage on pin SUPIC		9.6	10.0	10.4	V
$\Delta_{(vlow-vuvp)}$ SUPIC	low voltage to undervoltage protection voltage difference on pin SUPIC	V <sub>low</sub> – V <sub>uvp</sub>	1.7	2.0	2.3	V
V <sub>rst(SUPIC)</sub>	reset voltage on pin SUPIC		8.6	9.0	9.4	V
I <sub>CC(SUPIC)</sub>	supply current on pin SUPIC	non-operating mode; $I_{snsfb} = -100 \mu A;$ $I_{snscap} = -100 \mu A$	700	890	1100	μΑ
		operating mode; $f_{HB} = 100 \text{ kHz};$ $I_{snsfb} = -80 \mu\text{A};$ $I_{snscap} = -100 \mu\text{A};$ driver pins open	6	8	10	mA
Output overvolta	ige protection					
V <sub>O(ovp)</sub> SUPIC	output overvoltage protection voltage on pin SUPIC		27.9	28.7	29.5	V
t <sub>d(ovp)</sub> SUPIC	overvoltage protection delay time on pin SUPIC		45	50	55	μs
Mains voltage s	sensing (SNSMAINS pin)			-	I	
I <sub>clamp(max)</sub>	maximum clamp current	V <sub>SNSMAINS</sub> = 9.5 V	2.5	3.5	4.5	mA
I <sub>I(lim)</sub> SNSMAINS	limiting input current on pin SNS MAINS	SNSMAINS limit measuring input current	17.2	18.6	20.0	μΑ
I <sub>bi</sub>	brownin current		5.3	5.5	5.7	μA

Digital configurable LLC controller

Table 7. Characteristics...continued

 $T_{amb}$  = 25 °C;  $V_{SUPIC}$  = 19.5 V; all voltages are measured with respect to GND; currents are positive when flowing into the IC; unless otherwise specified. Expected values for different MTP settings (min/typ/max) are provided in the documentation in the Ringo software.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
I <sub>bo</sub>	brownout current		4.6	4.8	5.0	μΑ
I <sub>bo(hys)</sub>	hysteresis of brownout current	I <sub>bi</sub> – I <sub>bo</sub>	0.66	0.73	0.80	μΑ
t <sub>d(det)bo</sub>	brownout detection delay time		270	300	330	ms
	nperature measurement		1			
I <sub>o(SNSMAINS)</sub>	output current on pin SNS MAINS		-645	-600	-565	μA
t <sub>det(max)NTC</sub>	NTC maximum detection time		45	50	55	μs
V <sub>det(SNSMAINS)</sub>	detection voltage on pin SNS MAINS	NTC measurement; I <sub>SNSMAINS</sub> = -600 μA	2.89	3.08	3.27	V
$t_{d(otp)}$	overtemperature protection delay time		3.6	4.0	4.4	s
X-capacitor dis	charge			•		
t <sub>d(dch)</sub>	discharge delay time		180	200	220	ms
SNSBOOST pir	1		1		'	,
I <sub>pd(SNSBOOST)</sub>	pull-down current on pin SNS BOOST	at V <sub>SNSBOOST</sub> = V <sub>scp(stop)</sub>	25	50	75	nA
V <sub>stop(ovp)</sub>	overvoltage protection stop voltage	[2]	2.59	2.63	2.67	V
V <sub>uvp(SNSBOOST)</sub>	undervoltage protection voltage on pin SNSBOOST		1.60	1.65	1.70	V
V <sub>start(SNSBOOST)</sub>	start voltage on pin SNSBOOST		2.23	2.30	2.37	V
V <sub>det(SNSBOOST)</sub>	detection voltage on pin SNS BOOST	Power good detection voltage	1.715	1.750	1.785	V
$\Delta V_{reg\text{-det}}$	voltage difference between regulation and detection	pin SNSBOOST; indication of the power good delay	0.72	0.75	0.78	V
Fast disable fu	nction		1			
$V_{\text{scp(stop)}}$	stop short-circuit protection voltage		0.37	0.39	0.41	V
V <sub>scp(start)</sub>	start short-circuit protection voltage		0.40	0.45	0.50	V
t <sub>fitr(scp)</sub>	short-circuit protection filter time		4	10	15	μs
SNSCAP pin	1	1	1	1	1	
V <sub>AV(regd)</sub> SNSCAP	regulated average voltage on pin SNSCAP	regulated average of $V_{hs(SNSCAP)}$ and $V_{ls(SNSCAP)}$	2.44	2.50	2.56	V
I <sub>bias(max)</sub> SNSCAP	maximum bias current on pin SNSCAP		-245	-210	-175	μA

Digital configurable LLC controller

Table 7. Characteristics...continued

 $T_{amb}$  = 25 °C;  $V_{SUPIC}$  = 19.5 V; all voltages are measured with respect to GND; currents are positive when flowing into the IC; unless otherwise specified. Expected values for different MTP settings (min/typ/max) are provided in the documentation in the Ringo software.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>range</sub> (SNSCAP)	voltage range on pin SNSCAP	SNSCAP voltage range for the high-side comparator, V <sub>hs(SNSCAP)</sub> .	2.35	-	4.50	V
		SNSCAP voltage range for the low-side comparator, $V_{\text{Is(SNSCAP)}}$ .	0.50	-	2.65	V
V <sub>acc</sub>	voltage accuracy	SNSCAP comparator voltage accuracy	-10	-	+10	mV
$\Delta V_{th(SNSCAP)}$	threshold voltage difference on pin SNSCAP	V <sub>hs(SNSCAP)</sub> - V <sub>ls(SNSCAP)</sub> ; P <sub>out</sub> = 200 %; V <sub>SNSBOOST</sub> < 1.9 V	3.12	3.27	3.42	V
		V <sub>hs(SNSCAP)</sub> - V <sub>ls(SNSCAP)</sub> ; P <sub>out</sub> = 100 %; V <sub>SNSBOOST</sub> = 2.5 V	0.93	1.01	1.09	V
t <sub>d</sub>	delay time	delay between exceeding V <sub>caph</sub> /V <sub>capl</sub> and driver off; dV/dt = 0.1 V/µs	-	-	125	ns
SNSCURLLC pi	n					
V <sub>bias</sub> (SNSCURLLC)	bias voltage on pin SNSCURLLC		2.4	2.5	2.6	V
R <sub>O(SNSCURLLC)</sub>	output resistance on pin SNS CURLLC		45	55	65	kΩ
V <sub>Imtr(ocp)</sub>	overcurrent protection voltage limiter	soft-start overcurrent limiter	0.66	0.75	0.83	V
V <sub>ocp(LLC)</sub>	LLC overcurrent protection voltage	positive level V <sub>SNSCURLLC</sub> - V <sub>bias(SNSCURLLC)</sub>	1.35	1.50	1.65	V
		negative level V <sub>SNSCURLLC</sub> - V <sub>bias(SNSCURLLC)</sub>	-1.65	-1.50	-1.35	V
V <sub>reg(capm)</sub>	capacitive mode regulation level	positive level VSNSCURLLC - Vbias(SNSCURLLC)	83	100	115	mV
		negative level V <sub>SNSCURLLC</sub> - V <sub>bias</sub> (SNSCURLLC)	-115	-100	-83	mV
V <sub>det(zero)</sub>	zero detection voltage	detected as ≥ 0	-16	-11	-6	mV
		detected as ≤ 0	6	11	16	mV
SNSFB pin						
V <sub>low(SNSFB)</sub>	low voltage on pin SNSFB	indicating iPowerGood = '1'; 0 μA < I <sub>opto</sub> < 3.5 mA.	0.43	0.50	0.57	V
V <sub>high(SNSFB)</sub>	high voltage on pin SNSFB	indicating iPowerGood = '0'; 0 μA < I <sub>opto</sub> < 3.5 mA.	3.3	3.5	3.8	V
t <sub>t(powergood)</sub>	powergood transition time		1.5	1.8	2.0	ms
Optobias regulat	or					
I <sub>reg(SNSFB)</sub>	regulation current on pin SNSFB		-90	-80	-70	μA

TEA2226AT

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Digital configurable LLC controller

Table 7. Characteristics...continued

 $T_{amb}$  = 25 °C;  $V_{SUPIC}$  = 19.5 V; all voltages are measured with respect to GND; currents are positive when flowing into the IC; unless otherwise specified. Expected values for different MTP settings (min/typ/max) are provided in the documentation in the Ringo software.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Burst mode reg	julator			'		
I <sub>start(burst)</sub>	burst mode start current	LLC burst mode	-110	-100	-90	μA
I <sub>stop(burst)</sub>	burst mode stop current		-220	-200	-180	μΑ
Burst mode				'		
f <sub>burst(max)</sub>	maximum burst mode frequency		720	800	880	Hz
t <sub>d(burst)exit</sub>	burst-mode exit delay time		3.6	4	4.4	ms
Power good c	haracteristics (pin SNSFB)		'		'	
t <sub>d(powergood)</sub>	power good delay time	delay power good after output voltage ready	4.5	5.0	5.5	ms
		power good delay before protection	3.6	4.0	4.4	ms
LLC timing					'	
t <sub>on(min)LLC</sub>	LLC minimum on-time		1105	1230	1355	ns
t <sub>on(max)LLC</sub>	LLC maximum on-time		18	20	22	μs
Overpower pro	otection		'			_
t <sub>startup(max)</sub>	maximum start-up time		90	100	110	ms
t <sub>d(opp)</sub>	overpower protection delay time	OPP 1	45	50	55	ms
HB pin						
$\Delta V_{\text{det(min)}}/\Delta t$	minimum slope detection voltage	positive and negative minimum slope detection level.	-	-	120	V/µs
$\Delta V_{\text{det(max)}} / \Delta t$	maximum slope detection voltage	positive and negative maximum slope detection level.	50	-	-	V/ns
t <sub>no(min)</sub>	minimum non-overlap time		200	230	260	ns
t <sub>no(max)</sub>	maximum non-overlap time		0.99	1.10	1.21	μs
GATELS pin						
I <sub>source(peak)</sub>	source peak current	V <sub>SUPIC</sub> ≥ 13 V	<sup>[1]</sup> -1.1	-0.9	-0.7	А
I <sub>sink(peak)</sub>	sink peak current	C <sub>load</sub> = 4.7 nF; V <sub>SUPIC</sub> ≥ 13 V	0.7	1.0	1.3	А
R <sub>OH(GATELS)</sub>	HIGH-level output resistance on pin GATELS	I <sub>GATELS</sub> = -30 mA; V <sub>SUPIC</sub> = 14.5 V	8	14	20	Ω
R <sub>OL(GATELS)</sub>	LOW-level output resistance n pin GATELS	I <sub>GATELS</sub> = 30 mA; V <sub>SUPIC</sub> = 14.5 V	3	4.5	6	Ω

Digital configurable LLC controller

Table 7. Characteristics...continued

 $T_{amb}$  = 25 °C;  $V_{SUPIC}$  = 19.5 V; all voltages are measured with respect to GND; currents are positive when flowing into the IC; unless otherwise specified. Expected values for different MTP settings (min/typ/max) are provided in the documentation in the Ringo software.

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
V <sub>OH(GATELS)</sub>	HIGH-level output voltage on pin GATELS	$f_{sw} = 100 \text{ kHz};$ $I_{load} = 0;$ $V_{SUPIC} \ge 14.5 \text{ V}$	[1]	11.5	12.3	13.1	V
		$f_{sw}$ = 100 kHz; $I_{load}$ = 0; $V_{SUPIC}$ = 9.5 V	[1]	9.45	9.5	9.55	V
V <sub>OL(GATELS)</sub>	LOW-level output voltage on pin GATELS	I <sub>GATELS</sub> = 40 mA; V <sub>SUPIC</sub> ≥ 14.5 V		0.10	0.17	0.24	V
t <sub>r(GATELS)</sub>	rise time on pin GATELS	1 V to 9 V; V <sub>SUPIC</sub> = 13 V; 1 nF load	[1]	10	15	20	ns
t <sub>f(GATELS)</sub>	fall time on pin GATELS	9 V to 1 V; V <sub>SUPIC</sub> = 13 V; 1 nF load	[1]	10	15	20	ns
GATEHS pin		1			1	1	
I <sub>source(peak)</sub>	source peak current	C <sub>load</sub> = 4.7 nF; V <sub>SUPHS</sub> - V <sub>HB</sub> = 12 V	[1]	-0.8	-0.6	-0.4	А
I <sub>sink(peak)</sub>	sink peak current	$C_{load}$ = 4.7 nF; $V_{SUPHS}$ - $V_{HB}$ = 12 V	[1]	8.0	1.1	1.4	A
R <sub>OH(GATEHS)</sub>	HIGH-level output resistance on pin GATEHS	$I_{GATEHS}$ = -30 mA; $V_{SUPHS}$ - $V_{HB}$ = 12 V		6	10	14	Ω
R <sub>OL(GATEHS)</sub>	LOW-level output resistance on pin GATEHS	$I_{GATEHS}$ = 30 mA; $V_{SUPHS}$ - $V_{HB}$ = 12 V		3	5	7	Ω
V <sub>OH(GATEHS)</sub>	HIGH-level output voltage on pin GATEHS	$f_{sw}$ = 100 kHz; $I_{load}$ = 0; $V_{SUPHS}$ - $V_{HB}$ = 12 V	[1]	11.5	12	12.5	V
V <sub>OL(GATEHS)</sub>	LOW-level output voltage on pin GATEHS	I <sub>GATEHS</sub> = 40 mA; V <sub>SUPHS</sub> - V <sub>HB</sub> = 12 V		0.1	0.2	0.3	V
t <sub>r(GATEHS)</sub>	rise time on pin GATEHS	1 V to 9 V; V <sub>SUPHS</sub> - V <sub>HB</sub> = 11 V; 1 nF load		15	25	35	ns
t <sub>f(GATEHS)</sub>	fall time on pin GATEHS	9 V to 1 V; V <sub>SUPHS</sub> - V <sub>HB</sub> = 11 V; 1 nF load	[1]	10	15	20	ns
SUPHS pin							
V <sub>rst(SUPHS</sub> )	reset voltage on pin SUPHS	+25 °C < T < 125 °C		5.5	7.2	8.2	V
System protect	ction					ı	
t <sub>d(restart)</sub>	restart delay time			0.9	1.0	1.1	s
t <sub>d(flr)</sub>	fast latch reset delay time			45	50	55	ms
I <sup>2</sup> C communic	eation						
V <sub>IL</sub>	LOW-level input voltage			0	-	0.8	V

TEA2226AT

Product data sheet

Digital configurable LLC controller

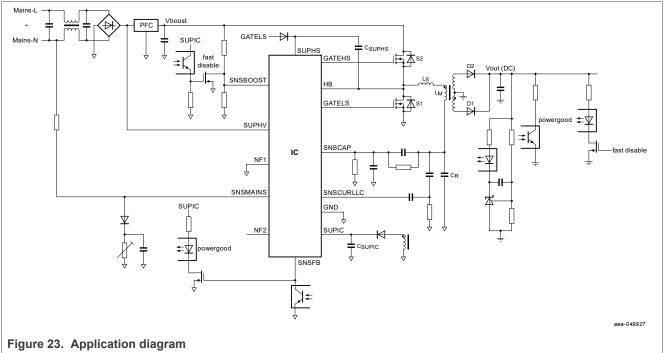
Table 7. Characteristics...continued

 $T_{amb}$  = 25 °C;  $V_{SUPIC}$  = 19.5 V; all voltages are measured with respect to GND; currents are positive when flowing into the IC; unless otherwise specified. Expected values for different MTP settings (min/typ/max) are provided in the documentation in the Ringo software.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit		
V <sub>IH</sub>	HIGH-level input voltage		1.4	-	5.0	V		
I <sub>pd</sub> (SNSCAP)	pull-down current on pin SNSCAP	To ensure proper operation, the external pull-up must always be lower than 6.8 mA.	6.8	-	-	mA		
Overtemperatur	Overtemperature protection							
T <sub>otp</sub>	overtemperature protection trip		120	135	150	°C		

- Covered by correlating measurement TEA2226AT MTP programming: "Disable LLC after SNSBOOST OVP" = off As the minimum limit determines the application design, the maximum limit is not relevant.

## **Application information**



# 13 Ringo parameter settings

Table 8. Ringo parameter/IC parameter settings

	Ringo parameter/IC parameter se	IC parameter name	Value	Unit	Binary value
1	NXP ID code	nxp_id_code	0x01	-	1
2	Boost OVP (SNSBOOST)	boost_ovp_snsboost	OK	-	0
3	LLC OPP 1	Ilc_opp1	OK	-	0
4	LLC OPP 2	Ilc_opp2	OK	-	0
5	LLC maximum start-up time	Ilc_max_startup_time	OK	-	0
6	LLC OCP	Ilc_ocp	OK	-	0
7	LLC OVP	Ilc_ovp_prot	OK	-	0
8	External OTP	ext_otp	OK	-	0
9	Internal OTP	int_otp	OK	-	0
10	Fast disable	fast_disable	OK	-	0
11	LLC maximum on-time	Ilc_max_on_time	OK	-	0
12	LLC maximum lopto	Ilc_max_iopto	OK	-	0
13	LLC capacitive mode	Ilc_cap_mode	OK	-	0
14	MTP read failure	mtp_read_fail	OK	-	0
15	OPP via SUPIC UVP	opp_via_supic_uvp	OK	-	0
16	Write lock	write_lock	write enabled	-	0
17	Read lock	read_lock	read enabled	-	0
18	Brownin level	brownin_lvl	5.5	μΑ	0
19	Brownin/brownout hysteresis	brownin_hys	0.75	μΑ	0
20	Brownout delay	t_brownout	50	ms	0
21	Mains resistor value	rmains	20	ΜΩ	0
22	Mains SNS resistors	nr_mains_resistors	1	resistor	0
23	LLC soft-start speed	Ilc_tsoftstart	7	Х	0
24	SUPIC control near UVP	dis_vlow	enabled	-	0
25	SUPIC start level	sup_start	19	V	0
26	LLC converter	Ilc_disable	enabled	-	0
27	Vdump level	vdump	2.55	V	1
28	Capacitive mode regulation level	capm_lvl	100	mV	0
29	Maximum on-time	Ilc_max_on	20	μs	0
30	LLC LP mode	lpmode_dis	enabled	-	0
31	OTP/external burst mode select	ext_burstmode	Ext OTP	-	0
		· L			-

Digital configurable LLC controller

Table 8. Ringo parameter/IC parameter settings...continued

	Ringo parameter name	IC parameter name	Value	Unit	Binary value
32	LLC non-overlap mode	llc_non_overlap	adaptive	-	0
33	Maximum non-overlap time	t_no_max	1.1	μs	0
34	Minimum non-overlap time	t_no_min	230	ns	0
35	Opto current level	iopto	80	μA	0
36	Burst-on end by opto current	iopto_bm_end	2.5	Х	0
37	SNSBOOST compensation	snsb_comp	-1.4	-	0
38	HP-LP transition level	hp_lp_lev	30	%	0
39	HP-LP hysteresis	hp_lp_hys	20	%	0
40	Opto regulation level	opto_reg_level	standard	-	0
41	Opto regulation gain increase	opto_reg_gain_incr	96	-	0
42	LP number of peaks	lp_nr_peaks	2	-	0
43	LP-BM transition level	lp_bm_lev	10	%	0
44	BM-LP hysteresis	bm_lp_hys	50	%	7
45	BM LP hysteresis filter	bm_lp_filt	4	-	0
46	LP-BM delay time	lp_bm_del	0	s	0
47	Zero power slope	min_slope	6	mV/µs	0
48	dVcap offset	vcap_offset	0	mV	0
49	BM frequency	bm_freq	800	Hz	0
50	BM energy-per-cycle increase	bm_incr	1	X	0
51	Minimum cycles in burst	min_nr_cycl	3	-	0
52	Number of BM soft-start cycles	nr_bm_sstart	2	-	2
53	Number of BM soft-stop cycles	nr_bm_sstop	2	-	2
54	Burst mode exit delay	bm_exit_del	4000	μs	0
55	Slope of 4th BM soft-start cycle	start_cycle4	2	-	0
56	Slope of 3rd BM soft-start cycle	start_cycle3	6	-	0
57	Slope of 2nd BM soft-start cycle	start_cycle2	10	-	5
58	Slope of 1st BM soft-start cycle	start_cycle1	96	-	0
59	Slope of 4th BM soft-stop cycle	stop_cycle4	96	-	0
60	Slope of 3rd BM soft-stop cycle	stop_cycle3	24	-	0
61	Slope of 2nd BM soft-stop cycle	stop_cycle2	10	-	4
62	Slope of 1st BM soft-stop cycle	stop_cycle1	4	-	2
63	External OTP current level	eotp_lvl	600	μΑ	0

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Table 8. Ringo parameter/IC parameter settings...continued

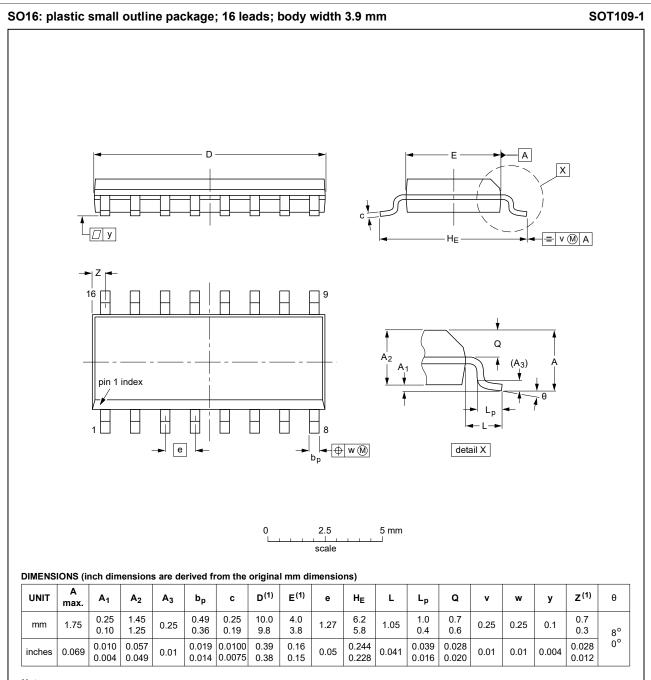
	Ringo parameter/IC parameter se	IC parameter name	Value	Unit	Binary value
64	External OTP delay time	t_eotp	4	s	0
65	OTP mode	otp_ltch	safe restart	-	0
66	OTP number of restarts to latch	otp_nr_rest	0	-	0
67	Fast disable by SNSBOOST	llc_fast_disable	latched	-	3
68	X-cap discharge delay time	t_xcap_disch	200	ms	0
69	Fast latch reset delay time	t_flr	50	ms	0
70	Safe restart timer	sr_time	1	s	0
71	Boost OVP level (SNSBOOST)	ovp_lvl	2.63	V	0
72	LLC soft-start current limit	max_llc_istartup	0.75	V	0
73	Maximum (start-up) frequency	max_llc_freq	350	kHz	0
74	Maximum start-up time	t_start_max	100	ms	0
75	LLC maximum ringing time	max_tring_llc	5	μs	0
76	LLC OCP filter	Ilc_tocp	5	-	0
77	LLC OCP mode	llc_ocp_ltch	safe restart	-	0
78	OCP restarts to latch	Ilc_ocp_nr_rest	0	-	0
79	LLC (SUPIC) OVP level	llc_ovp	10	V	0
80	LLC (SUPIC) OVP delay	Ilc_tovp	50	μs	0
81	Down-counts/up-count (SUPIC) OVP	llc_ovp_nr_dwn	1	-	0
82	(SUPIC) OVP mode	llc_ovp_ltch	safe restart	-	0
83	OVP restarts to latch	Ilc_ovp_nr_rest	0	-	0
84	LLC brownin level (SNSBOOST)	snsb_start	2.3	V	6
85	LLC brownout level (SNSBOOST)	snsb_stop	1.65	V	3
86	Disable LLC after SNSBOOST OVP	dis_ovp_snsb	off	-	3
87	Disable LLC after mains brownout	llc_dis_bo	250	ms	0
88	OPP1 level	opp1_lvl	-20	%	0
89	OPP1 time delay	opp1_time	50	ms	0
90	Fast disable FLR	fast_disable_flr	FD not starts FLR	-	0
91	OPP2 level	opp2_lvl	-10	%	0
92	OPP2 time delay	opp2_time	infinite	-	0
93	Down-counts/up-count OPP	opp_nr_dwn	1	-	0

# Digital configurable LLC controller

Table 8. Ringo parameter/IC parameter settings...continued

	Ringo parameter name	IC parameter name	Value	Unit	Binary value
94	OPP mode	opp_ltch	safe restart	-	0
95	OPP restarts to latch	opp_nr_rest	0	-	0
96	LLC power limitation level	pow_lim	155	%	0
97	Power good inverted	pgood_inv	disabled	-	0
98	Power good SNSBOOST reset level	pgd_lvl	1.75	V	0
99	Power good at mains brownout	pgd_bo	enabled	-	0
100	Power good at OPP	pgd_opp	enabled	-	0
101	Power good at OTP	pgd_otp	enabled	-	0
102	Power good signal at SNSBOOST OVP	pgd_ovp_sbo	enabled	-	0
103	Power good signal edge (SNSFB)	pgd_tr	1.8	ms	0
104	Power good delay	pgd_del	5	ms	0
105	Power good time to protection	pgd_tim	4	ms	0
106	Vendor code	mtp_code	0	-	0

# 14 Package outline



#### Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

OUTLINE VERSION	REFERENCES				EUROPEAN	ISSUE DATE
	IEC	JEDEC	JEITA		PROJECTION	133UE DATE
SOT109-1	076E07	MS-012				<del>99-12-27</del> 03-02-19

Figure 24. Package outline SOT109-1 (SO16)

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# 15 Revision history

#### Table 9. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
TEA2226AT v.1.1	20231102	Product data sheet	-	TEA2226AT v.1
Modifications:	New template for NXP technical documentation.			
TEA2226AT v.1	20230714	Product data sheet	-	-

# **Legal information**

#### Data sheet status

Document status <sup>[1][2]</sup>	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions".
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### **Contents**

1	General description	1
2	Features and benefits	
2.1	Distinctive features	
2.2	Green features	2
2.3	Protection features	2
3	Applications	
4	Ordering information	3
5	Marking	
6	Block diagram	
7	Pinning information	5
7.1	Pinning	5
7.2	Pin description	
8	Functional description	6
8.1	Supply voltages	6
8.1.1	Start-up and supply voltage	
8.1.2	High-side driver floating supply (SUPHS	
	pin)	8
8.2	LLC system regulation	
8.2.1	Output power regulation loop	
8.2.2	Output voltage start-up	
8.3	Modes of operation	
8.3.1	High-power mode	
8.3.2	Low-power mode	
8.3.3	Burst mode	
8.3.3.1	Frequency regulation	
8.3.3.2	Negative transient response	
8.3.3.3	Burst-mode exit delay function	
8.4	Optobias regulation	
8.5	Active X-capacitor discharge	
8.6	Protections	
8.6.1	Undervoltage protection SUPIC	.21
8.6.2	MTP fail	
8.6.3	Internal overtemperature protection (OTP)	. 21
8.6.4	Brownin/brownout and external	
	overtemperature protection	.22
8.6.5	Short-circuit protection/fast disable	.23
8.6.6	Brownout mains	
8.6.7	Overvoltage protection (SNSBOOST pin)	.23
8.6.8	Undervoltage protection SUPHS	
8.6.9	Undervoltage protection boost	
8.6.10	Overvoltage protection (SUPIC pin)	
8.6.11	Capacitive mode regulation (CMR)	
8.6.12	Overcurrent protection	
8.6.13	Maximum start-up time	
8.6.14	Overpower protection	
8.6.15	Latched, safe restart, or latched after safe	
	restart	.26
8.6.16	Fast latch reset	.26
8.7	Power good function	.27
8.8	Settings	
8.8.1	General settings	
8.8.1.1	Protection register	.28
8.8.1.2	Supply start level	

8.8.1.3	Read lock	28
8.8.1.4	Write lock	28
8.8.1.5	Reset to the default values	28
8.8.1.6	Customer MTP code	28
8.8.1.7	Active X-capacitor discharge	29
8.8.1.8	Mains measurement impedance	
8.8.1.9	Number of mains resistors	
8.8.2	LLC settings	29
8.8.2.1	LLC disable	
8.8.2.2	Start-up	29
8.8.2.3	LLC switching	30
8.8.2.4	Feedback	30
8.8.2.5	Operation modes	30
8.8.3	Protection settings	32
8.8.3.1	General protections	32
8.8.3.2	LLC general protections	33
8.8.4	Power good settings	34
9	Limiting values	36
10	Thermal characteristics	37
11	Characteristics	38
12	Application information	43
13	Ringo parameter settings	44
14	Package outline	
15	Revision history	
	Legal information	

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