The Automotive Math and Motor Control Library (AMMCLib) set provides essential building blocks for rapid development of automotive embedded applications with high-performance arithmetic, trigonometric, digital signal processing and math functions. The AMMCLib is available as a production-ready precompiled or source code package.

A significant portion of the AMMCLib supports both sensor-based and sensorless motor control applications; it also assists with fixed-point fractional 16/32-bit and single-precision floating-point arithmetic. All AMMCLib functions come with MATLAB® and Simulink® bit-accurate models for model-based design, simulation and code generation supporting Embedded Coder®.
Auto AMMCLIB General Architecture Block Diagram

- GMCLIB: General Motor Control Library
  - Park/Clark Transformation
  - Inverse Park/Clark
  - Space Vector Modulation
  - DC Bus Ripple Elimination
  - PMSM Decoupling
  - BackEMF Observer
  - Tracking Observer

- AMCLIB: Advanced Motor Control Library

- GFLIB: General Function Library
- GDFLIB: General Digital Filter Library
  - Sine, Cosine, Tangent
  - Inverse Sine, Cosine, Tangent
  - Hysteresis
  - LUT, Ramp, Limitation
  - First, Second Order IIR Filter

- MLIB: Mathematical Library
  - Absolute Value
  - Addition, Subtraction
  - Multiplication, Division
  - Right/Left Shift
  - Type Conversion

Auto AMMCLIB Architecture for KEA Block Diagram

- GMCLIB: General Motor Control Library
  - Park/Clark Transformation
  - Inverse Park/Clark
  - Space Vector Modulation
  - DC Bus Ripple Elimination
  - PMSM Decoupling

- GFLIB: General Function Library
- GDFLIB: General Digital Filter Library

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  - Absolute Value
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View additional information for Automotive Math and Motor Control Library (AMMCLib).