



# Installing and using CW 10.6 for TPMS applications

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Revision 4

May 2015

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## 1. Installing Code Warrior for MCUs v10.6

### a. General information

Code Warrior v10.6 for MCUs is a new version based on the Eclipse development platform. It is compatible with the following host platforms:

- Microsoft® Windows XP 32-bit and 64-bit (Professional Edition)
- Microsoft Windows 7 32-bit and 64-bit (Home Premium Edition and Professional Edition)
- Microsoft Windows 8 32-bit and 64-bit (Home Premium Edition and Professional Edition)

More information concerning the system requirements, target interfaces, new features... can be found on the website. For that, go to [www.freescale.com](http://www.freescale.com) > *Software and Tools* > *Code Warrior Development Tools*. To download the IDE with an evaluation license go to the *Evaluation Software* page:

**CodeWarrior Embedded Software Development Tools**

CodeWarrior embedded software development studio is a complete integrated development environment (IDE) that provides a highly visual and automated framework to accelerate development of the most complex embedded applications.

**CodeWarrior Development Suites for Networked Applications**

- Architect (A Suite)**  
This suite would best be used by personnel who have a need to dig deep into the networking aspects of a development project.
- Specialist (S Suite)**  
Product creation for every market Board-analysis tools
- Developer (D Suite)**  
Multicore processors development on: Power Architecture QorIQ LS QorIQ Converge SoCs StarCore technology

**CodeWarrior Development Suites**

- Professional (P Suite)**  
Full featured development suites
- Standard (S Suite)**  
Selectively featured development suites
- Basic (B Suite)**  
Compiler upgrades to special editions, Linux Applications Editions and Flash programmers

**Download Now**

**Evaluation Software**  
Evaluation Editions are available for free download and work for a limited time.

**Special Edition**  
Special Editions are fully functional free download with code size restrictions.

**Helpful Tools**

**CodeWarrior Suite Selector**  
Find best suite for your development needs.

**Register Now**  
Register your new product or support.

**Featured Videos**

**Video Vault**

## b. Downloading the IDE

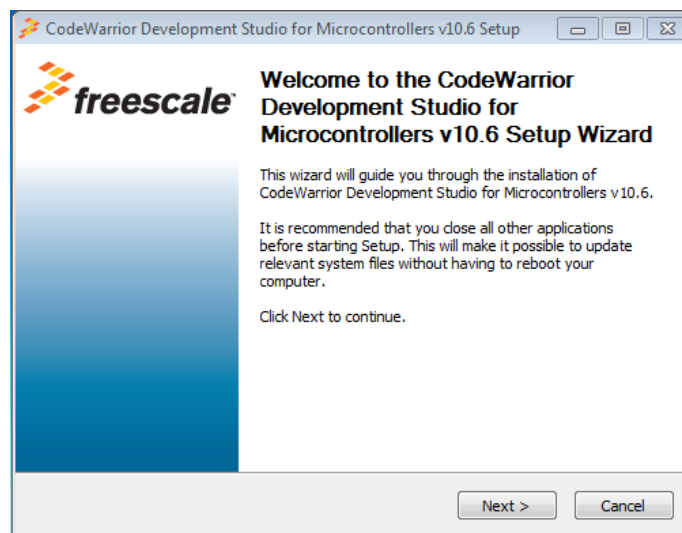
The evaluation version is free and available on this page. On this page choose the Eclipse IDE for MCUs v10.6.

### IDE - Debug, Compile and Build Tools

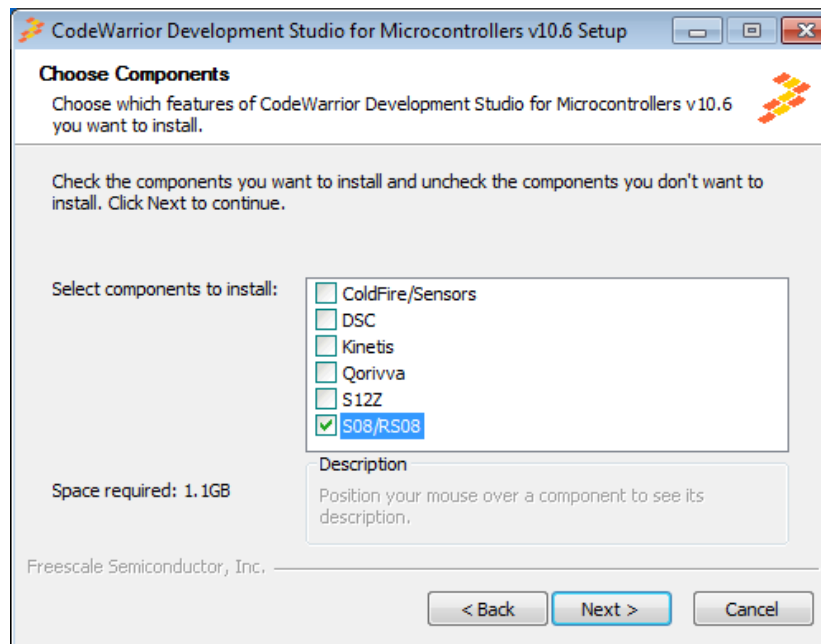
ID and Description	Vendor ID	Rev #	Availability
CodeWarrior Development Studio for 56800/E Digital Signal Controllers (Classic IDE) v8.3 CodeWarrior Development Studio for 56800/E Digital Signal Controllers v8.3 allows both 56800 and 56800/E developers build and deploy even the most sophisticated systems quickly and easily by integrating support for both architectures into a single...	FREESCALE	8.3	<a href="#">Buy Now</a> <a href="#">Evaluation</a>
CodeWarrior Development Studio for 68K Embedded Systems (Classic IDE) v3.2 CodeWarrior Development Tools for 68K v3.2 Embedded Systems are powerful development tools that speed time to market by allowing you to create, compile, assemble, deploy and debug within a single, integrated development environment.	FREESCALE	3.2	<a href="#">Buy Now</a> <a href="#">Evaluation</a>
CodeWarrior Development Studio for ColdFire Architectures (Classic IDE) v7.2 CodeWarrior Development Studio for ColdFire Architectures v7.2 is a single, integrated tool suite designed to get you on the design fast track with ColdFire V2, V3, V4 and V4e members of the Freescale Controller Continuum. By combining...	FREESCALE	7.2	<a href="#">Buy Now</a> <a href="#">Evaluation</a>
CodeWarrior Development Studio for ColdFire Architectures: Linux® Editions (Classic IDE) v2.5 CodeWarrior Development Studio for ColdFire Architectures Linux Application Edition and Linux Platform Edition v2.5 are all-inclusive tool suites designed to accelerate embedded Linux® application development for ColdFire processors.	FREESCALE	2.5	<a href="#">Buy Now</a> <a href="#">Evaluation</a>
CodeWarrior Development Studio for HCS12(X) Microcontrollers (Classic IDE) v5.1 CodeWarrior Development Studio for Freescale HCS12(X) v5.1 Microcontrollers enables engineers to build and deploy HCS12 or HCS12XXGATE systems quickly and easily. This tool suite provides the capabilities required by every engineer in the...	FREESCALE	5.1	<a href="#">Buy Now</a> <a href="#">Evaluation</a>
CodeWarrior Development Studio for QorIQ LS series for ARM v7 ISA v10.0.4 CodeWarrior Development Studio for QorIQ LS series featuring ARMv7 ISA is a development software tool created by Freescale based on the award-winning CodeWarrior IDE technology. This software is one of the first software tools both used and developed...	FREESCALE	10.0.4	<a href="#">Buy Now</a> <a href="#">Evaluation</a>
CodeWarrior for MCUs (Eclipse IDE) - ColdFire, 56800/E DSC, Kinetis, Freescale 56xx, RS08/S08, S12Z v10.6 Freescale's CodeWarrior for MCU's v10.6 integrates the development tools for the ColdFire, ColdFire+, DSC, Kinetis, Qorivva, RS08, S08 and S12Z architectures into a single product based on the Eclipse open development platform. Eclipse offers an...	FREESCALE	10.6	<a href="#">Buy Now</a> <a href="#">Evaluation</a>

## c. Installing CW 10.6

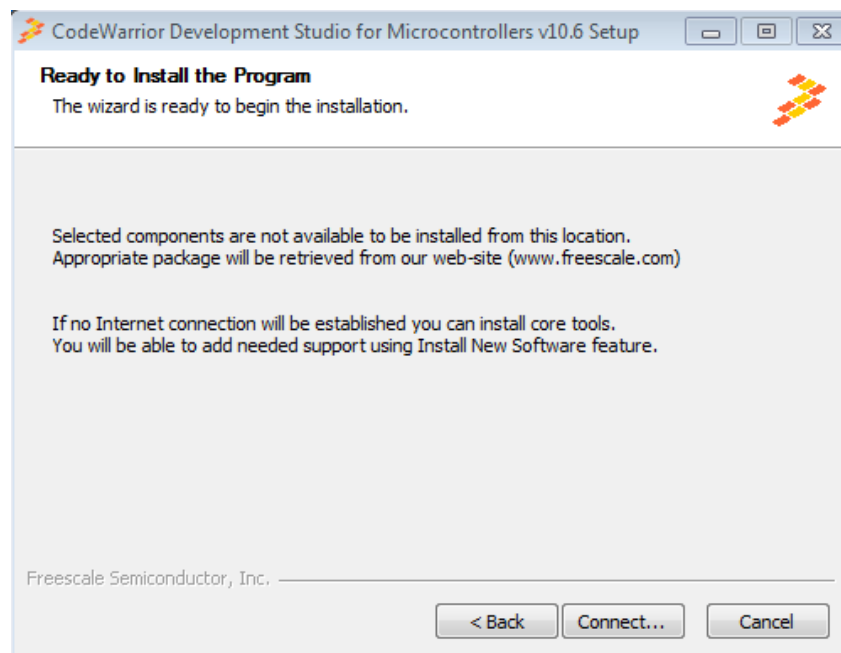
Once downloaded the application can be executed.



After having accepted the terms of the license agreement the following window appears. For TPMS applications, the only necessary components to be installed are **S08/RS08** components. However more components can be installed for further applications.



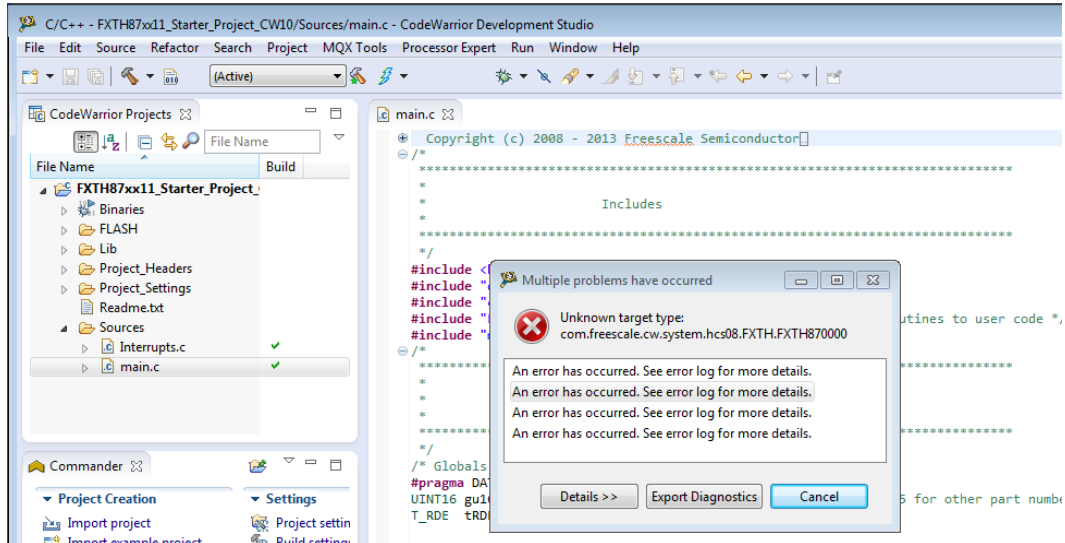
Then click *Connect...*



Once the installation is complete CW 10.6 for MCUs can be used. However, in order to be able to use the IDE for TPMS applications, it is necessary to install some updates (c.f. to next section).

## 2. Installing the necessary updates for TPMS applications

If a TPMS project is opened with CW 10.6 and if the updates for TPMS applications have not been installed, the following error window will appear.

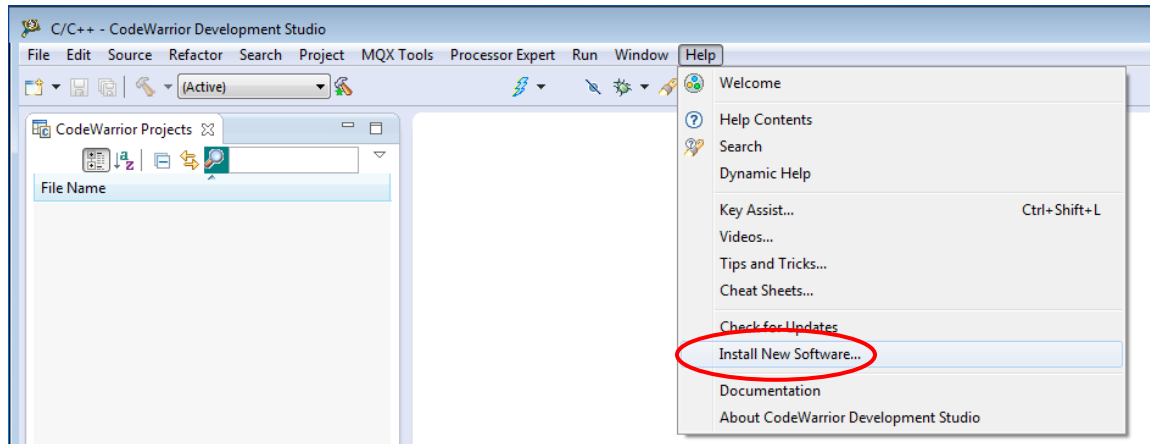


To prevent this error from occurring, a general update needs to be installed. This update can be downloaded from the website. Go to the following link (need to sign in or register):  
<https://freescale.flexnetoperations.com/control/frse/download?agree=Accept&element=5901381>

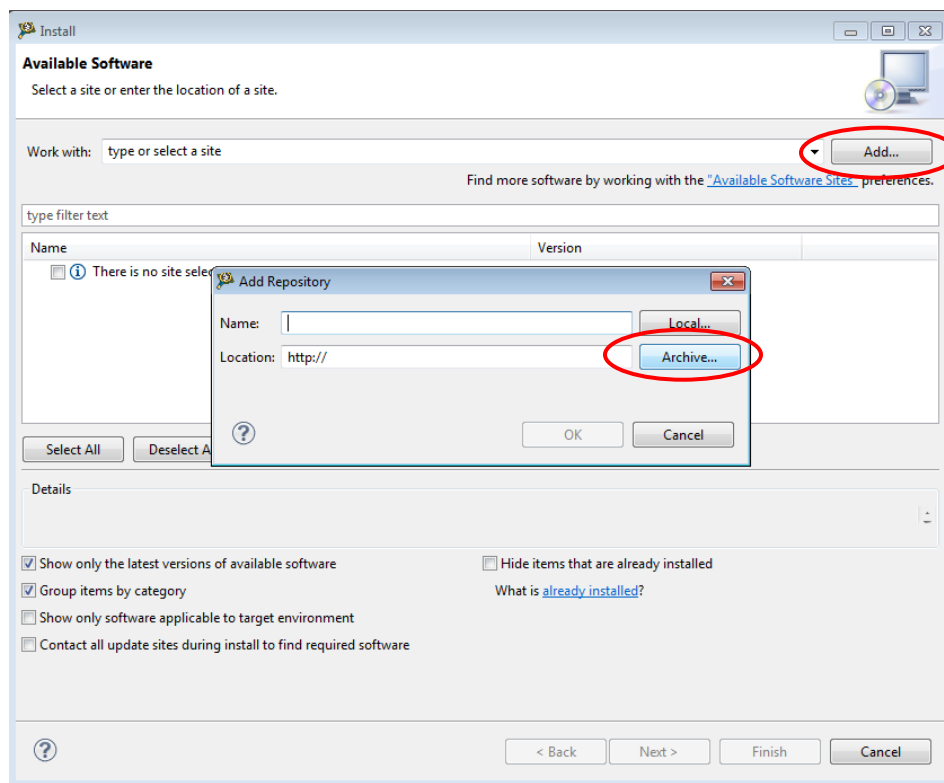
Download the **CW MCU v10.6 General Update 3.0.0** zip file. Do **not** unzip it.

File Description	File Size	File Name
+ Installer: CodeWarrior for Microcontrollers (Windows Hosted, Eclipse based) v10.6.4 Offline.exe	1.5 GB	CodeWarrior for Microcontrollers (Windows Hosted, Eclipse based) v10.6.4 Offline.exe
+ Installer: CodeWarrior for Microcontrollers (Windows Hosted, Eclipse based) v10.6.4 Online	509 MB	CodeWarrior for Microcontrollers (Windows Hosted, Eclipse based) v10.6.4 Online.exe
+ Installer: CodeWarrior for Microcontrollers (Windows Hosted, Eclipse based) v10.6 Online	432.6 MB	CodeWarrior for Microcontrollers (Windows Hosted, Eclipse based) v10.6 Online.exe
+ Installer: CodeWarrior for Microcontrollers (Windows Hosted, Eclipse based) v10.6 Offline	1.4 GB	CodeWarrior for Microcontrollers (Windows Hosted, Eclipse based) v10.6 Offline.exe
+ General Update: CodeWarrior for MCU v10.6 General Update 3.0.0	923.3 MB	CodeWarrior for MCU v10.6 General Update 3.0.0.zip
+ General Update: CW_MCU_10-6_Update_2.0.0	790.9 MB	CW_MCU_10-6_Update_2.0.0.zip
+ General Update: CW MCU v10.6 General Update v1.0.0.zip	693.6 MB	CW MCU v10.6 General Update v1.0.0.zip.zip
+ Service Pack: CW MCU v10.6 MC1323x Service Pack v1.0.0	394.9 KB	CW MCU v10.6 MC1323x Service Pack v1.0.0.zip
+ Service Pack: CW MCU v10.6 S12ZVC Service Pack v1.0.1	7.5 MB	CW MCU v10.6 S12ZVC Service Pack v1.0.1.zip
+ Service Pack: CW MCU v10.6 S12ZVHL Service Pack v1.0.2	5.1 MB	CW MCU v10.6 S12ZVHL Service Pack v1.0.2.zip
+ Service Pack: CW MCU v10.6 Wireless Charging MWCT1xxx Service Pack v1.0.1	4.4 MB	CW MCU v10.6 Wireless Charging MWCT1xxx Service Pack v1.0.1.zip
+ Service Pack: CodeWarrior for MCU v10.6 S12ZVM Service Pack 1.0.0	4.9 MB	CodeWarrior for MCU v10.6 S12ZVM Service Pack 1.0.0.zip

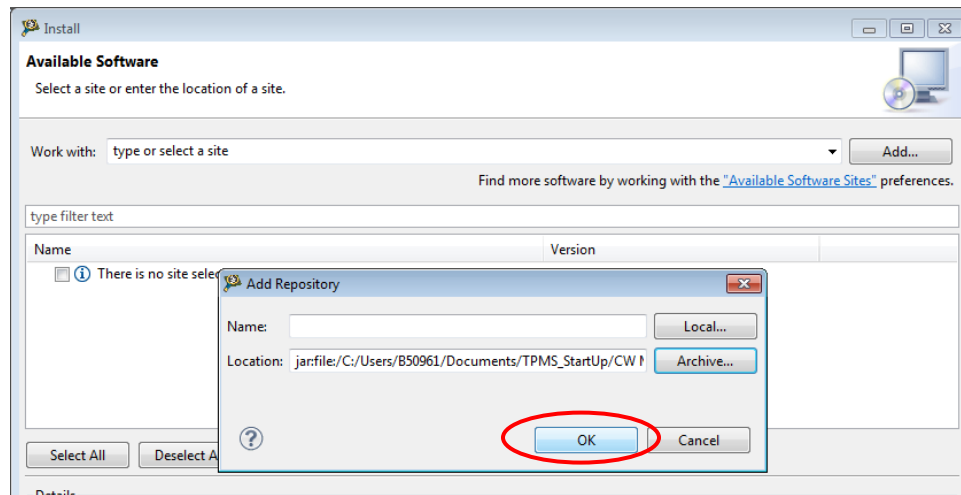
To install this file start CW v10.6, open the *Help* window and click on *Install New Software*.



Then click on *Add* and then on *Archive*.

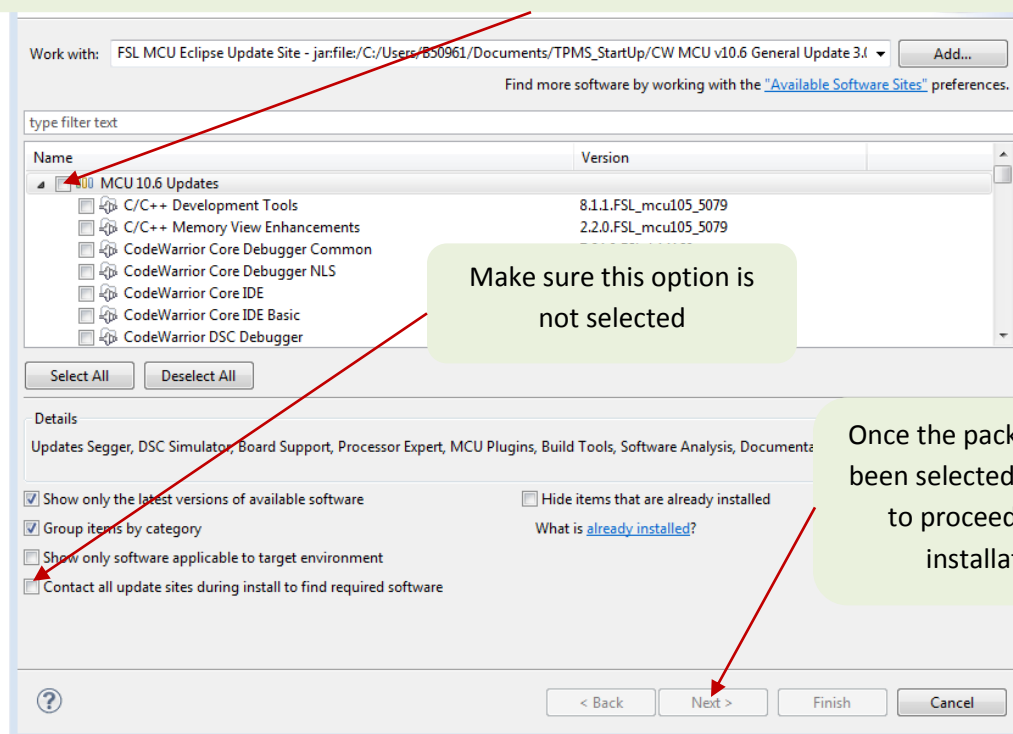


Select your zip file and click **OK**.



At this point the user can choose which packages of the general update have to be installed (either specific packages or the whole update if all the components related to the update have been installed). **If updates that correspond to components that have not been installed are selected then errors will occur.** In what follows the list of the necessary packages for TPMS applications is given.

Tick the box to install the complete update – only if **all the components** have been installed. **Otherwise just tick the necessary packages** (the ones related to the installed components). See below for the list of these packages for TPMS.





**List of the necessary packages to be installed for TPMS applications:**

If all the components related to the general update have not been installed then the whole update cannot be installed. The specific packages need to be selected. To install the minimum number of packages for TPMS applications (only the packages related to TPMS) follow the procedure below. Otherwise install everything (if all the components have been installed) and once the installation is complete restart CW 10.6. After that TPMS projects can be used with CW 10.6.

*Procedure to install the packages specific to TPMS applications:*

The necessary Service Pack for TPMS is the package **MCU v10.6 S08 Service Pack for HCS08 FXTH870000** included in the general update 3.0. However, this package alone cannot be installed. In order to install this package other additional packages are necessary as well (packages that contain information to install the S08 Service Pack). The list of all these packages is given below.

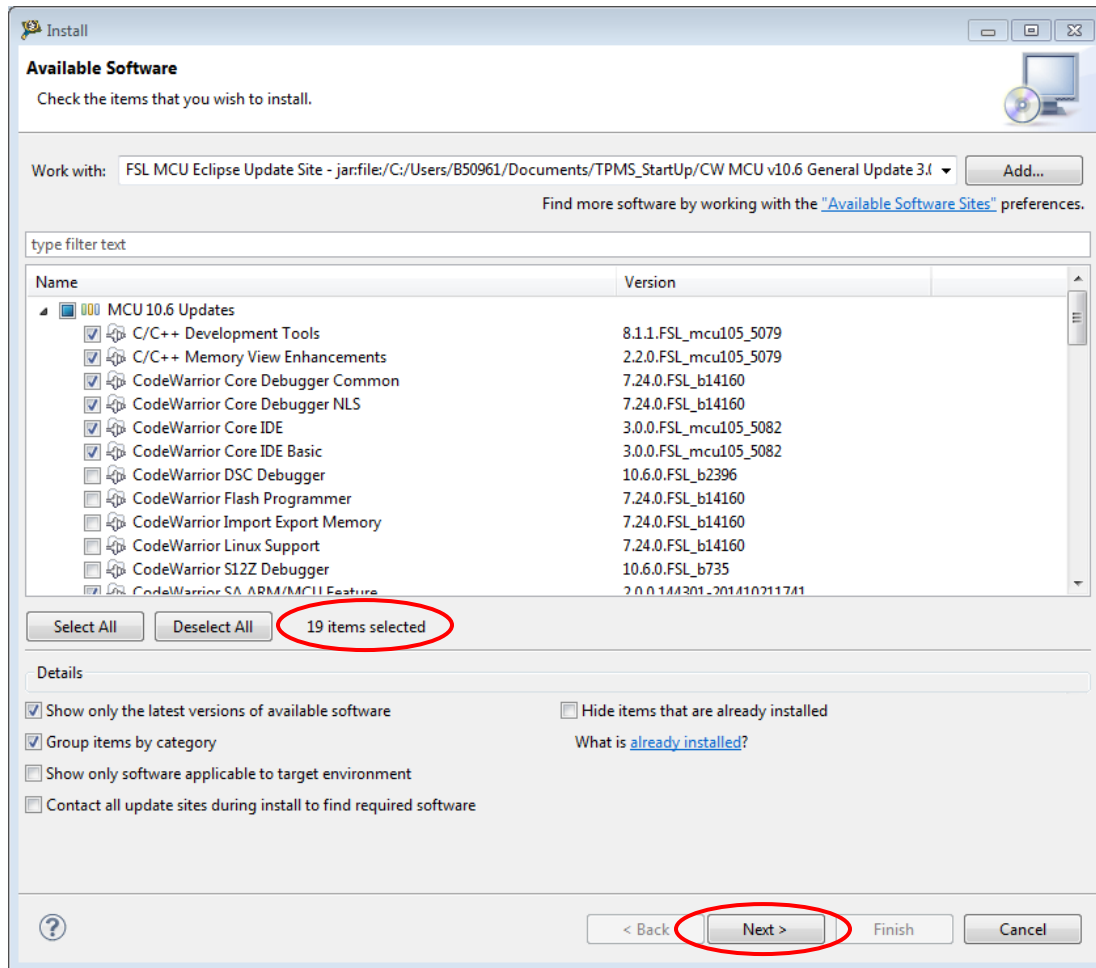
Name		Version	Id
MCU v10.6 S08 Service Pack for HCS08 FXTH870000		1.0.5	com.freescale.mcu10_6.HCS08_FXTH8700...
S08/RS08 Wizard, Debugger		1.0.5	com.freescale.hcs.architecture.feature.gro...
MCU v10.6 Core update		3.0.0	com.freescale.mcu10_6.update.feature.gr...
C/C++ Development Tools		8.1.1.FSL_mcu105_5...	org.eclipse.cdt.feature.group
C/C++ Memory View Enhancements		2.2.0.FSL_mcu105_5...	org.eclipse.cdt.debug.ui.memory.feature....
CodeWarrior Core Debugger Common		7.24.0.FSL_b14160	com.freescale.coretech.debugger.commo...
CodeWarrior Core Debugger NLS		7.24.0.FSL_b14160	com.freescale.coretech.debugger.nls.feat...
CodeWarrior Core IDE		3.0.0.FSL_mcu105_5...	com.freescale.core.ide.feature.group
CodeWarrior Core IDE Basic		3.0.0.FSL_mcu105_5...	com.freescale.core.ide.basic.feature.group
CodeWarrior SA ARM/MCU Feature		2.0.0.144301-20141...	com.freescale.sa.arm.feature.group
CodeWarrior SA ARM/MCU NLS Feature		2.0.0.144301-20141...	com.freescale.sa.arm.nls.feature.group
CodeWarrior SA Core Feature		2.0.0.144301-20141...	com.freescale.sa.feature.group
CodeWarrior SA Core NLS Feature		2.0.0.144301-20141...	com.freescale.sa.nls.feature.group
Common Documentation		5.0.0	com.freescale.doc.feature.group
Component Development Environment		1.6.3.CW_b1441-0004	com.freescale.processorexpert.cde.featur...
DDR Configuration		1.0.0.b1429-0610	com.freescale.processorexpert.feature.ddr...
MCU Wizard and Tools Plugins		10.6.0.FSL_b06012	com.freescale.mcu.feature.group
PEMicro LCD Feature		1.4.18	com.pemicro.lcd.feature.feature.group
Processor Expert for MCU		10.6.3.RT6_b1446-0...	com.freescale.processorexpert.feature.mc...

18  
necessary  
additional  
packages to  
install

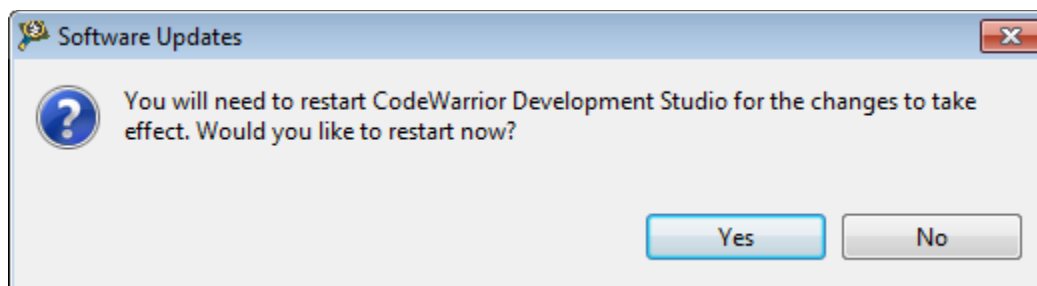
Package we want to install

So for TPMS there are **at least 19** packages to install: the **MCU v10.6 S08 Service Pack for HCS08 FXTH870000** plus the additional 18 packages listed above. These 19 packages must be selected (ticked) in the *Install* window.

Select the right ones, then click *Next*, accept the terms of the license agreement and start the installation of the update.



When the following window appears, click Yes.

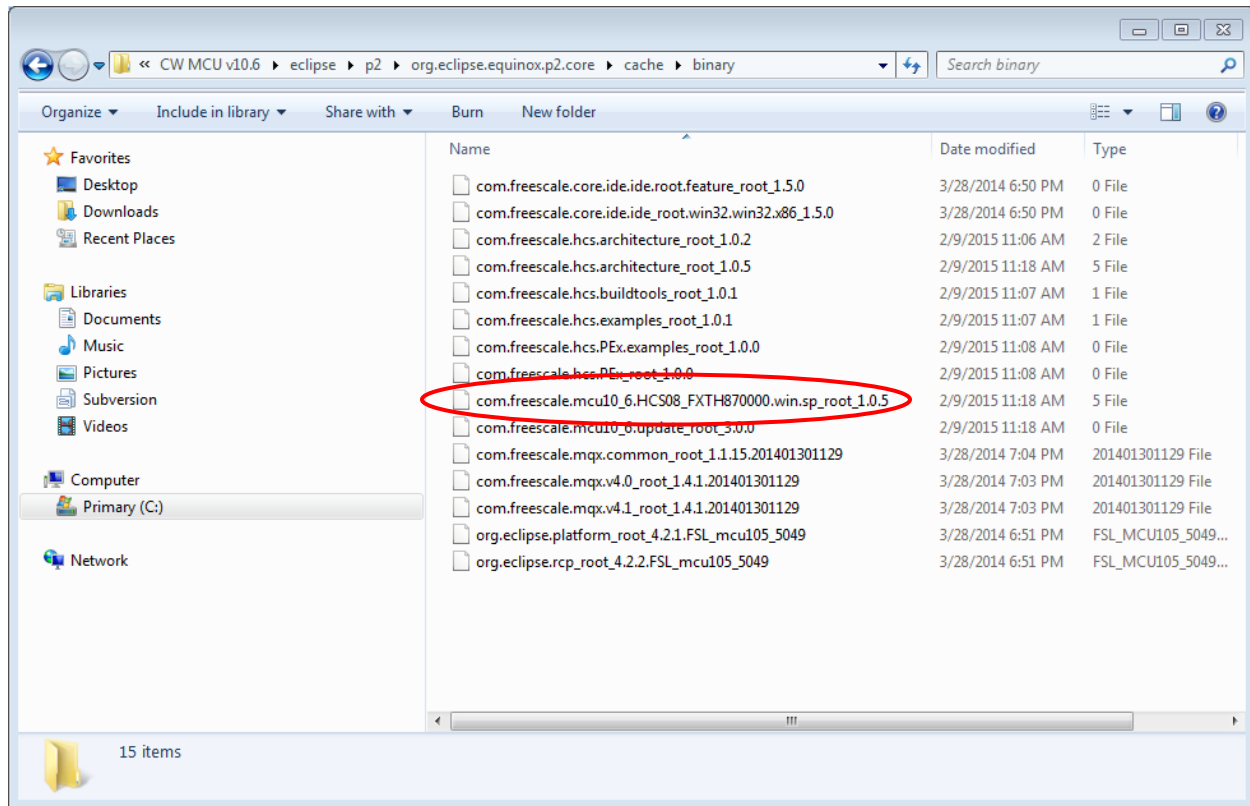


After that the installation is complete. TPMS projects can now be used with CW v10.6.

**Note 1:**

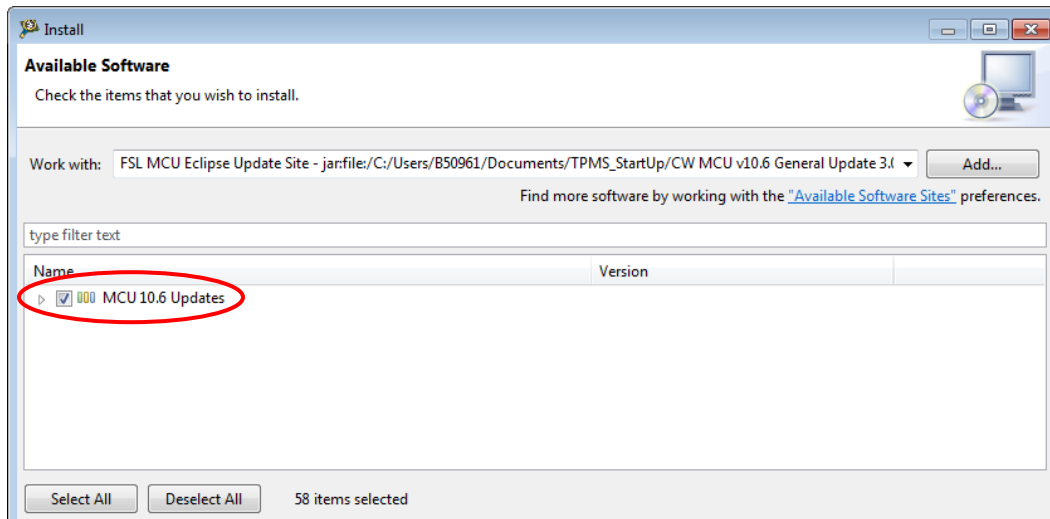
Once the installation of the update is complete the newly installed TPMS service pack can be seen in the following folder:

(CW Installation Path) > CW MCU v10.6 > eclipse > p2 > org.eclipse.equinox.p2.core > cache > binary

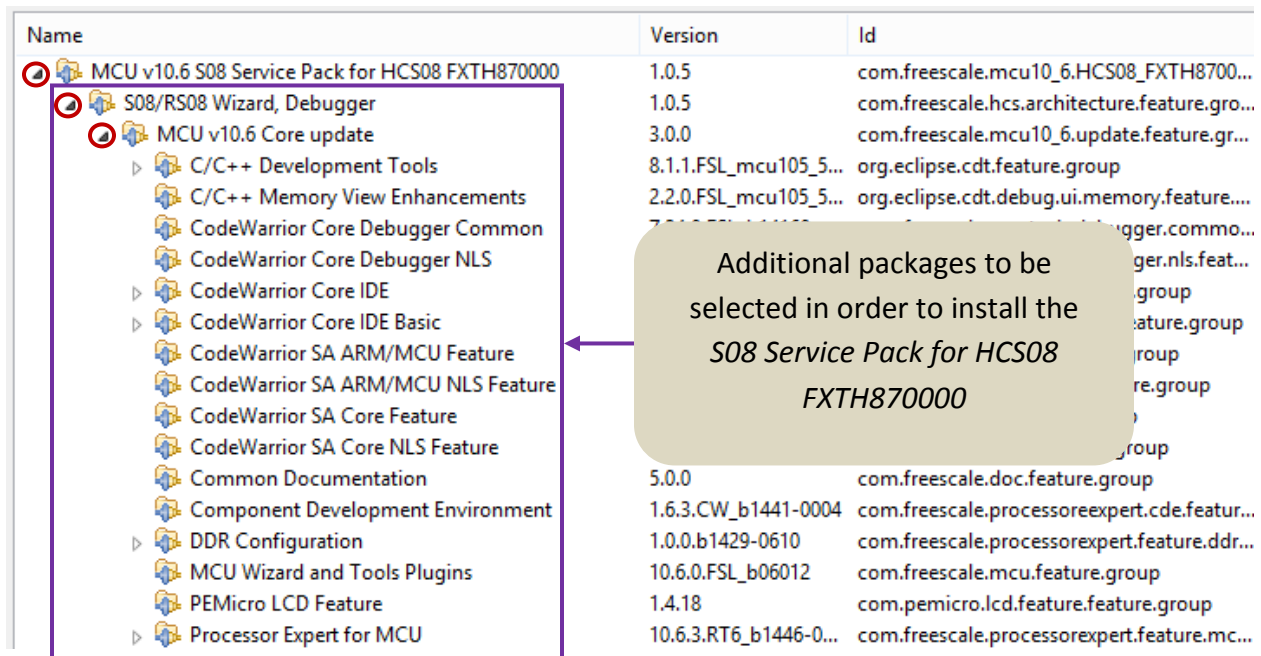
**Note 2 – General information about update installation:**

A general update contains several packages. In order to install a specific service pack (a specific package among all the other packages and not the whole update) it is often necessary to install additional packages because there are dependencies between them. There is a way to know the minimum list of the necessary complementary packages to be installed for a given package.

To see this list, first select all the packages of the update. Then click next.



On the next window the list of the packages appears. When clicking on the little arrow next to the name of the package the list of the dependencies is displayed. In this example it means that in order to install the S08 Service Pack it is necessary to install also all the other packages listed below.



Then go back to the previous window and select only the necessary packages. Then proceed to the installation.

### 3. Programming the Starter project

#### a. Downloading the project

A TPMS starter project can be found in the web site in: *Products > Sensors > Tire Pressure Monitoring Sensors > FXTH87*. This is the TPMS main page. To download the project, go to *Software & Tools*.

#### FXTH87: Freescale FXTH87 Tire Pressure Monitor Sensor Family ☆

Overview Documentation **Software & Tools** Buy / Parametrics Training & Support

Data Sheet Application Notes Buy Sample Export to Excel Expand All Sections

Hardware Development Tools (10) Expand All Sort by Modified Date

Printed Circuit Boards and Schematics-Printed Circuit Boards (10)

Software Development Tools (7) Expand All Sort by Modified Date

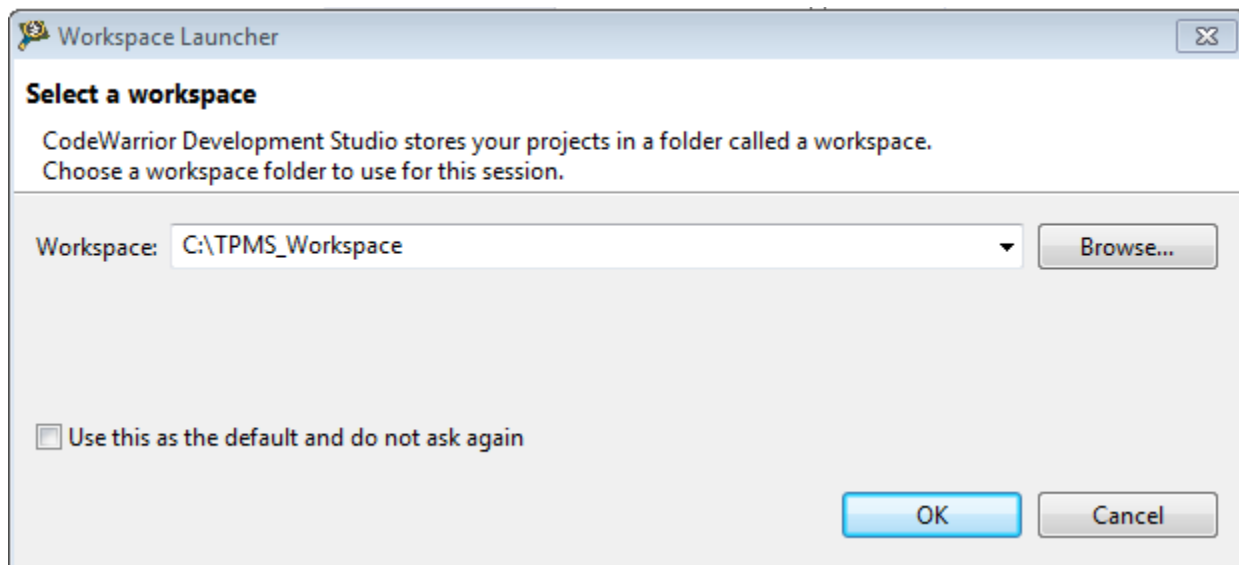
Lab and Test Software (7)

ID and Description	Vendor	Availability	Favorite
Configuring Tektronix AFG3102 Generator to send LF signals ⓘ : To be used with the FXTH87XXXX LF TRIGGERED RF TRANSMISSION CW10 project. It contains files and explanations to configure the Tektronix AFG3102 signal generator to send the LF frames that trigger the TPMS RF transmission. Size (K): 4 Format: zip Rev #: 0 Modified: 3/6/2015	FREESCALE	<a href="#">Download</a>	☆
FSL-SENSOR-GUI-R3-3-0-3: FSL Sensor GUI R3.3.0.3. Size (K): 168776 Format: zip Rev #: 3.3.0.3 Modified: 4/7/2015	FREESCALE	<a href="#">Download</a>	☆
<b>FXTH87xx11_STARTERPJ_CW10: FXTH87xx11 Starter Project CW10.</b> Size (K): 125 Format: zip Rev #: 0 Modified: 5/12/2014	FREESCALE	<a href="#">Download</a>	☆

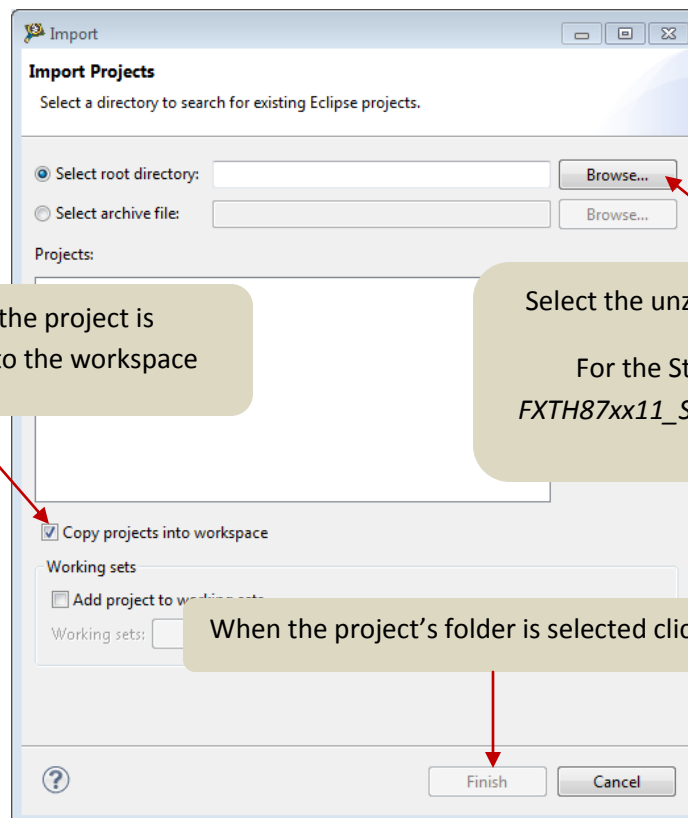
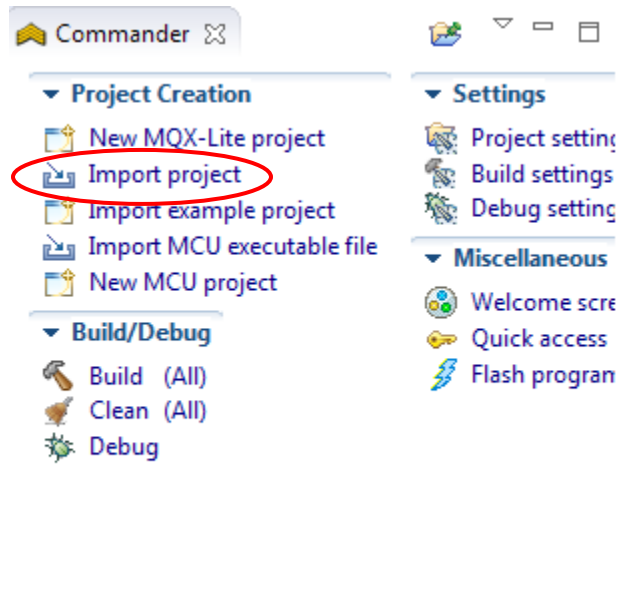
Download the project and unzip it.

#### b. Importing the project in CW 10.6

Start Code Warrior v10.6. Select the workspace i.e. the folder in which your project will be stored.



When the IDE is started click on *Import Project*.



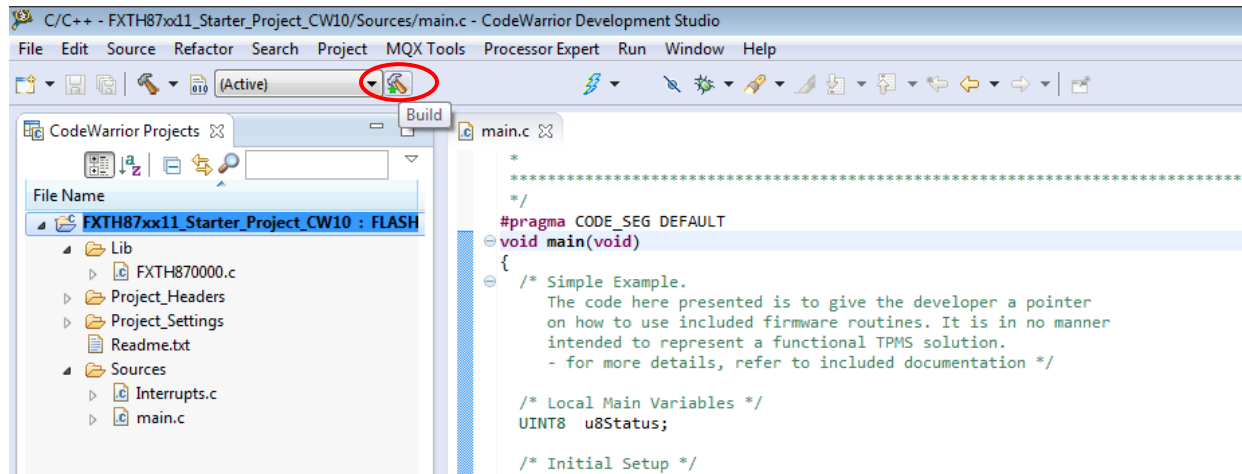
Tick the box so that the project is automatically copied into the workspace

Select the unzipped folder of the project.

For the Starter project select the *FXTH87xx11\_Starter\_Project\_CW10* folder

When the project's folder is selected click *Finish*

Once the project is opened, build it. It might be necessary to clean it before building it (right click on the project and select *Clean Project*).

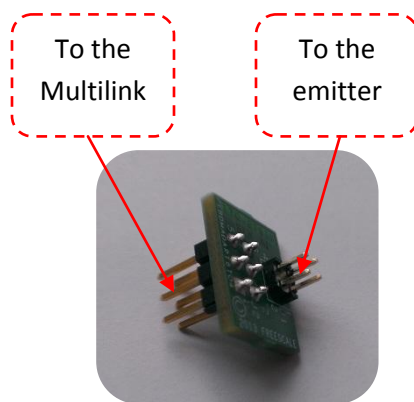


## c. Programming the device

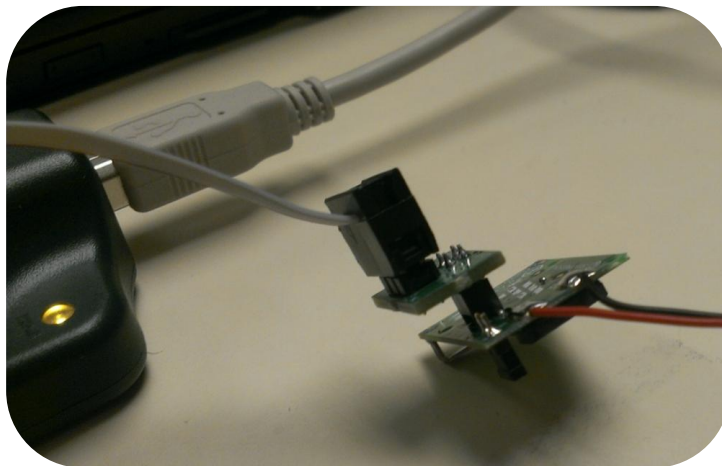
### i. Hardware set up

To program the TPMS emitter a P&E's USB Multilink Universal is required. For more information about this product visit [P&E Multilink](#) web page.

The Multilink connects to the TPMS emitter board via the connector board as shown below:

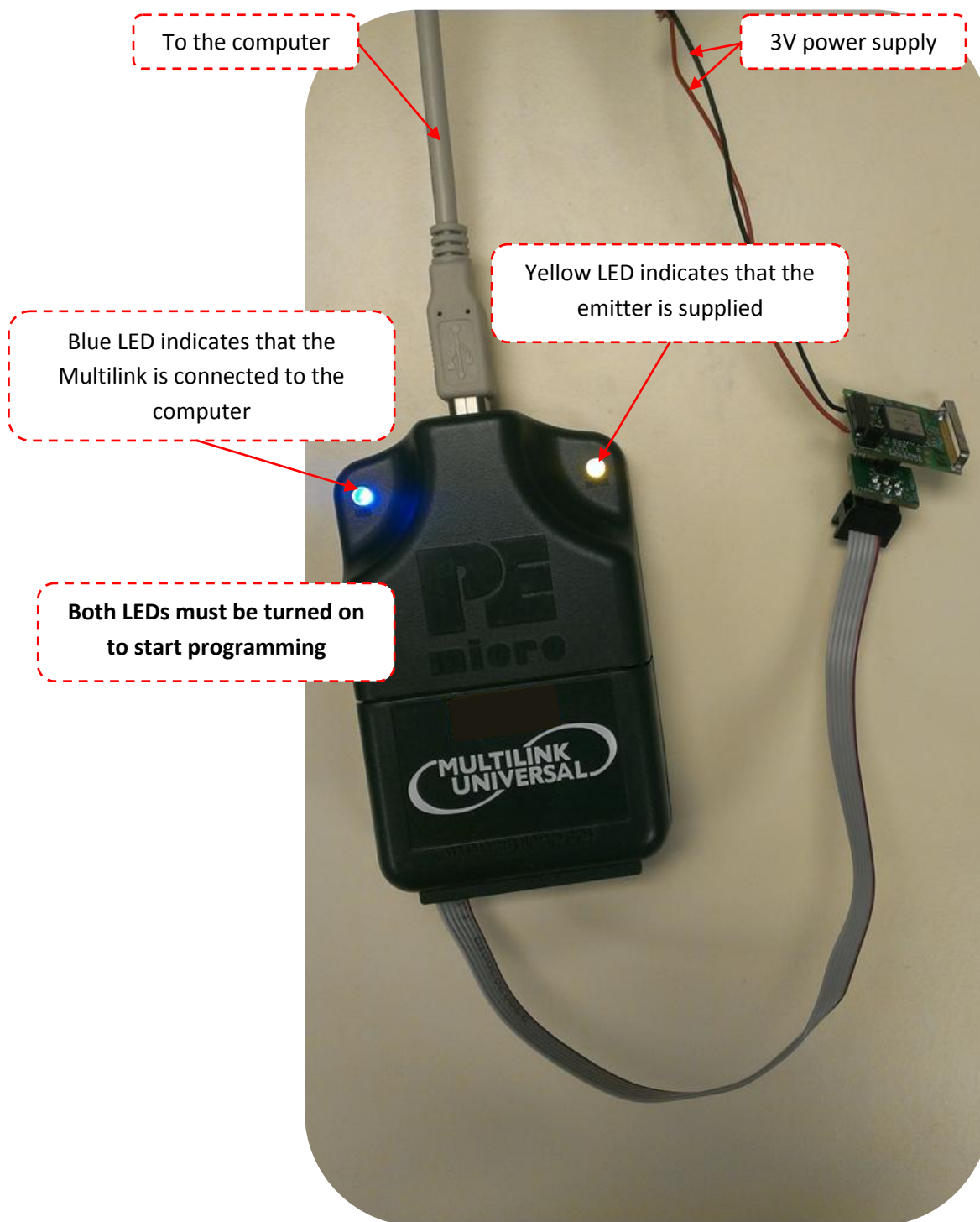


Connector board



Connection between the Multilink and the TPMS emitter

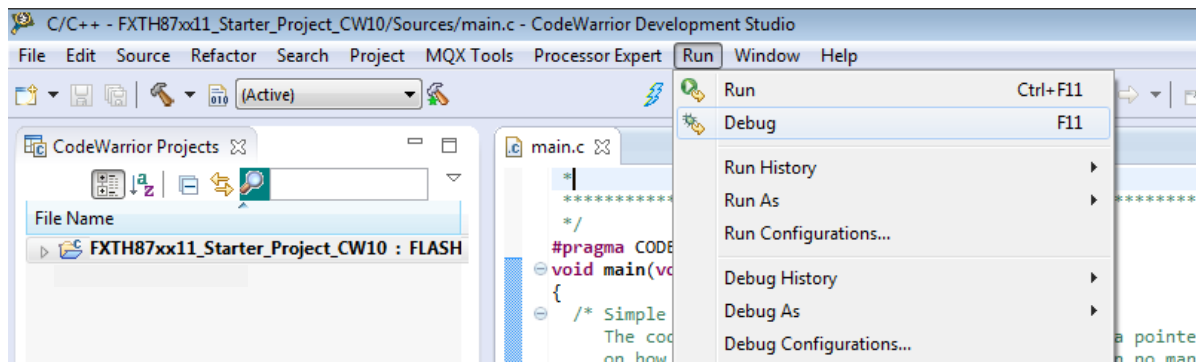






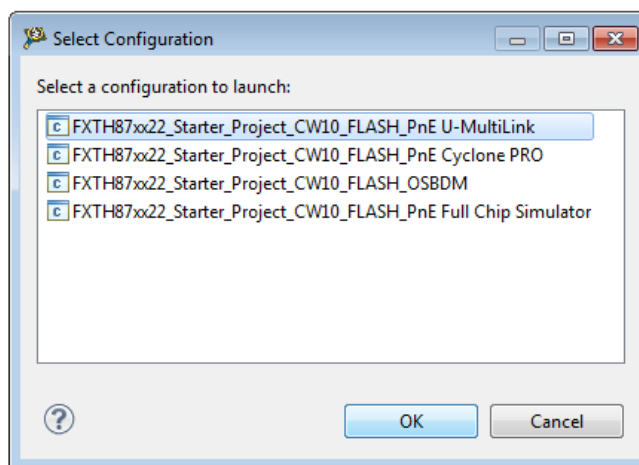
## ii. Debug Configuration

After having built the project go to *Run* and select *Debug*.



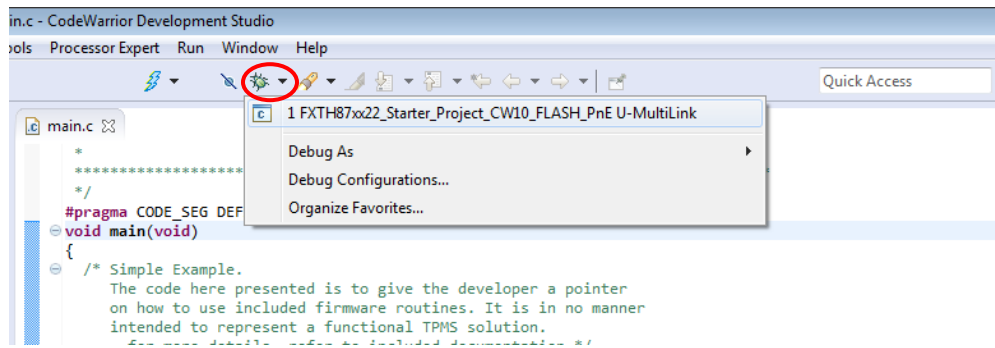
The following window should appear. Choose the right configuration and click *OK*. If the P&E micro Multilink Universal is used, select the *FLASH\_PnE U-Multilink* configuration.

If no configurations are available, see below *Adding or modifying a debug configuration*. If configurations are available but problems occur when entering the debugger, see the Troubleshooting part of this document (some settings may need to be (re)selected) or do the configurations again (see below).



### Note:

Once a configuration has been selected and used, it is directly available by clicking on the arrow next to the debug button.

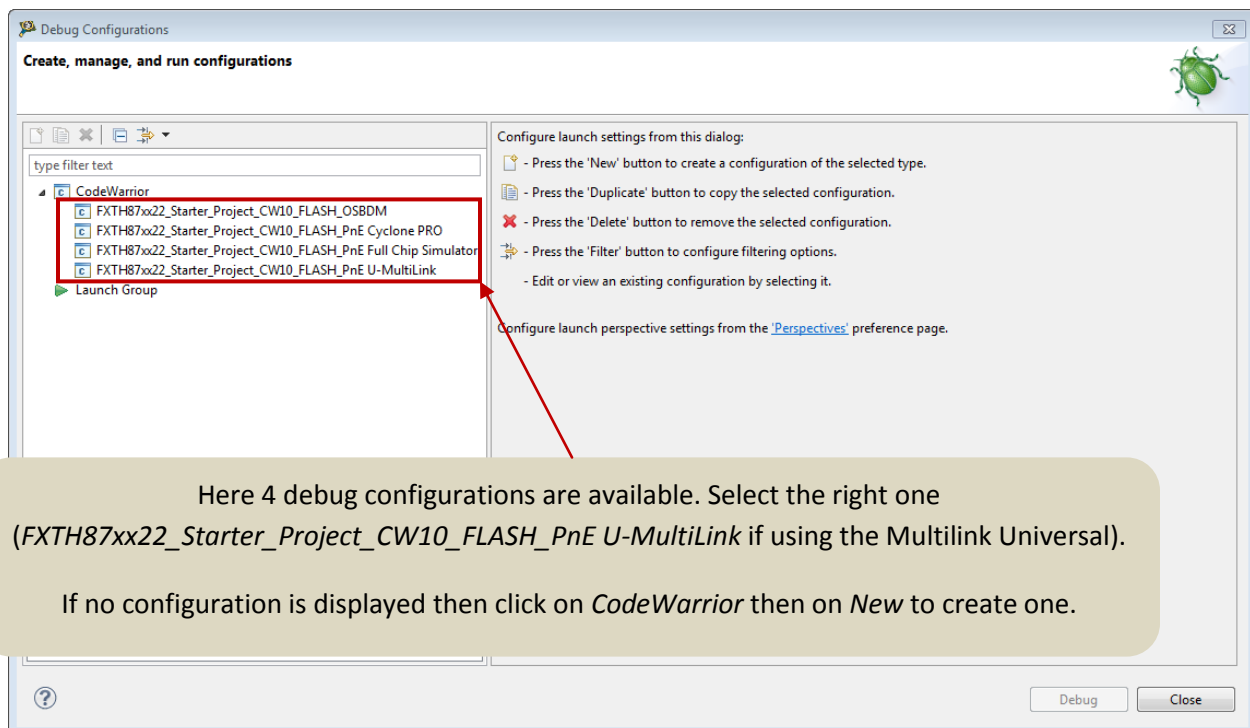


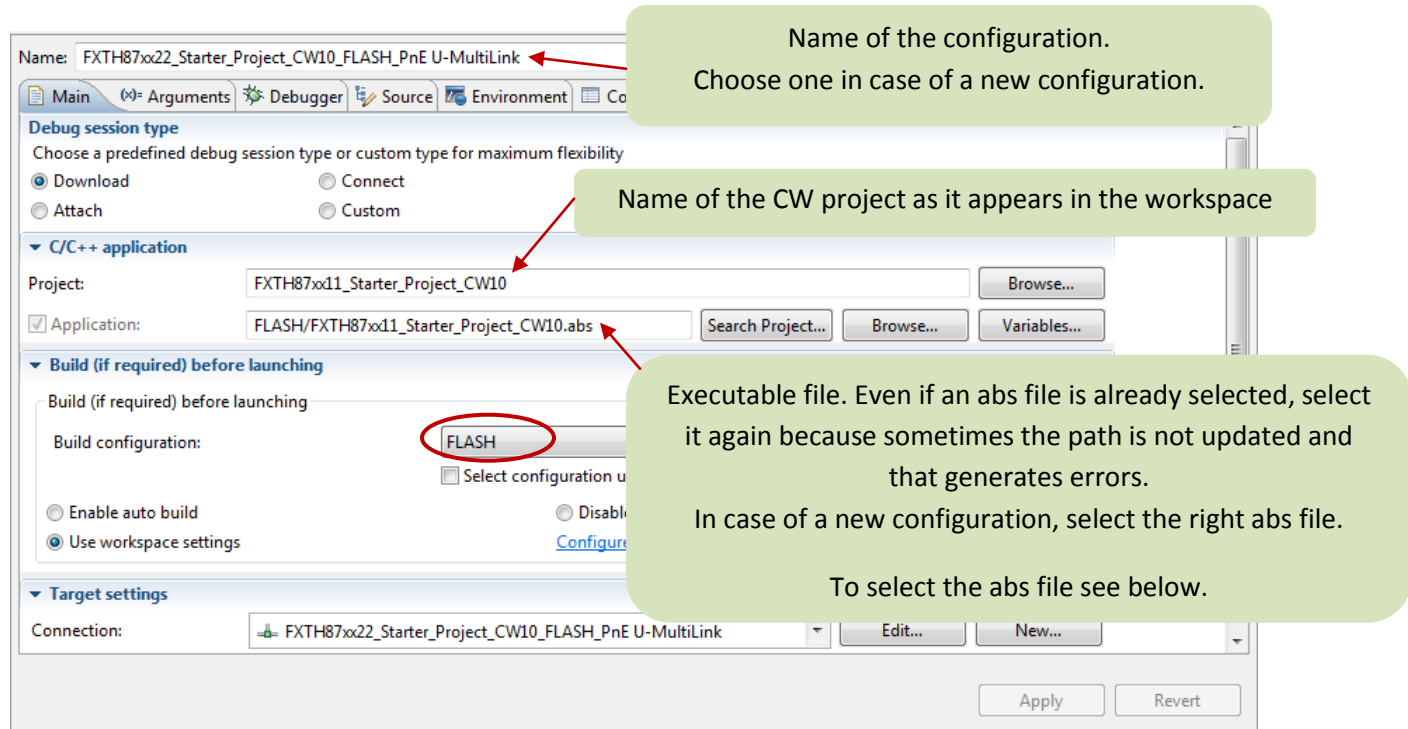
### Adding or modifying a debug configuration

Below is explained how to set or modify a debug configuration.

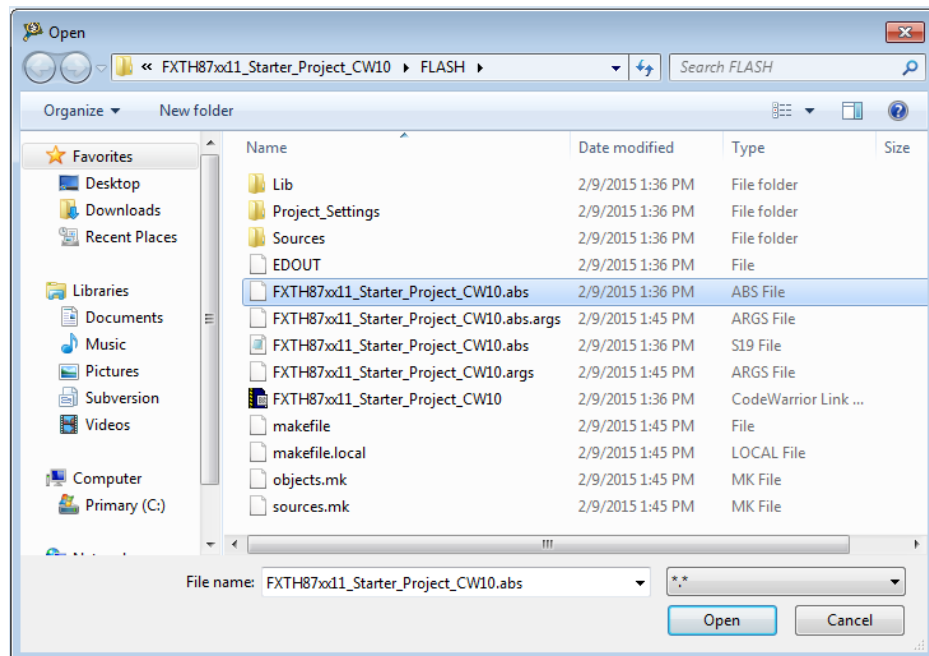
In the *Debug Configurations* window, the following parameters have to be chosen: the project executable file (.abs), the connection interface and the target type.

First open the *Debug Configurations* window by clicking on *Run > Debug Configurations*. This window can also be accessed through the project properties (right click on the project then click on *Properties > Run/Debug Settings*).

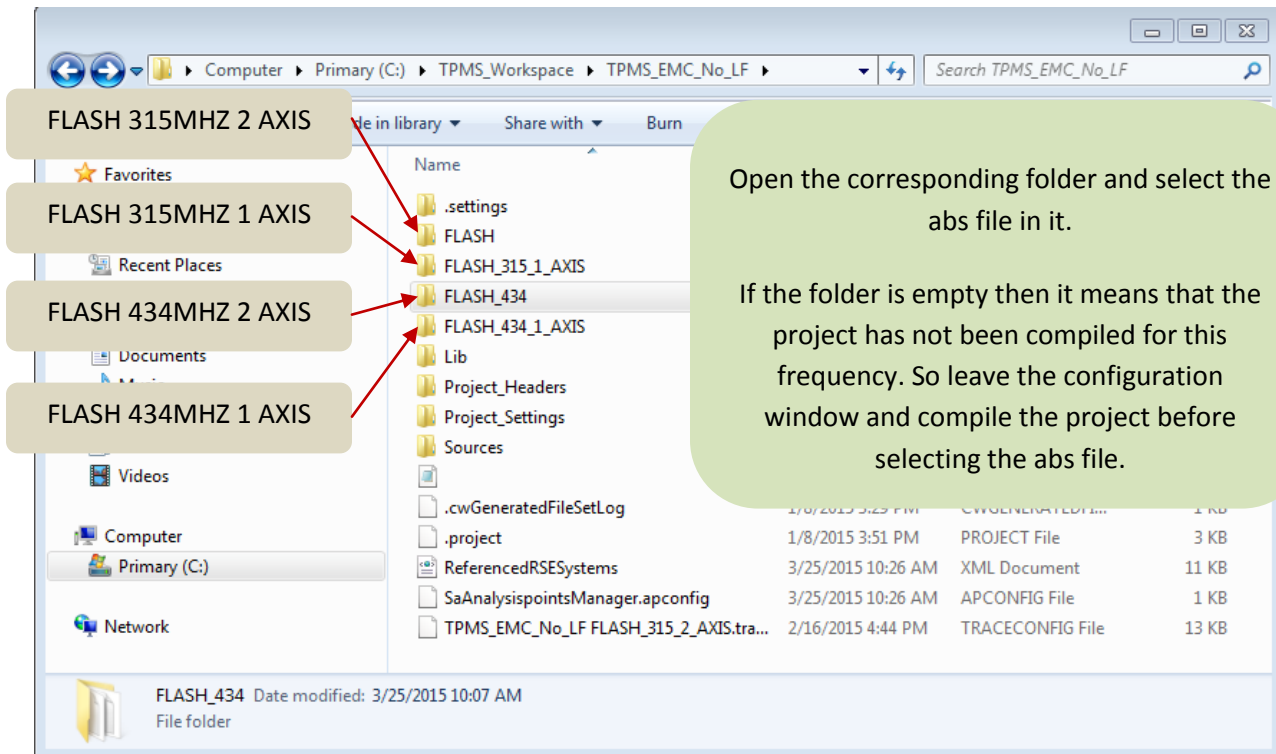




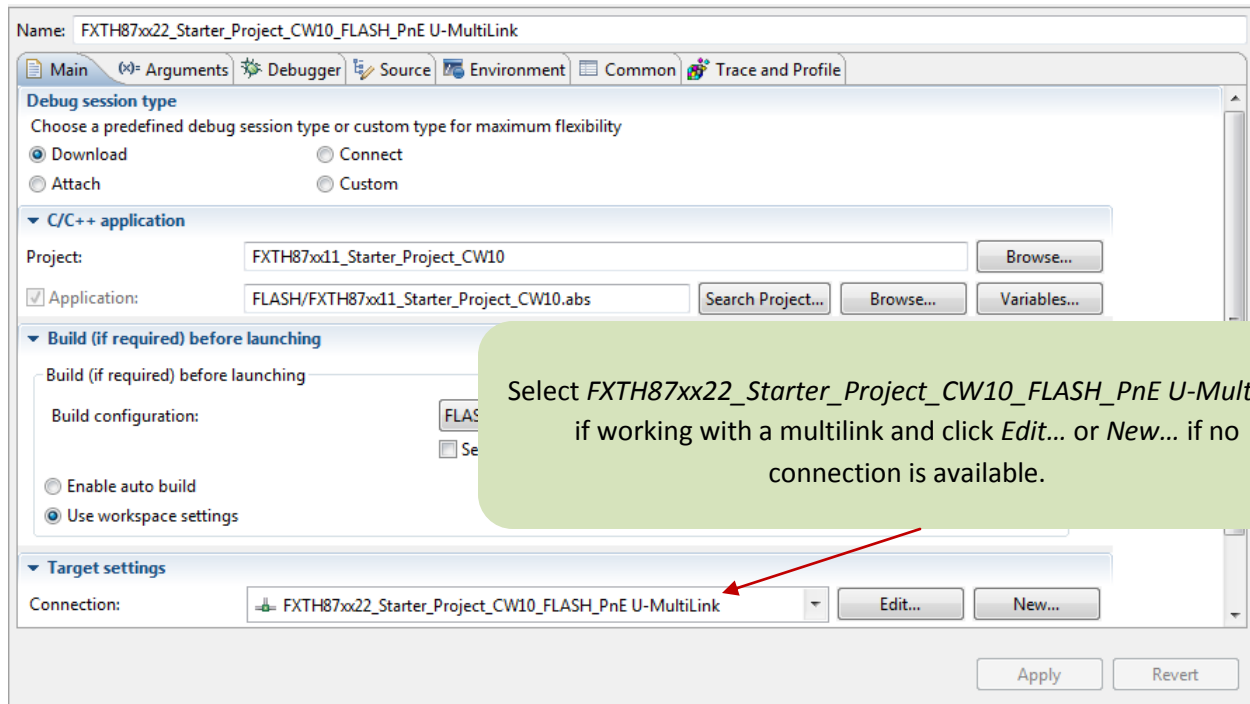
To select the right abs file click on *Browse...* Then go to the FLASH folder (it is in the project's folder – if there are several FLASH folders see below) and choose the abs file (be careful: do not select the s19 file that has the same name).



**Note:** in some projects several abs files are available, depending on frequency chosen during the compilation (315MHz 2 axis, 434MHz 2 axis...). In this case, select the abs file corresponding to the chosen frequency.

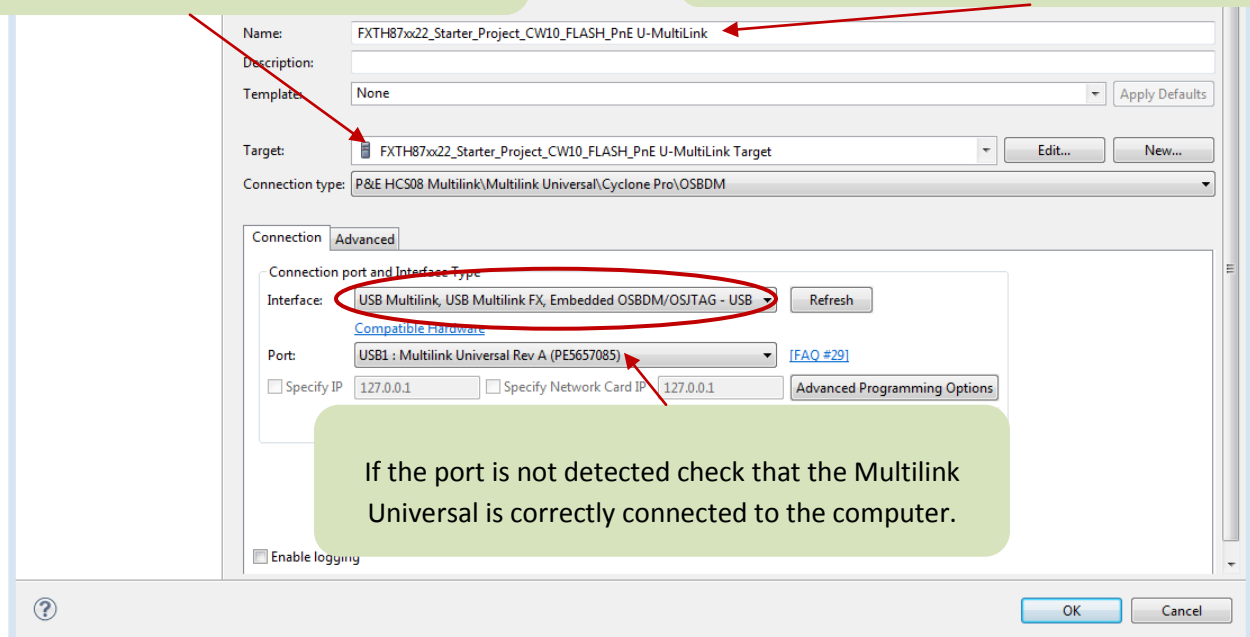


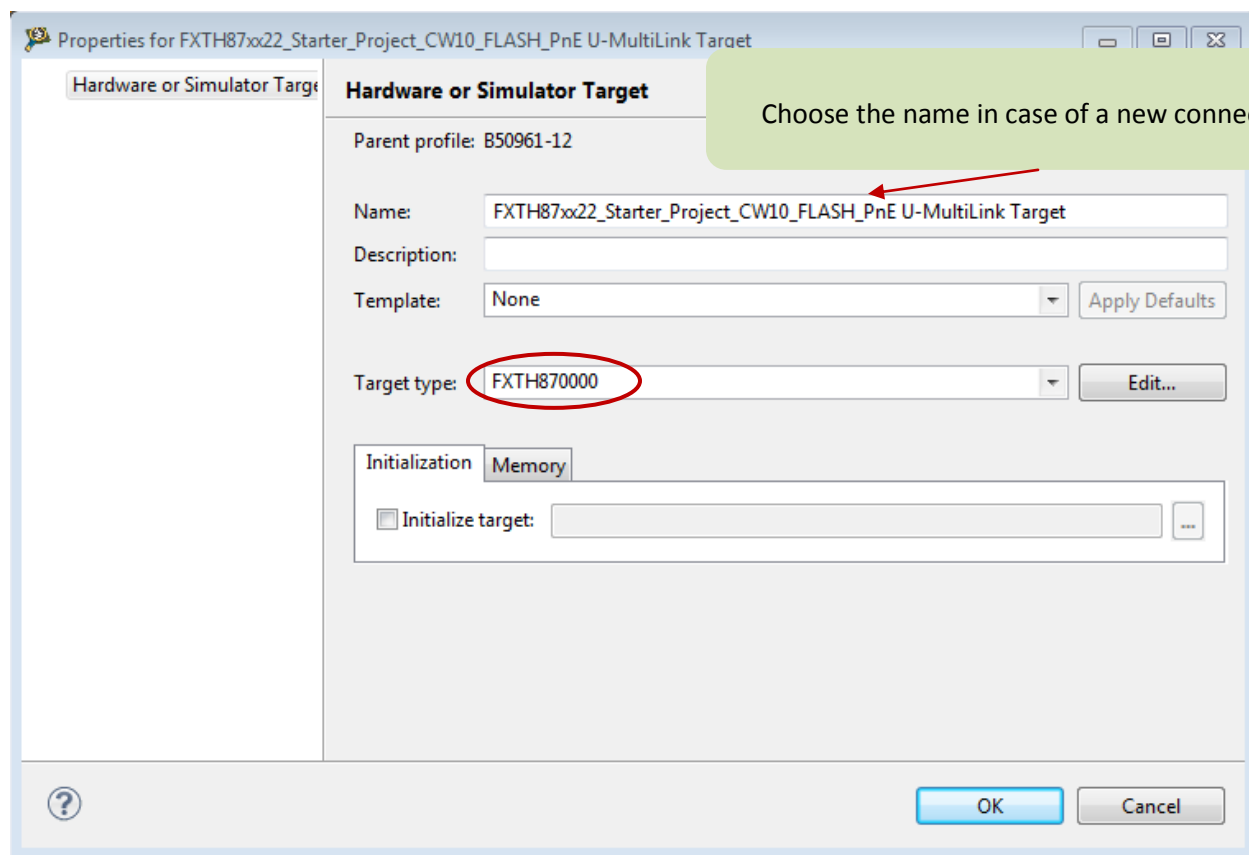
Once the executable file has been selected, choose the connection.



Edit the target to verify that the right one has been selected or click on *New* in case of a new connection

Choose the name in case of a new connection





With that the debug environment configuration is complete.  
The debug configuration can now be selected to program the device.

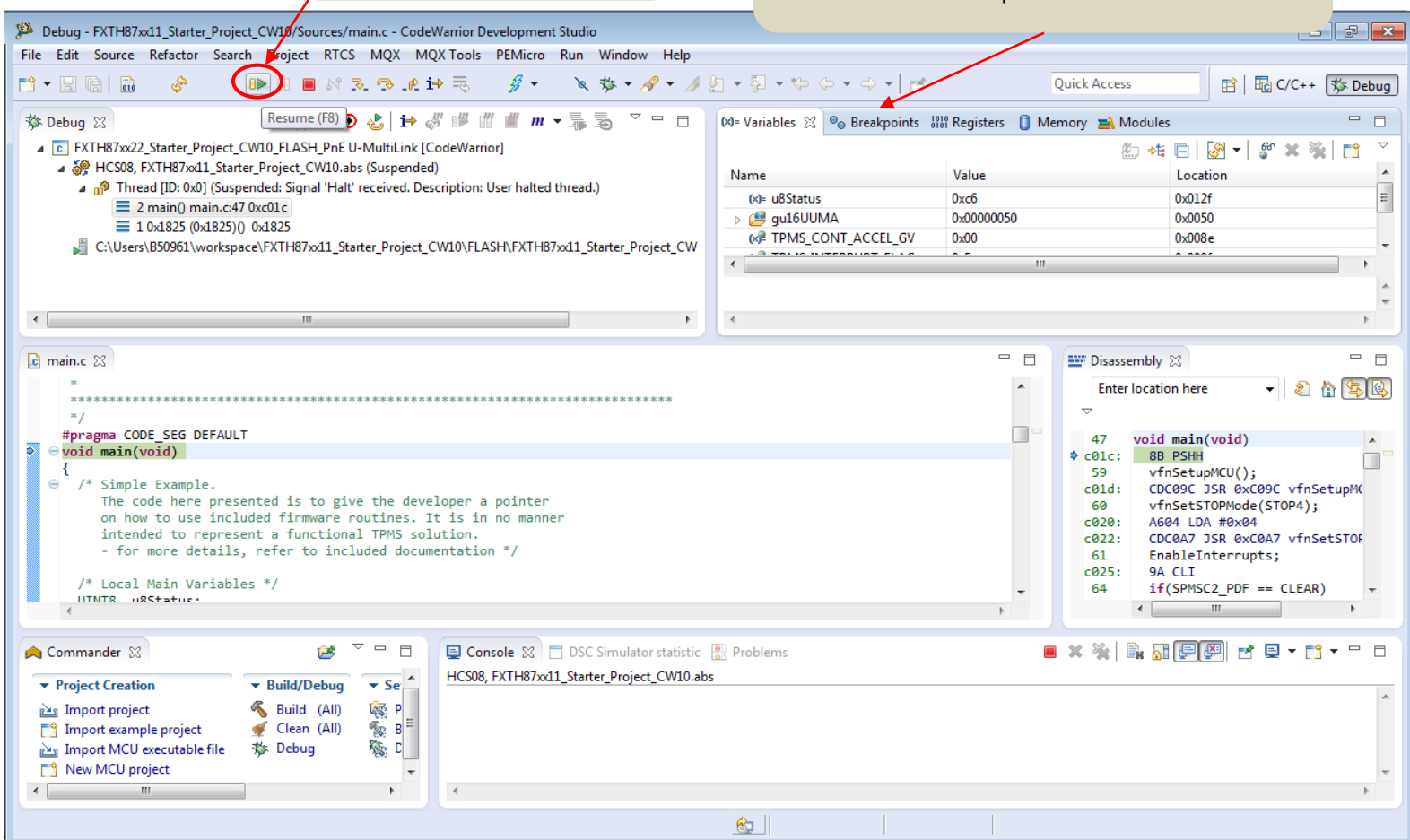
## d. Running the program

When the debugger has been launched the following window is displayed. In order to run the program and leave the debugger click on *Run* then on *Terminate* and leave the *Debug* panel. Then reset the TPMS emitter. No frames will be sent if the module has not been reseted.

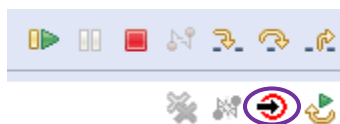
In order to work in debug mode do the following:

Click here to run the program  
**after** having reseted the  
device (see below)

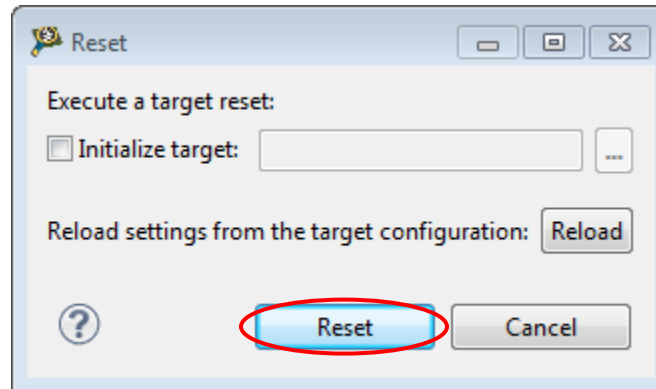
In this window the breakpoints can be managed.  
Look at the Important note concerning the  
breakpoints below.



Before being used the device needs to be reseted. It is necessary to reset it each time it has been reprogrammed. For that click on *Reset*.



Then click *Reset* again.

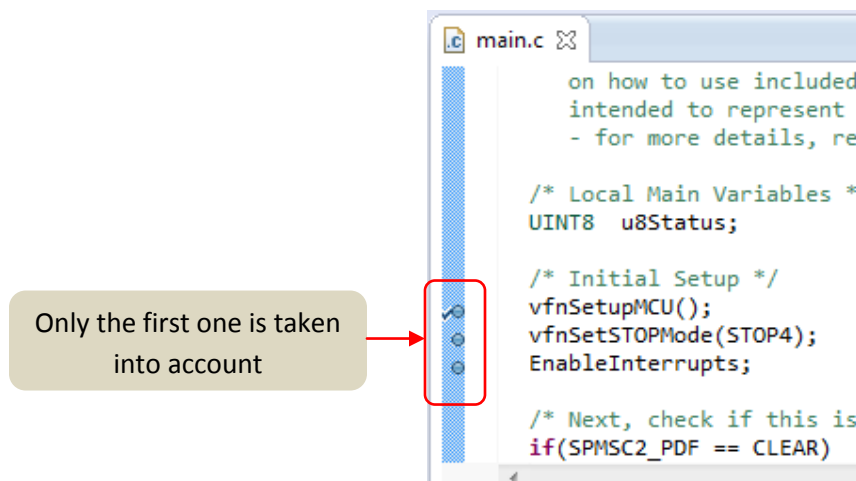


It is only after this reset that the device can be used. Do not run the program before having reseted the device.

#### Important note – breakpoints:

With TPMS devices it can be used only **ONE** breakpoint at a time. By default one breakpoint is set by the debugger at the beginning of the main. That is why the program is stopped at the beginning of the main after the debugger has been launched.

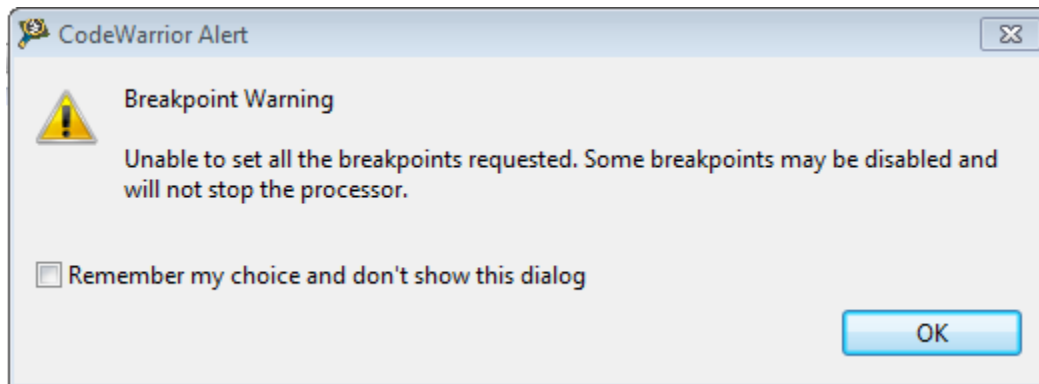
Once the program has been stopped at the beginning of the main, another (and only one) breakpoint at a time can be set elsewhere. If several breakpoints are set, only the first one will be taken into account.





If the user wants to have several breakpoints **it is not possible to have them at the same time**. The only possible thing to do is to set one breakpoint, then when the program stops on this breakpoint the user can delete it (by double clicking on it) and set a new one at another line. Then when the program reaches this other breakpoint the user can delete it, set a new one...

If a breakpoint is set somewhere **before** entering the debugger, the following warning will appear.

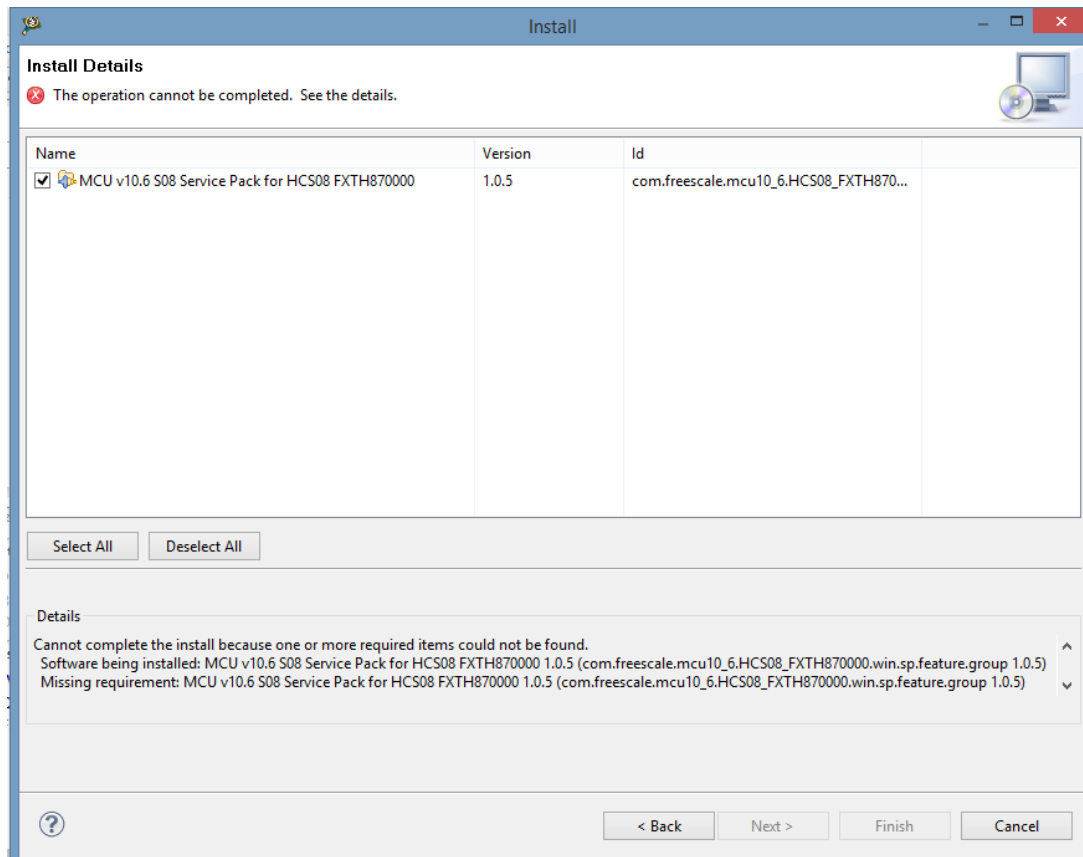


In this case the program will stop at the breakpoint set by the user and not at the one set by default (at the beginning of the main). Again, if several breakpoints have been set, only the first one will be taken into account.

## 4. Troubleshooting

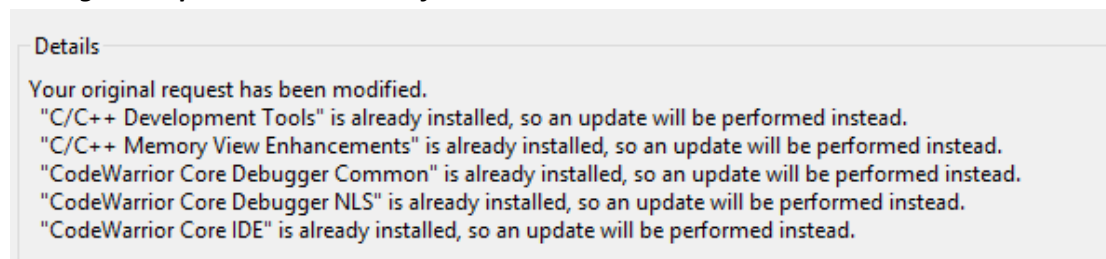
### a. During the installation of the update

⇒ ***The operation cannot be completed: one or more required items could not be found***



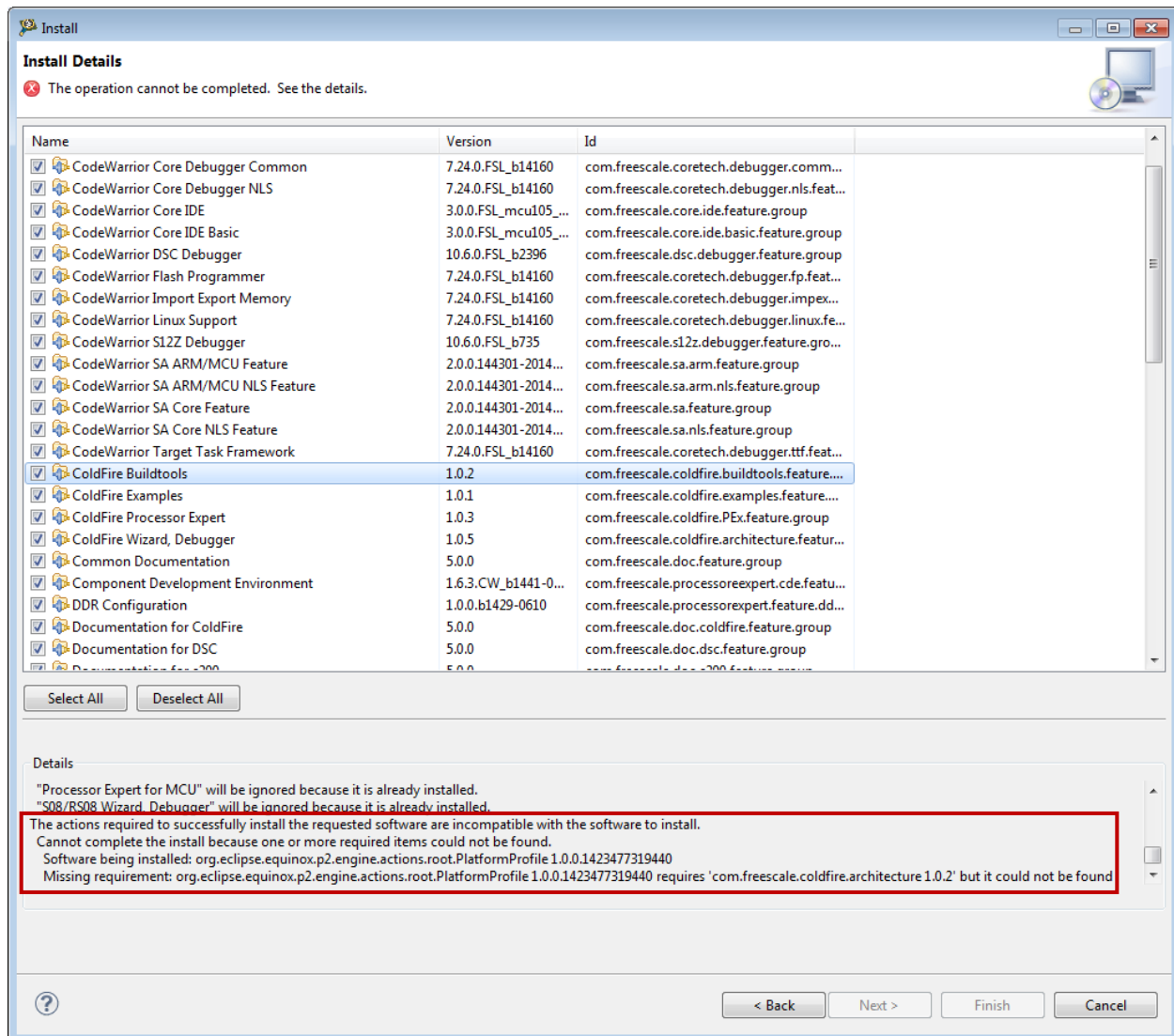
This error means that some necessary complementary packages have not been selected. So go back to the previous window and select additional packages. To know the list of the necessary packages, c.f. to the end of Part 2: Note 2 – General information about update installation.

⇒ ***Your original request has been modified***



This is not a problem, so continue the installation.

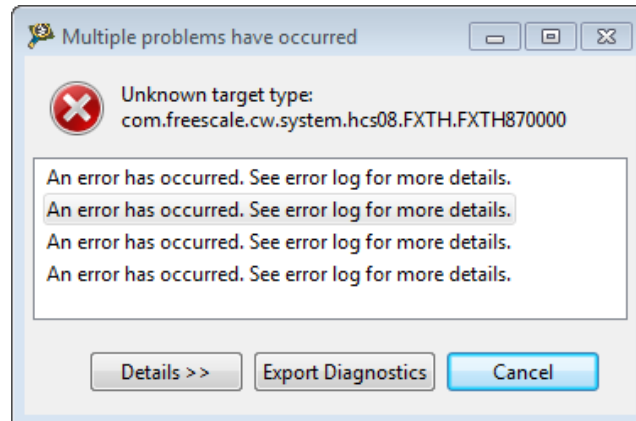
⇒ **Cannot complete the install because one or more required items could not be found**



This means that some packages related to components that have not been installed have been selected. In this example, updates for coldfire components have been selected whereas the coldfire component has not been installed (it has not been selected during CW 10.6 installation).

## b. When opening a TPMS project with CW 10.6

⇒ **Unknown target type**



The necessary Service Pack has not been installed.

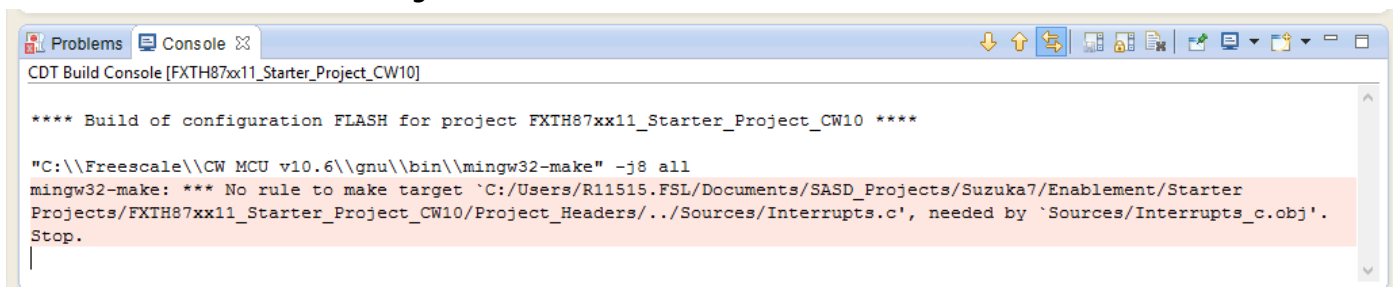
Verify the content of the following folder:

(CW Installation Path) > CW MCU v10.6 > eclipse > p2 > org.eclipse.equinox.p2.core > cache > binary

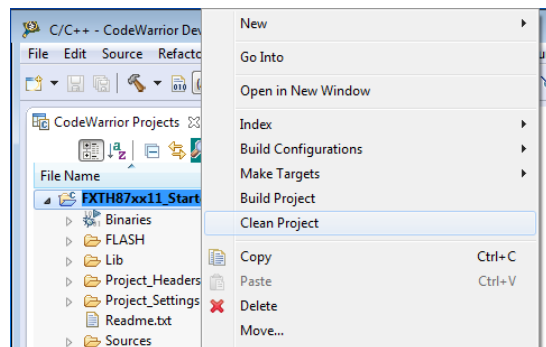
The *com.freescale.mcu10\_6.HCS08\_FXTH870000.win.sp\_root\_1.0* file should be here. If it is, close the project, close CW 10.6 and then reopen everything. If the file is not in the folder follow the whole procedure explained in Part 2 of this document.

## c. When building a TPMS project with CW 10.6

⇒ **No rule to make target**

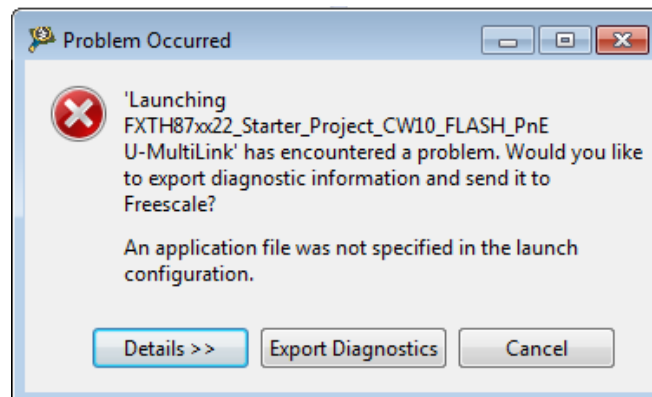


The project needs to be cleaned before being built. For that, right click on the project and select *Clean Project*. Then try to build it again.

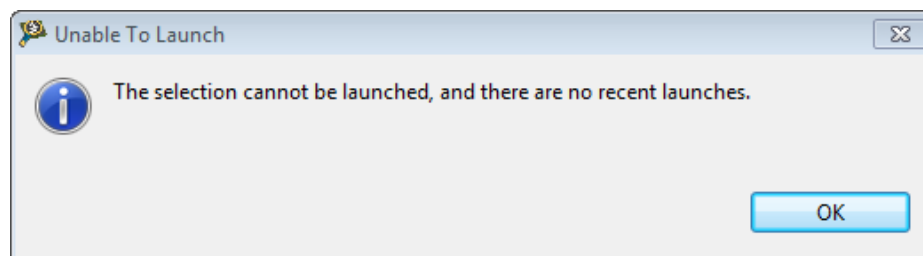


#### d. When entering the debugger

⇒ **Problem Occurred or Unable To Launch**

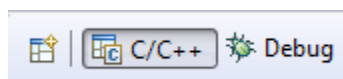


Or

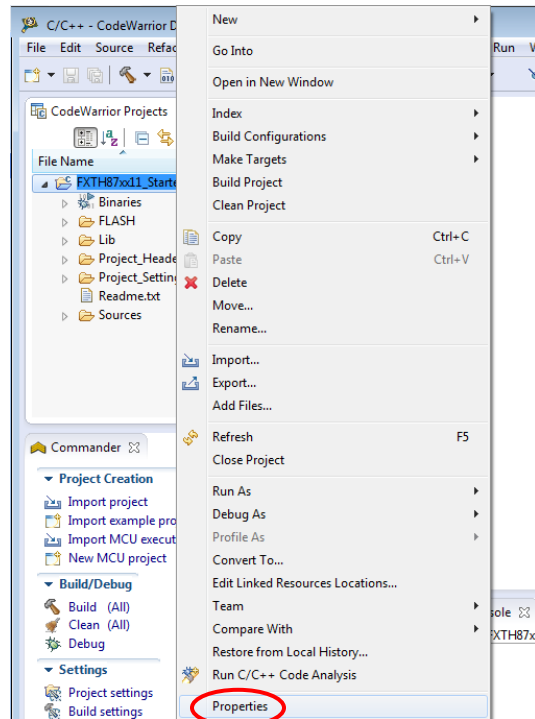


Before programming the device for the first time some Debug Configurations may need to be (re)selected. To do that the project needs to be built first.

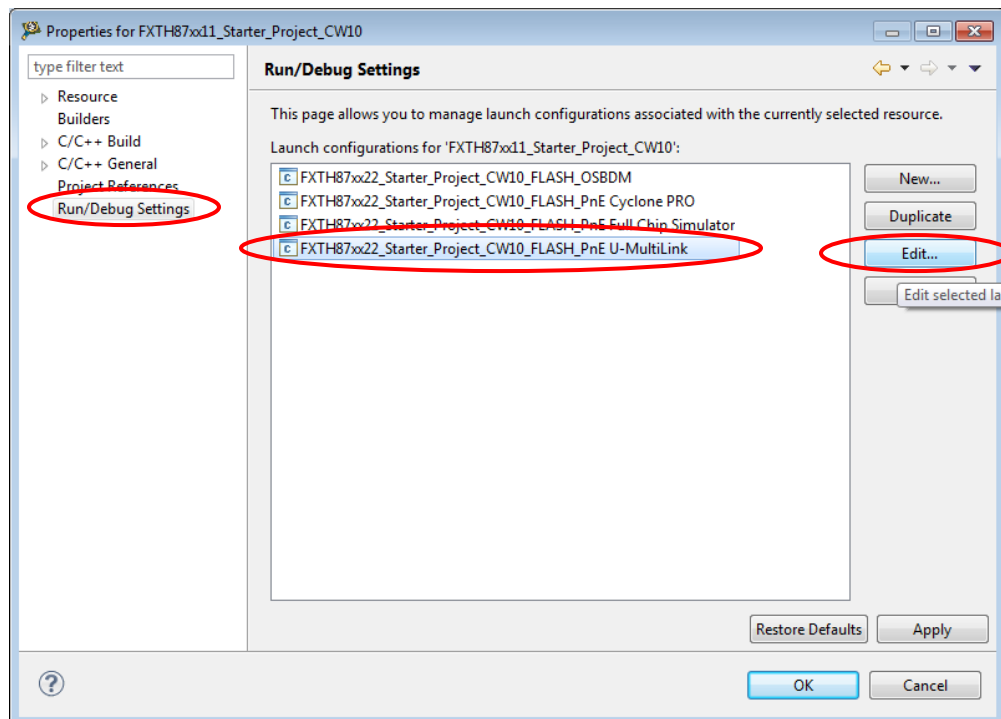
Leave the debugger if it has been launched. To leave the debugger click on C/C++ at the top right part of the CW window.



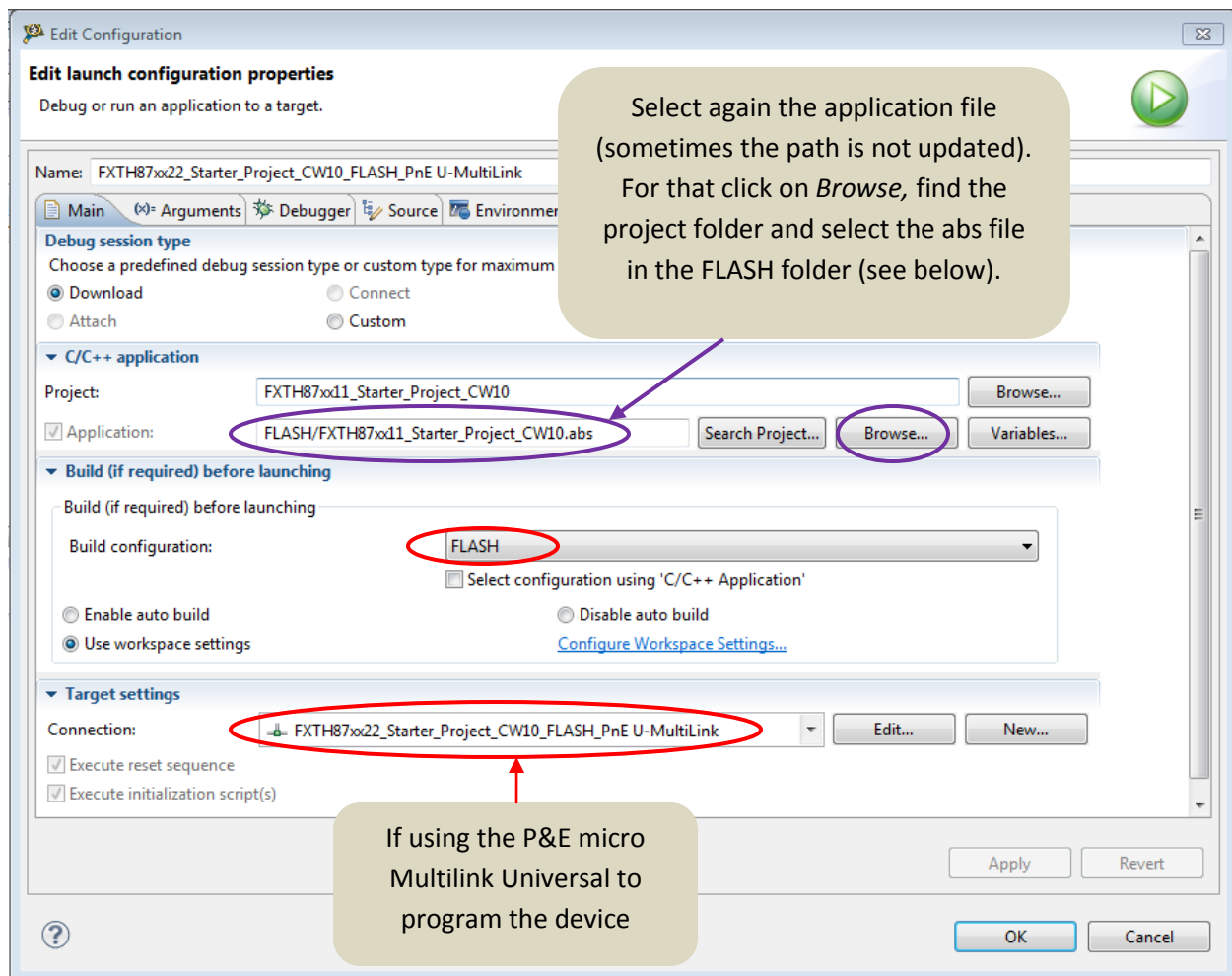
Then build again the project if necessary, right click on the project and select *Properties*.



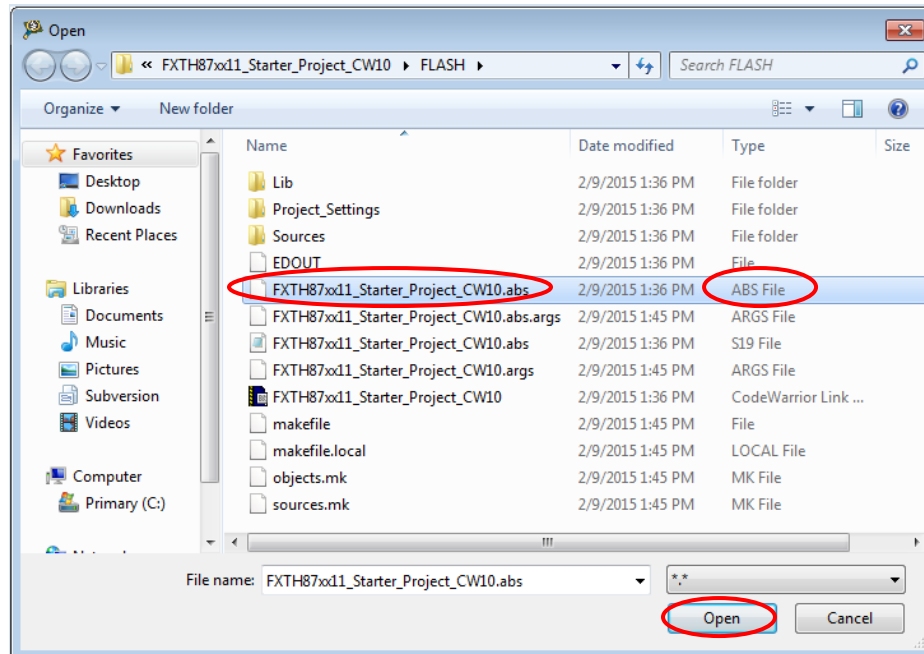
Go to *Run/Debug Settings* and edit the configuration that is used. Here it is the *FLASH\_PnE U-Multilink* configuration (the P&E micro Multilink Universal is used to program the device).



The Configuration window must look like the following.

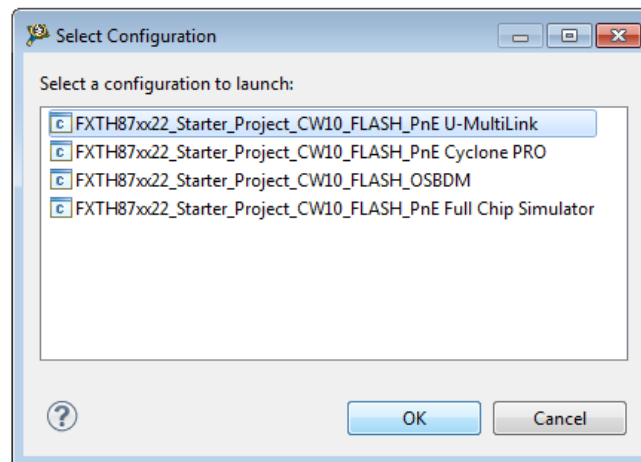


To select the application file go into the FLASH folder (it is in the project's folder) and choose the abs file (be careful: do not select the s19 file that has the same name).



Once the configurations are done, click *Apply* and OK.

In Code Warrior, click on *Run* and then *Debug*. If the following window appears, choose again the correct configuration.



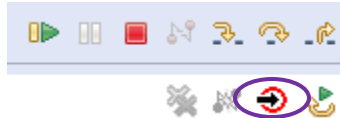


### e. When running the program after having reprogrammed the device

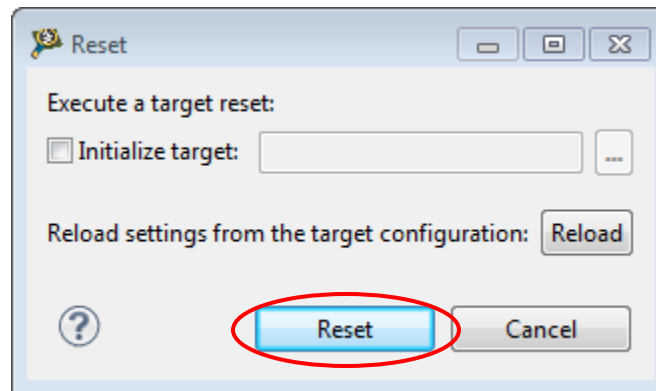
#### ⇒ If the program does not stop at breakpoints

Verify that only one breakpoint is set. If it is the case the target has probably not been reseted. The device must always be reseted after having been reprogrammed.

In the debugger window click on *Reset*.



Then click on *Reset* again.



After this reset a new breakpoint can be set.