Migration Guide from MKW36Z512xxx4 to MKW35Z512xxx4

1. Introduction

This document describes how to migrate from Kinetis MKW36Z512xxx4 to MKW35Z512xxx4 microcontrollers emphasizing in connectivity software. In this document MKW36Z512xxx4 and MKW35Z512xxx4 are referred as MKW36 and MKW35 respectively. The document is intended for software engineers, software testers, software integrators, and customers designing their own hardware.

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2. Hardware Considerations

The MKW35 wireless MCU is pin to pin compatible with MKW36, and almost all peripherals are in accord in both devices. The main difference between MKW36 and MKW35 microcontrollers is related to the size and addressing of the On-chip Flash Memory. The *Table* 1 shows the differences:

Device	512 KB P-Flash	256 KB P-Flash + 256 KB FlexNVM	Capable to emulate 8 KB EEPROM	2 nd instance of LPUART	FlexCAN module
MKW36		X	X	X	X
MKW35	X				

Table 1. Differences between MKW36 and MKW35

2.1. Peripherals Instantiation

KW36/35 devices are pin to pin compatible for both available packages (40-pin QFN and 48-pin LQFN). MKW35 does not support LPUART1 and FlexCAN, therefore, the signals of the last instances are not available for multiplexing in this device. **Bold** alternatives are only included for MKW36 microcontroller.

Pin Name	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	ALT8	ALT9
PTA16		PTA16/ LLWU_P4	SPI1_SOUT	LPUART1_ RTS_b		ТРМ0_СН0				
PTA17		PTA17/ LLWU_P5/	SPI1_SIN	LPUART1_ RX	CAN0_TX	TPM_				
		RF_RESET		IX.		CLKIN1				
PTA18		PTA18/ LLWU_P6	SPI1_SCK	LPUART1_ TX	CAN0_RX	TPM2_CH0				
PTA19	ADC0_SE5	PTA19/ LLWU_P7	SPI1_PCS0	LPUART1_ CTS_b		TPM2_CH1				
		PTB0/								
PTB0		LLWU_P8/		I2C0_SCL	CMP0_OUT	TPM0_CH1		CLKOUT	CAN0_TX	
		RF_ RFOSC_								
		EN/								
		RF_RESET								
PTB1	ADC0_SE1/ CMP0_IN5	PTB1/ RF_	DTM_RX	I2C0_SDA	LPTMR0_ ALT1	TPM0_CH2		CMT_IRO	CAN0_RX	
	5 5_1115	PRIORITY			11111					

Table 2. MKW35/36 instance comparative

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Demo	ADC0_SE2/	DEEDO	LPUART1_		OI WOLUM	mpres cure	RTC_		
РТВ3	CMP0_IN4	PTB3	RTS_b		CLKOUT	TPM1_CH1	CLKOUT		
PTB16	EXTAL32K	PTB16	LPUART1_	I2C1_SCL		TPM2_CH0			
PIDIO		PIDIO	RX	12C1_5CL		TPMZ_CHU			
PTB17	XTAL32K	PTB17	LPUART1_	I2C1_SDA		TPM2_CH1	BSM_CLK		
11017		11017	TX	1201_5571		11 1/12_0111	DOW_GER		
PTB18	ADC0_SE4/ CMP0_IN2	PTB18	LPUART1_	I2C1_SCL	TPM_ CLKIN0	TPM0_CH0	NMI_b		
	GMP0_IN2		CTS_b	_	CLKINU	_			
PTC3		PTC3/ LLWU_P11	RX_ SWITCH	I2C1_SDA	LPUART0_ TX	TPM0_CH1	DTM_TX	SPI1_SIN	CAN0_TX
		DDW 0_111	5 111 611		171				
		PERC 11			I DILL DES				
PTC4		PTC4/ LLWU_P12/		EXTRG_IN	LPUART0_ CTS_b	TPM1_CH0	BSM_DATA	SPI1_PCS0	CANO_RX
		BLE_RF_			_				
		ACTIVE PTC16/			LPUART0_			LPUART1_	
PTC16		LLWU_P0/	SPI0_SCK	I2C0_SDA	RTS_b	TPM0_CH3		_	
		RF_						RTS_b	
		STATUS PTC17/			LPUARTO_	BSM_		LPUART1_	
PTC17		LLWU_P1/	SPI0_SOUT	I2C1_SCL	RX	FRAME	DTM_RX	RX	
		RF_EXT_ OSC_EN						I.A.	
		PTC18/	anva av-	70.01.07	LPUARTO_	P01 6 P 1 F 1		LPUART1_	
PTC18		LLWU_P2	SPI0_SIN	I2C1_SDA	TX	BSM_DATA	DTM_TX	TX	
		PTC19/			LPUARTO_			LPUART1_	
PTC19		LLWU_P3/	SPI0_PCS0	I2C0_SCL	CTS_b	BSM_CLK		CTS_b	
		RF_ EARLY_							
		WARNING							

NOTE

Table 2 is not a full description of the MKW35/36 pinout.

NOTE

There is a change in the number of available digital pins between 40-pin and 48-pin packages due to different number of pins. For example, in the 48-pin package, there is a total of 25 digital pins while in the 40-pin package, 18 digital pins are available.

2.2. MCU On-chip Memory

2.2.1 MKW36 Flash Memory

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MKW36 Flash is partitioned into:

- One 256 KB Program Flash (P-Flash) array divided into 2 KB sectors. Flash address range from 0x0000 0000 to 0x0003 FFFF.
- One 256 KB FlexNVM array divided in 2 KB sectors, flash address range from 0x1000_0000 to 0x1003_FFFF with an Alias memory with address range 0x0004_0000 to 0x0007_FFFF. FlexNVM memory can be used as Program Flash (P-Flash), Data Flash (D-Flash) and EEPROM Flash.



Figure 1. KW36 Flash Memory Map

2.2.2 MKW35 Flash Memory

MKW35 Flash does not support FlexNVM nor Alias memory, therefore, Program Flash array increase to:

2x256 KB Program Flash (P-Flash) array starting from 0x0000_0000 to 0x0007 FFFF address divided into 2 KB sectors.

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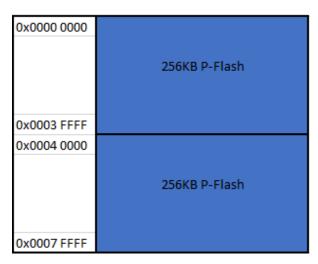


Figure 2. KW35 Flash Memory Map

3. Software Development Kit Download and Install

This chapter provides all the steps needed to download the SDK (Software Development Kit) for MKW35Z512xxx4 due it is used as starting point to migrate a MKW36 code to MKW35 MCU. Below are the steps to download the SDK package:

- 1. Go to MCUXpresso web page (mcuxpresso.nxp.com).
- 2. Log in with your registered account.
- 3. Search for "KW35Z" device. Then click on the suggested processor and click on "Build MCUXpresso SDK".

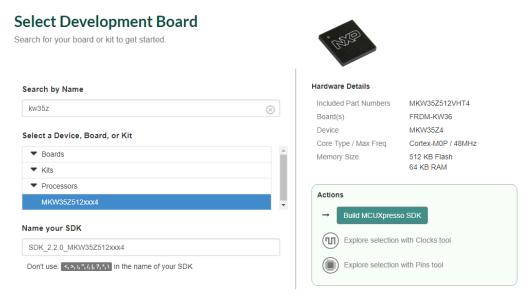


Figure 3. Building MKW35 SDK package

4. The next page is displayed. Select "All toolchains" in the "Toolchain / IDE" box and provide name to identify the package.

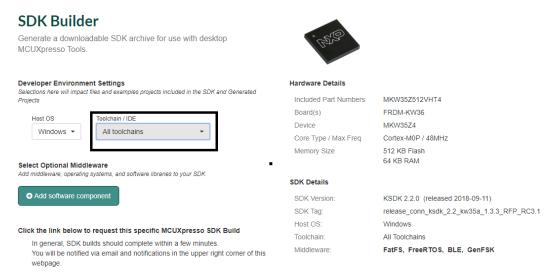


Figure 4. Selecting version of SDK

- 5. Click on the "Request Build" button. This will start the building process of the desired SDK. It will take few minutes until the system get the package into your profile in MCUXpresso web page.
- 6. Once the SDK is ready to download, it is displayed in the MCUXpresso Dashboard as shown in *Figure* 5



Figure 5. MKW35 SDK displayed in Dashboard

7. Click on download icon as shown in *Figure* 5 A new window appears to download the package.

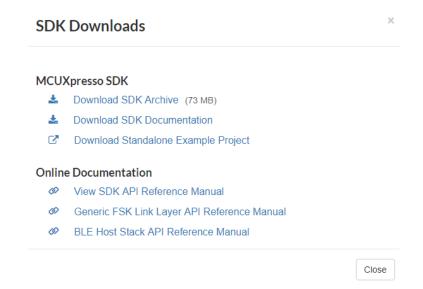


Figure 6. MKW35 SDK displayed in Dashboard

- 8. Accept the license agreement and save the SDK in your desired location.
- 9. If MCUXpresso IDE is used, drag and drop the MKW35 SDK zip folder in "Installed SDK's" perspective to install the package.

At this point, you have downloaded and installed the SDK package for MKW35Z device.

4. Software Migration in IAR Embedded Workbench

This chapter provides all the steps needed to migrate a MKW36 example code to MKW35 MCU in IAR Embedded Workbench IDE. The Heart Rate Sensor project is used as base in this document because it has easy to understand example and involves the Bluetooth LE connectivity software stack (included in SDK).

4.1. Changes Required in Project Options and Settings

NOTE

In this section "bare metal" version of the project was used, however, the same steps apply for "freertos" projects. Some paths related to "bm" projects may differ if "freertos" versions were used.

- 1. Open the heart rate sensor project located at the following path: <*SDK_root*>/boards/frdmkw36/wireless_examples/bluetooth/hrs/bm/iar/hrs_bm.eww
- 2. Select the project in the workspace and press Alt + F7 to open project options.

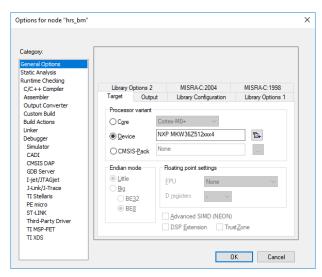


Figure 7. Project options window

3. In the General Options/Target window click the icon next to the device name and select the appropriate device NXP/KinetisKW/KW3x/NXP MKW35Z512xxx4, then click the OK button.

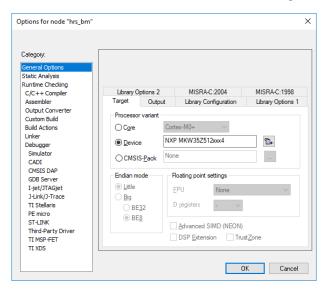


Figure 8. Selecting MKW35 device

- 4. Create a new folder with the name MKW35Z at following paths:
 - <SDK_root>/middleware/wireless/framework_5.4.2/DCDC/Interface
 - <SDK_root>/middleware/wireless/framework_5.4.2/DCDC/Source
 - <SDK_root>/middleware/wireless/framework_5.4.2/LowPower/Interface
 - $<\!\!SDK_root\!\!>\!\!/middleware/wireless/\!framework_5.4.2/LowPower/\!Source$
 - <SDK_root>/middleware/wireless/framework_5.4.2/XCVR



Figure 9. Creating MKW35Z folders

5. Copy all files inside MKW36Z folders located at the above mentioned paths and paste in MKW35Z folders.

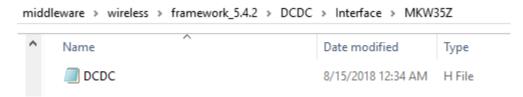


Figure 10. Creating the MKW35 files

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6. Select the heart rate sensor in the workspace and press Alt+F7 to open project options window. In C/C++ Compiler/Preprocessor window, rename the paths related to MKW36Z folders to MKW35Z folders modifying a 5 number instead of 6 in the additional include directories text box. The results must look similar as shown below:

```
$PROJ_DIR$/middleware/wireless/framework_5.4.2/LowPower/Interface/MKW35Z
```

\$PROJ_DIR\$/../../../devices/MKW35Z4/drivers

\$PROJ_DIR\$/../../../middleware/wireless/framework_5.4.2/DCDC/Interface/MKW35Z

\$PROJ_DIR\$/../../../middleware/wireless/framework_5.4.2/XCVR/MKW35Z4

\$PROJ_DIR\$/../../../devices/MKW35Z4

\$PROJ DIR\$/../../../devices/MKW35Z4/utilities

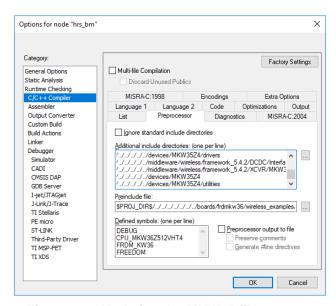


Figure 11. Updating the MKW35 files

7. Rename the CPU_MKW36Z512VHT4 macro as CPU_MKW35Z512VHT4 and delete FRDM_KW36 and FREEDOM macros in defined symbols text box. Click the OK button.

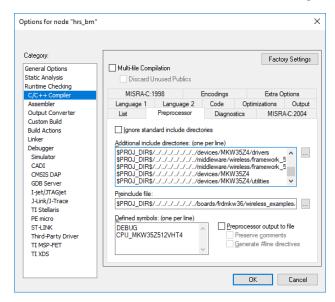


Figure 12. Defining MKW35 macros

8. Expand the startup folder, select all files, click the right mouse button and select the "Remove" option. Click right mouse button on the folder and select "Add/Add files". Add the startup_MKW35Z4.s located at this path:

<SDK_root>/devices/MKW35Z4/iar/startup_MKW35Z4.s

Also, add system_MKW35Z4.c and system_MKW35Z4.h into the startup folder. Both files are located at next path:

<SDK_root>/devices/MKW35Z4

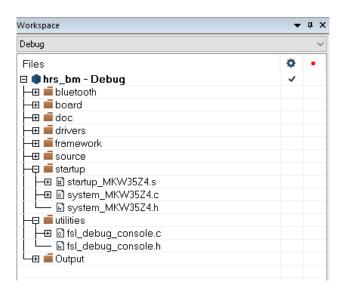


Figure 13. Replacing startup and system files

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 Some files need to be updated. Go to PWRLib.c file (in workspace framework/LowPower/Source). Replace LPUART0_LPUART1_IRQn by LPUART0_IRQn in the PWRLib_StopUpdateWakeupReason function.

Figure 14. Updating PWRLib.c file

10. Open clock_config.c file in board folder. Delete CLOCK_SetLpuart1Clock call to function in the BOARD_BootClockRUN function.

```
CLOCK_SetLpuartOClock(SIM_LPUART_CLK_SEL_OSCERCLK_CLK);

/* Set LPUART1 clock source. */

// Delete this line: CLOCK_SetLpuart1Clock(SIM_LPUART_CLK_SEL_OSCERCLK_CLK)

/* Set TPM clock source. */

CLOCK_SetTpmClock(SIM_TPM_CLK_SEL_OSCERCLK_CLK);
```

Figure 15. Updating clock_config.c file

11. If it is necessary, open the app_preinclude.h file under the source directory in the workspace. This file contains important information about the board such as the number of switches and LED's, timers, power consumption settings, etc. Examine and update this file to fit into own custom board.

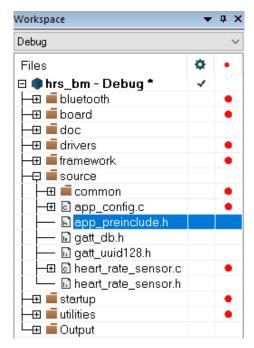


Figure 16. Location of preinclude file

12. If it is necessary, open the pin mux files (pin_mux.c and pin_mux.h) and gpio files (gpio_pins.c and gpio_pins.h) under the board directory in the workspace. These files contain alternatives, options and multiplexing information of the pins. Examine and update to fit into own custom board.

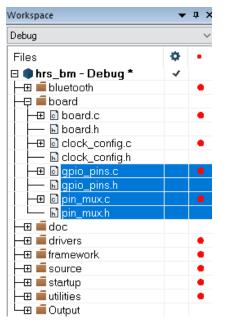


Figure 17. Location of pin mux and gpio files

13. Save the MKW35Z512xxx4_connectivity.icf file located at:

<SDK_root>/middleware/wireless/framework_5.4.4/Common/devices/MKW35Z4/iar

Into the folder of the heart rate sensor project located at the following path:

<SDK_root>/boards/frdmkw36/wireless_examples/bluetooth/hrs/bm/iar

14. Open the project options window (Alt+F7). In Linker/Config window click the icon next to linker path and select the linker configuration file MKW35Z512xxx4_connectivity.icf.

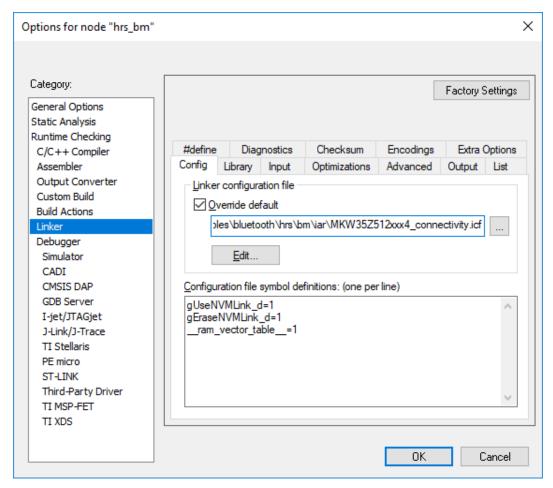


Figure 18. Updating the linker file

- 15. Click the OK button in the project options window to save the new configuration.
- 16. Select the project in the workspace, click the right mouse button and press clean.
- 17. Rebuild the project. At this point, the project is already migrated and you can customize the application for your own purpose using MKW35 device.

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5. Software Migration in MCUXpresso IDE

This chapter provides all the steps needed to migrate a MKW36 example code to MKW35 MCU in MCUXpresso IDE. The Heart Rate Sensor project is used as base because it has easy to understand example and involves the Bluetooth LE connectivity software stack (included in SDK).

5.1. Changes Required in Project Properties

1. Find the Quickstart Panel in the lower left-hand corner.

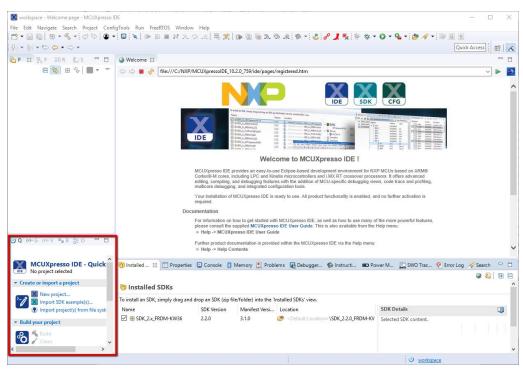


Figure 19. Quickstart Panel perspective in MCUXpresso IDE

2. Then click on "Import SDK examples(s)..." option.

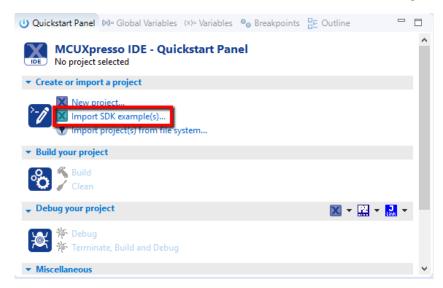


Figure 20. Importing an SDK example

3. Click on the **frdmkw36** board and then click on Next.

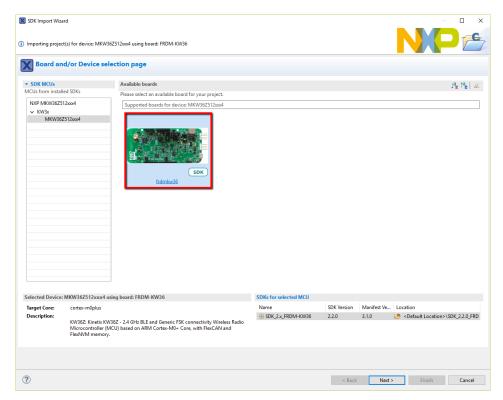


Figure 21. Select FRDM-KW36 board

4. In the search text box, type "hrs" to filter the example projects. Use the arrow button to expand the list and locate the "hrs" project (wireless_examples -> bluetooth -> hrs), then, select the **bm** version of the project and click "Finish".

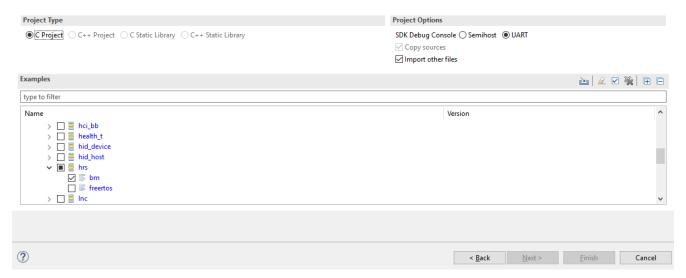


Figure 22. Opening heart rate sensor project

5. Go to *Project/Properties*. Expand *C/C++ Build/MCU settings* and select MKW35Z512xxx4 MCU. lick Apply and Close button to save the configuration.

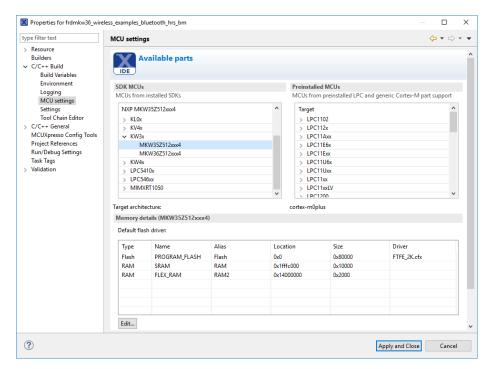


Figure 23. Selecting MKW35 MCU

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- 6. Rename MKW36 folders as MKW35 at the following paths (Default MCUXpresso root in Documents/MCUXpressoIDE<version>/workspace):
 - <MCUXpresso_hrs_project_root>/framework/DCDC/Interface
 - <MCUXpresso_hrs_project_root>/framework/DCDC/Source
 - <MCUXpresso_hrs_project_root>/framework/LowPower/Interface
 - <MCUXpresso_hrs_project_root>/framework/LowPower/Source
 - <MCUXpresso_hrs_project_root>/framework/XCVR
- 7. Select the heart rate sensor project in the workspace and press F5 to refresh the modified folders.

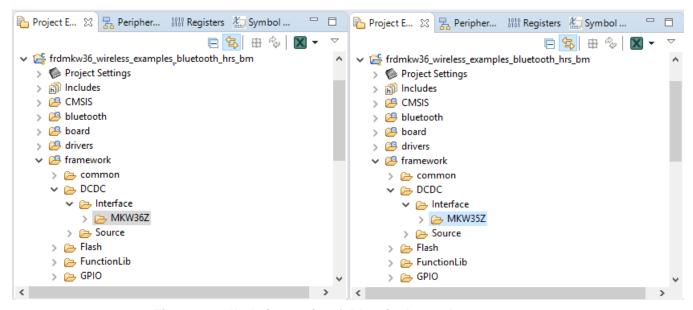


Figure 24. Updating project folders in the workspace

- 8. Open the *Project/Properties* window in MCUXpresso IDE. Go to *C/C++ Build/Settings* and select *MCU C Compliler/Includes* folder in *Tool Settings* window. Edit all paths related to MKW36 MCU, in according to MKW35 folders before created. The results must look similar as shown below:
 - ../framework/LowPower/Interface/MKW35Z
 - ../framework/LowPower/Source/MKW35Z
 - ../framework/DCDC/Interface/MKW35Z
 - ../framework/XCVR/MKW35Z4

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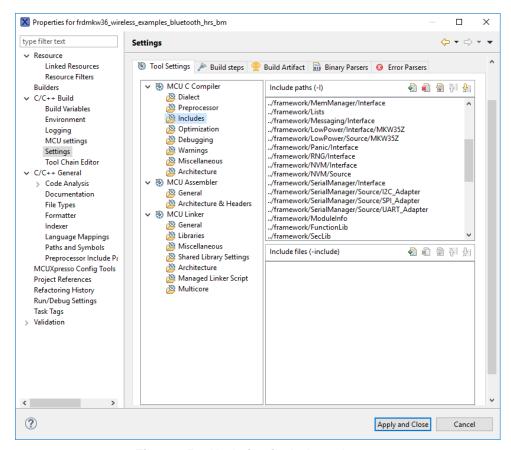


Figure 25. Updating include paths

- 9. Select *MCU Assembler/General* folder in *Tool Settings*. Edit the paths related to MKW36 MCU. The results must look similar as shown below:
 - ../framework/LowPower/Interface/MKW35Z
 - ../framework/LowPower/Source/MKW35Z
 - ../framework/DCDC/Interface/MKW35Z
 - ../framework/XCVR/MKW35Z4

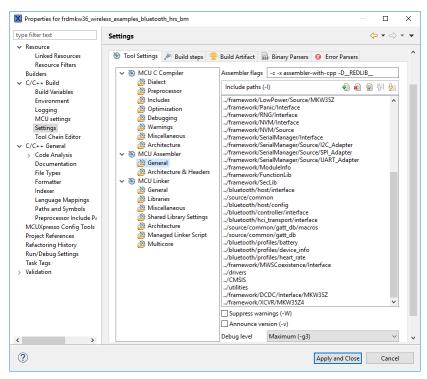


Figure 26. Updating assembler paths

10. Open MCU C Compiler/Preprocessor window, edit the CPU_MKW36Z512VHT4 and CPU_MKW36Z512VHT4_cm0plus macros by CPU_MKW35Z512VHT4_cm0plus and CPU_MKW35Z512VHT4_cm0plus respectively. Delete FRDM_KW36 and FREEDOM macros. Then click Apply and Close button.

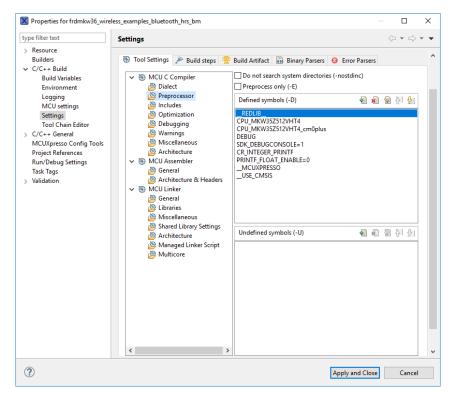


Figure 27. Updating preprocessor macros

- 11. Delete "fsl_device_registers, MKW36Z4, MKW36Z4_features, system_MKW36Z4.h and system_MKW36Z4.c" files located at CMSIS folder in the workspace.
- 12. Unzip the MKW35Z SDK package and search for "fsl_device_registers, MKW35Z4, MKW35Z4_features, system_MKW35Z4.h and system_MKW35Z4.c" files into this folder at the following paths:
 - <SDK_folder_root>/devices/MKW35Z4/fsl_device_registers.h
 - <SDK_folder_root>/devices/MKW35Z4/MKW35Z4.h
 - <SDK_folder_root>/devices/MKW35Z4/MKW35Z4_features.h
 - <SDK_folder_root>/devices/MKW35Z4/system_MKW35Z4.h
 - <SDK_folder_root>/devices/MKW35Z4/system_MKW35Z4.c

Drag and drop this files into the CMSIS folder in the workspace.

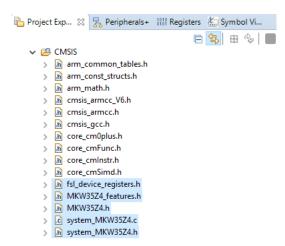


Figure 28. Updating CMSIS files

13. Replace the "startup_MKW36Z.S" file located at startup folder in the workspace by the "startup_MKW35Z4.S". This file is located, as the same as in the last step, in the MKW35Z SDK at following path:

<SDK_folder_root>/devices/MKW35Z4/gcc/startup_MKW35Z4.S

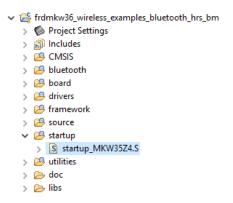


Figure 29. Updating the startup file

14. Some files need to be updated. Go to PWRLib.c file (in workspace framework/LowPower/Source/MKW35Z). Replace LPUART0_LPUART1_IRQn by LPUART0_IRQn in the PWRLib_StopUpdateWakeupReason function.

```
void PWRLib_StopUpdateWakeupReason(void)
{
    uint32_t iser;
    uint32_t ispr;

    iser = NVIC->ISER[0];
    ispr = NVIC->ISPR[0];

    if(( iser & ispr) & (1 << LPUART0_IRQn)) //Replace LPUART0_LPUART1_IRQn by LPUART0_IRQn
    {
        PWRLib_MCU_WakeupReason.Bits.FromPSwitch_UART = 1;
    }

    if(( iser & ispr) & (1 << LVD_LVW_DCDC_IRQn))
    {
        PWRLib_MCU_WakeupReason.Bits.FromPSwitch_UART = 1;
    }
}</pre>
```

Figure 30. Updating PWRLib.c file

15. Open clock_config.c file in board folder. Delete CLOCK_SetLpuart1Clock call to function in the BOARD BootClockRUN function.

```
/* Set LPUART0 clock source. */
CLOCK_SetLpuart0Clock(SIM_LPUART_CLK_SEL_OSCERCLK_CLK);
/* Set LPUART1 clock source. */
//Delete this line: CLOCK_SetLpuart1Clock(SIM_LPUART_CLK_SEL_OSCERCLK_CLK);
/* Set TPM clock source. */
CLOCK_SetTpmClock(SIM_TPM_CLK_SEL_OSCERCLK_CLK);
```

Figure 31. Updating clock_config.c file

16. If it is necessary, open the app_preinclude.h file under the source directory in the workspace. This file contains important information about the board such as the number of switches and LED's, timers, power consumption settings, etc. Examine and update this file to fit into own custom board.

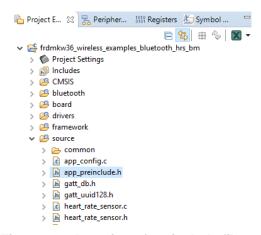


Figure 32. Location of preinclude file

17. If it is necessary, open the pin mux files (pin_mux.c and pin_mux.h) and gpio files (gpio_pins.c and gpio_pins.h) under the board directory in the workspace. These files contain alternatives, options and multiplexing information of the pins. Examine and update to fit into own custom board.

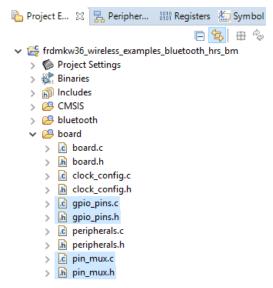


Figure 33. Location of pin mux and gpio files

18. Replace the MKW36Z512xxx4_PD_connectivity.ld file by MKW35Z512xxx4_connectivity.ld located at:

<SDK_root>/middleware/wireless/framework_5.4.4/Common/devices/MKW35Z4/gcc Into the source folder in the workspace.

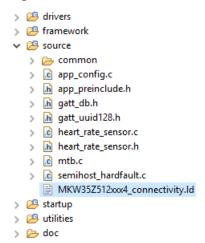


Figure 34. Replacing the linker file

Migration Guide from MKW36Z512xxx4 to MKW35Z512xxx4, User's Guide, Rev. 1, 06/2019

19. Open the *Project/Properties* window. Next, go to the *MCU Linker/Managed Linker Script* perspective and edit the Linker Script name according with MKW35 device. Press Apply and Close button.

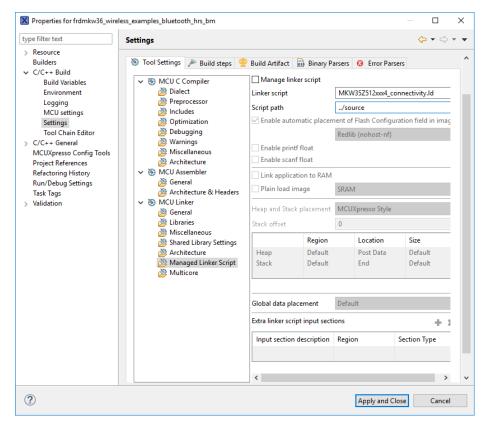


Figure 35. Establishing the linker path

20. Build the project. At this point, the project is already migrated and you are ready to play with the demo using MKW35.

6. Build and Run Bluetooth LE Connectivity Stack **Examples**

All the examples referenced in BLE Demo Applications User's Guide (BLEDAUG) are compatible with MKW35 device following modifications described in this document. The BLEDAUG is part of the FRDM-KW36 SDK documentation.

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