

Freescale Semiconductor

Application Note

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Interfacing HCS12 Microcontrollers to the MFR4310 FlexRay Controller

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1 Introduction

Freescale Semiconductor offers a range of standalone FlexRay communication controllers (MFR4xxx) that can be interfaced with 16-bit and 32-bit microcontrollers (MCU). This application note describes the hardware, software and timing considerations necessary for reliable communication between the MFR4310 controller and the HCS12 family of MCUs.

2 Objective

The aim of the document is to demonstrate the simplicity of the hardware interface between the MFR4310 and the HCS12 and to provide an example of the software used to configure the HCS12 for operation. The information contained can help you quickly design a fully functional FlexRay node based on the HCS12 Family of MCUs. Evaluation boards with software are available from Freescale, to assist in the development of FlexRay applications. (See http://www.freescale.com/flexray.)

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Note: In this document, active-low signals are indicated by a "#" at the end of the signal name, e.g. "IRQn#".



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Hardware Design

3 Hardware Design

The MFR4310 FlexRay controller has two separate controller host interfaces (CHI) on board - an HCS12 interface, for direct connection to Freescale's HCS12 family of microcontrollers, and an asynchronous memory interface (AMI) for asynchronous connection to all other microcontrollers. The HCS12 interface clock signal, used to synchronize the data transfer, can run at a maximum rate of 8 MHz.

Chip selection for the S12 interface is generated internally using the following signals:

- The input values of the expanded address signals XADDR[14:19] are compared with logical 0's (the S12 External Bus Interface (EBI) is in the Paged or Unpaged mode).
- The three most significant bits of the demultiplexed address bus, PA[5:7], are compared with the pattern set up externally on the address chip select pins ACS[0:2]; PA5 is compared with ACS0, PA6 with ACS1, PA7 with ACS2.

NOTE

The address decoding phase of a read/write operation is passed if all the comparisons described above are passed.

The devices can be connected together without additional glue logic, thereby simplifying the design and reducing the system cost.

Section 3.2 shows how to connect the FlexRay CC to an S12 MCU with EBI paged mode and unpaged mode support.

3.1 Selecting the HCS12 Mode

There are two modes of operation for the controller host interface (CHI), the AMI mode and the HCS12 mode. The HCS12 mode is used to interface to the HCS12 Family of microcontrollers.

To select the HCS12 mode, IF_SEL1 must be at the logic high level and IF_SEL0 must be at the logic low level. When using 5V VDDIO, for example, IF_SEL1 must be pulled high using a 10 k Ω pullup resistor, and IF_SEL0 must be pulled low using a 47 k Ω pulldown resistor. (Similarly, at 3.3 V VDDIO, INT_CC# must be held high by a 16 k Ω pullup resistor.)

See the MFR4310 data sheet (reference 2) for recommended pullup and pulldown resistor values for the IF_SEL[1:0] inputs.

3.2 Paged Mode and Unpaged Mode

There are two modes of operation that can be used when interfacing the HCS12 and MFR4310 microcontrollers — paged and unpaged mode.

Figure 1 and Figure 2 show block diagrams with all the EBI connections that are necessary for each mode of operation.

Table 1 provides a description of each signal and pin that must be connected to interface the MFR4310 to a typical HCS12 MCU, the MC9S12DP256B in a 112-pin LQFP package.



Hardware Design

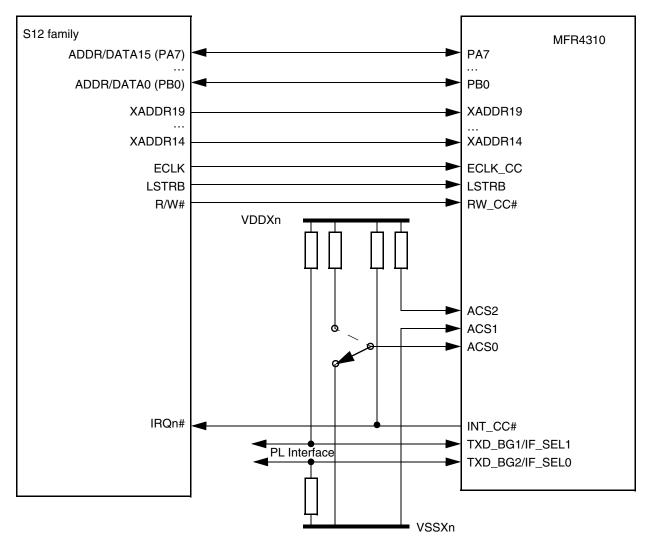


Figure 1. Connecting MFR4310 to HCS12 with Page Mode Support



Hardware Design

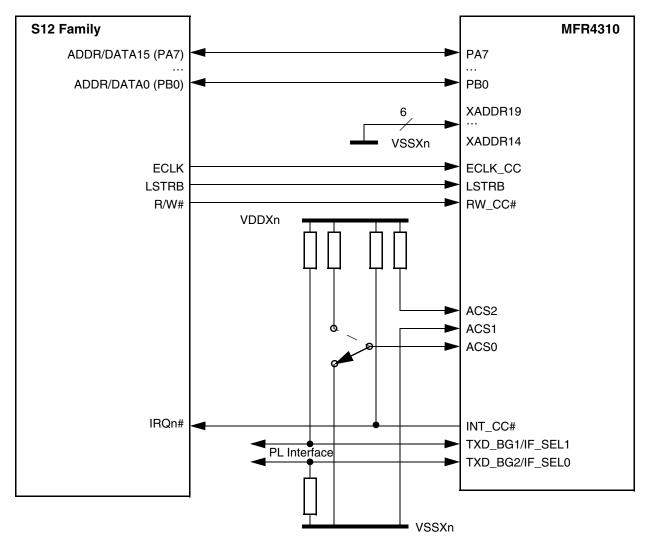


Figure 2. Connecting MFR4310 to HCS12 with Unpaged Mode Support



| | | HCS12 to MFR4310 Connect | tion | | |
|---------------------|----------|---------------------------------|---------------|---|--|
| MC9S12DP256B (112-F | in LQFP) | MFR300 | | Comments | |
| Signal | Pin | Signal | Pin | | |
| ADDR0/DATA0/PB0 | 24 | D15/PB0 | 10 | HCS12 data/address bus (LSB) | |
| ADDR1/DATA1/PB1 | 25 | D14/PB1 | 7 | HCS12 data/address bus | |
| ADDR2/DATA2/PB2 | 26 | D13/PB2 | 6 | HCS12 data/address bus | |
| ADDR3/DATA3/PB3 | 27 | D12/PB3 | 5 | HCS12 data/address bus | |
| ADDR4/DATA4/PB4 | 28 | D11/PB4 | 4 | HCS12 data/address bus | |
| ADDR5/DATA5/PB5 | 29 | D10/PB5 | 3 | HCS12 data/address bus | |
| ADDR6/DATA6/PB6 | 30 | D9/PB6 | 2 | HCS12 data/address bus | |
| ADDR7/DATA7/PB7 | 31 | D8/PB7 | 62 | HCS12 data/address bus | |
| PA0/ADDR8/DATA8 | 57 | D7/PA0 | 61 | HCS12 data/address bus | |
| PA1/ADDR9/DATA9 | 58 | D6/PA1 | 58 | HCS12 data/address bus | |
| PA2/ADDR10/DATA10 | 59 | D5/PA2 | 57 | HCS12 data/address bus | |
| PA3/ADDR11/DATA11 | 60 | D4/PA3 | 56 | HCS12 data/address bus | |
| PA4/ADDR12/DATA12 | 61 | D3/PA4 | 55 | HCS12 data/address bus | |
| PA5/ADDR13/DATA13 | 62 | D2/PA5 | 51 | HCS12 data/address bus | |
| PA6/ADDR14/DATA14 | 63 | D1/PA6 | 40 | HCS12 data/address bus | |
| PA7/ADDR15/DATA15 | 64 | D0/PA7 | 39 | HCS12 data/address bus | |
| XADDR14/PK0 | 8 | A6/XADDR14 | 17 | Extended addresses (page mode) | |
| XADDR15/PK1 | 7 | A5/XADDR15 | 15 | Extended addresses (page mode) | |
| XADDR16/PK2 | 6 | A4/XADDR16 | 14 | Extended addresses (page mode) | |
| XADDR17/PK3 | 5 | A3/XADDR17 | 13 | Extended addresses (page mode) | |
| XADDR18/PK4 | 20 | A2/XADDR18 | 12 | Extended addresses (page mode) | |
| XADDR19/PK5 | 19 | A1/XADDR19 | 11 | Extended addresses (page mode) | |
| ECLK/PE4 | 39 | A10/ECLK_CC | 52 | HCS12 clock input | |
| R/W#/PE2 | 54 | WE#/RW_CC# | 30 | HCS12 read/write select signal | |
| LSTRB/TAGL0/PE3 | 53 | CE#/LSTRB | 29 | HCS12 low-byte strobe signal | |
| GPIO (or PU/PD) | | OE#/ASC0, A11/ASC1, A12/ACS2 | 27, 28, 34 | HCS12 address select inputs | |
| GPIO | | RESET# | 16 | Hardware reset input | |
| PE1/IRQ# | 55 | INT_CC# | 64 | Controller interrupt output | |
| | | BGT/DBG2/IF_SEL0 | 32 | Host interface selection = LOW (HCS12 mode) | |
| | | TXD_BG1/TXD1_485/IF_SEL1 | 41 | Host interface selection = HIGH (HCS12 mode) | |

Table 1. Interface Signal Description



Timing Considerations

4 Timing Considerations

For the HCS12 and the MFR4310 communication controller to communicate reliably, the timing between the HCS12 and the MFR4310 must be matched. There is a requirement for the addition of stretch cycles¹ to match the timing characteristics. Refer to the MFR4310 data sheet (reference 2) for specific timing diagrams. A minimum of one stretch cycle must be inserted when running with an 8 MHz external clock. Table 3 summarizes the read and write timing for one stretch cycle, which is required for successful operation. The number of stretch cycles that can be added is controlled in the Miscellaneous System Control Register (MISC). Refer to the Module Mapping Control (MMC) section of the user manual. The available options are shown in Table 2.

| External Access Stretch Bit Definition | | | | |
|--|------------------------------|--|--|--|
| EXSTR[1:0] | Number of E Clocks Stretched | | | |
| 00 | 0 cycles | | | |
| 01 | 1 cycle | | | |
| 10 | 2 cycles | | | |
| 11 | 3 cycles | | | |

| | | Specified | | | |
|--|--------|-----------|-----|----------|---------|
| Rating | Symbol | Min | Max | Measured | Comment |
| Pulse width, ECLK Low | tLEC | 30 | | 560 | PASS |
| Pulse width, ECLK High | tHEC | 99 | | 190 | PASS |
| Address valid time to ECLK rise | tSA | 11 | | 56 | PASS |
| Write data delay time | tDDW | | 70 | 5 | PASS |
| Write data hold time | tHDW | 80 | | 190 | PASS |
| RW delay time | tDRW | | 7 | 0 | PASS |
| RW valid time to ECLK rise | tSRW | 14 | | 560 | PASS |
| RW hold time | tHRW | 2 | | 8 | PASS |
| Data hold to address | tHDA | 2 | | 8 | PASS |
| Multiplexed address hold time | tHA | 2 | | 12 | PASS |
| ECLK high access time (ECLK high to Read Data valid) | tDEC | 50 | 90 | 56 | PASS |
| Read data setup time | tSDR | 13 | | 135 | PASS |
| Read data hold time | tHDR | 0 | | 12 | PASS |

Table 3. HCS12 to MFR4310 Timing Parameters with One Stretch Cycle

^{1.} When accessing on-chip peripherals and memories, the HCS12 performs 8-bit and 16-bit core accesses in a single cycle. However, when the core accesses locations on the external bus using the expanded modes, the accesses are stretched and take more than a single cycle to complete. The minimum amount of stretching is one additional bus cycle, but can be increased. See Table 2 for details.



The S12 interface can run only with the 40 MHz EXTAL_CC clock. Therefore, the timing on the S12 bus is as described in the MFR4310 reference manual. Here, the minimum low is 30 ns and the minimum high 99 ns. That would give us a maximum ECLK frequency of 7.75 MHz (on the MFR4200 the maximum ECLK frequency is 25 ns + 114 ns = 7.19 MHz).

The S12 interface accepts only aligned 16-bit read and 8-bit or 16-bit write transactions. The S12 interface does not support 8-bit read accesses.

- The internal chip select, CS, the low byte strobe, LSTRB, the least significant bit of the address, ADDR[0], and the read/write select, RW#, are used to determine the type of access.
- RW_CC# indicates the direction of data transfer for a transaction.

| CS | RW | LSTRB | ADR[0] | Type of Access |
|----|----|-------|--------|---|
| 0 | Х | х | Х | No access |
| 1 | 0 | 0 | 0 | 16-bit write to word address ¹ |
| 1 | 0 | 0 | 1 | 8-bit write to an odd address ² |
| 1 | 0 | 1 | 0 | 8-bit write to an even address ² |
| 1 | 0 | 1 | 1 | Not supported |
| 1 | 1 | 0 | 0 | 16-bit read from an even address ³ |
| 1 | 1 | 0 | 1 | Not supported |
| 1 | 1 | 1 | 0 | Not supported |
| 1 | 1 | 1 | 1 | Not supported |

Table 4. HCS12 Access Types

¹ Write data from PA to even byte address and from PB to odd byte address.

² Write data from PB.

³ Read data from even byte address at PA and from odd byte address at PB.



5 Software

The software setup is concerned mainly with selection of the correct MCU operating mode, configuration of the HCS12 for communication with the MFR4310, and linking into the correct area of the memory map.

5.1 Mode Configuration and EBI Operation

As already stated, the HCS12 must be configured into normal expanded mode to enable the bus interface. In this mode, ports A and B are configured for the data/address bus, and port E is configured for the control signals. During initialization, the EBI is configured, and the mode is set to normal expanded wide mode by writing MODC = 1, MODB = 1, and MODA = 1 in the MODE register. The EBI must be initialized to use the correct chip select and to select the correct number of stretch cycles. See Section 4, "Timing Considerations" for specific details.

Figure 3 shows the steps required to configure the HCS12 MCU for communication with the MFR4310 controller.

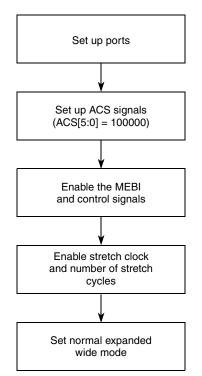


Figure 3. Initialization Flow Diagram

An example of typical HCS12 MCU initialization code is shown below.



Software

| <pre>// Set up ports PORTB = 0xFF; DDRB = 0xFF;</pre> | // Port B = 0xFF // Set port B as output |
|---|---|
| PTS = 0x00; DDRS = 0x04; | // Port S = 0x00 // Set port PS2 as output |
| PUCR_PUPEE = 1; | // Enable PULL UPS on PTE // Pull ups enabled on bits 7, 4-0 |
| PTH = 0x04; | // $ASC[2, 1, 0] = 100match 0x8000 on ADR bus$ |
| DDRH = 0×07 ; | // make PortH an Output |
| PPAGE = PAGE0; | // Pages \$00 - \$2F = External // Pages \$30 - \$3F = Internal |
| PEAR = 0x0C; | <pre>// Enable EBI // NOACCE = 0; PTE7 (GPIO) // PIPOE = 0; PTE[6:5](GPIO) // NECLK = 0; PTE4 (External ECLK) // LSTRE = 1; PTE3 (LSRTB#) // RDWE = 1; PTE2 (R/W#)</pre> |
| EBICTL = 0x01; | <pre>// ESTR = 1; Stretch Clock enabled</pre> |
| INTCR = 0xC0; | <pre>// IRQE = 0; low level // IRQEN = 1; Interrupt enabled</pre> |
| MISC = $0 \times 05;$ | <pre>// ESTR1:0 = 01; 1 clock stretches enabled // ROMHM = 0; Flash in low 1/2 of map can be accessed // ROMON = 1; Flash enabled in Memory map</pre> |
| MODE = 0xE3; | <pre>// MODC:MODB:MODA = 111; Normal Expanded Wide // IVIS = 0; No visibility of internal bus signals // EMK = 1; PORTK & DDRK removed from memory map // EME = 1; PORTE & DDRE removed from memory map</pre> |

NOTE

This is example code only; the port setup is dependent on specific schematic connections.



Conclusions

5.2 Placement of MFR4310 in Memory Map

Access to the external space is usually done by accessing locations in the page window (0x8000-0xC000) with PPAGE set to point to a page in external space.

In CodeWarrior, the FAR qualifier is used to tell the compiler to use the global instructions included in the HCS12 CPU. An example of how to place the MFR4310 registers into the memory map is shown below.

Example:

```
#define BASE_ADDRESS 0x8000
#define MVR (*(volatile unsigned int* far)(0x000 + BASE_ADDRESS))
#define MCR (*(volatile unsigned int* far)(0x002 + BASE_ADDRESS))
```

In this option, the placement of the memory map can be changed by modifying the BASE_ADDRESS. The selected BASE_ADDRESS of 8000 is in the external address range.¹

6 Conclusions

The FlexRay controller can be connected to the HCS12 Family of MCUs, with a maximum interface clock frequency (to synchronize data transfer) of 8 MHz.

Due to this specific interface between the HCS12 microcontrollers and MFR4310 FlexRay controller, no glue logic required. Software configuration is also straightforward, the peripheral being simply memory-mapped into the address space.

7 References

- 1. MC9S12DP256B Data Sheet (MC9S12DP256B)
- 2. MFR4310 FlexRay Communication Controller Reference Manual (MFR4310RM)

These documents are available on the Freescale Semiconductor web site at <u>http://www.freescale.com</u>.

More information on FlexRay and FlexRay products can be found at http://www.freescale.com/flexray

^{1.} Many alternative methods of defining the MFR4310 register exist.



References



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