Clock management and distribution in KL28

1. Introduction

This application note explains the clock architecture and clock distribution in KL28. Especially the two new clock related modules:

- SCG (System Clock Generator)
- PCC (Peripheral Clock Control)

SCG provides a broad range of reference clocks with more accuracy than MCG/_Lite, and more flexibility to work with different applications. With the help of the SCG, the core clock and peripherals clock can be routed from different clock sources. This means that the peripherals clock can be even faster than Core/Bus clock.

The PCC provides peripheral clock control and configuration registers, such as clock multiplexors and clock dividers. Unlike the old clock gate and configuration in SIM module, the PCC module makes it easier to select the peripheral clock source and the software oriented design makes the code more compatible.

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2. Clocking Architecture

The heart of the clocking architecture is the System Clock Generator (SCG) module. The SCG controls four clock sources (SIRC, FIRC, SOSC, and SPLL) that can then be distributed to the main core platform, the memory modules, and the peripherals. The peripherals in general have two clocks, one being the peripheral interface clock which is used by the core/DMA to interface with the peripheral’s registers, the second being the peripheral functional clock which is used for the main timing function of the peripheral (for instance it sources the baud rate for a serial communications peripheral, or is the input clock to the counter of a timer peripheral). The peripheral interface clock generally comes directly from the SCG to the peripheral. The second peripheral functional clock is selected via the Peripheral Clock Control (PCC) module. The SCG provides additional peripheral functional clocks with optional Dividers via the PCC module.

NOTE
1. All peripheral functional clocks are asynchronous clocks.
2. The peripheral interface clock is also known as the bus clock for other devices with MCG/_Lite.

The following diagram shows the various clock sources and clock trees for KL28.
In general, the DIVCORE_CLK is the old Core/Platform Clock, and DIVSLOW_CLK is the old Bus clock. Both the DIVCORE_CLK and DIVSLOW_CLK can act as peripheral interface clocks. The peripheral function clock is generally routed from <CLK_SRC>DIV1 - <CLK_SRC>DIV3_CLK. CLK_SRC is the SCG’s clock source and can be selected by the PCC module.

NOTE

1. KL28 flash clock is sourced from the DIV_SLOW clock.

2. All peripherals except from the USB module use the <CLK_SRC>DIV1 clock as their functional clock, the USB module uses <CLK_SRC>DIV3 as its functional clock.

Table 1 describes the detail of clock definition in KL28:

<table>
<thead>
<tr>
<th>Clock name</th>
<th>Run mode clock frequency</th>
<th>VLPR mode clock frequency</th>
<th>HSRUN mode clock frequency</th>
<th>Clock source</th>
<th>When can clock be disabled?</th>
</tr>
</thead>
<tbody>
<tr>
<td>DIVCORE_CLK</td>
<td>Up to 72 MHz</td>
<td>Up to 8 MHz</td>
<td>Up to 96 MHz</td>
<td>SCG</td>
<td>When both CPUs are in any stop modes except for Partial stop modes.</td>
</tr>
<tr>
<td>DIVSLOW_CLK</td>
<td>Up to 24 MHz</td>
<td>DIVCORE_CLK Divide by 4 or more.</td>
<td>Up to 24 MHz</td>
<td>SCG</td>
<td>When both CPUs are in any stop modes except for partial stop modes.</td>
</tr>
<tr>
<td>SOSCDIV1_CLK, SOSCDIV3_CLK</td>
<td>Up to 48 MHz</td>
<td>MHz Up to 8 MHz</td>
<td>Up to 48 MHz</td>
<td>SCG</td>
<td>If not being used by any peripheral and/or DIVCORE_CLK or feeding the PLL</td>
</tr>
<tr>
<td>SPLLDIV1_CLK, SPLLDIV3_CLK</td>
<td>Up to 72 MHz</td>
<td>PLL disabled</td>
<td>Up To 96 MHz</td>
<td>SCG</td>
<td>If not being used by any peripheral and/or DIVCORE_CLK</td>
</tr>
<tr>
<td>FIRCDIV1_CLK, FIRCDIV3_CLK</td>
<td>Up to 60 MHz</td>
<td>FIRC is disabled</td>
<td>Up to 60 MHz</td>
<td>SCG</td>
<td>If not being used by any peripheral and/or DIVCORE_CLK or feeding the PLL</td>
</tr>
<tr>
<td>SIRCDIV1_CLK, SIRCDIV3_CLK</td>
<td>8 MHz</td>
<td>8 MHz</td>
<td>8 MHz</td>
<td>SCG</td>
<td>If not being used by any peripheral</td>
</tr>
</tbody>
</table>

3. SCG (System Clock Generator)

3.1. SCG architecture

The system clock generator (SCG) module provides the system clocks of the MCU. The SCG contains:

- SOSC: output of the external oscillator (a crystal or externally applied clock input)
- SIRC: output of the slow (8 MHz) internal RC oscillator
- FIRC: output of the fast (48 MHz) internal RC oscillator
- SPLL: output of the PLL, which is sourced by either the SOSC reference clock or the FIRC
The SCG can select either one of the four output clocks as the source for the MCU system clocks. It also has dividers that can divide the clock output for the DIVCORE/DIVSLOW and peripheral functional clock.

The figure below shows the SCG module block diagram.

Figure 2. System Clock Generator (SCG) block diagram
3.2. Difference between SCG and MCG/MCG_Lite

Table 2 shows the different features between the old MCG/Lite and SCG mode.

<table>
<thead>
<tr>
<th>Feature</th>
<th>SCG</th>
<th>MCG/Lite</th>
<th>Advantages</th>
</tr>
</thead>
<tbody>
<tr>
<td>Internal Reference clock (IRC) frequency, accuracy and trimmable</td>
<td>SIRC=IRC8M: 2/8 MHz, 3 % temp drift  FIRC=IRC48M: 48 – 60 MHz, 1 % temp drift, programmable range  Both IRC user trimmable:  SIRC - frequency can trim shift +/- 10 %;  FIRC - trim accuracy: ~0.7 % or 0.04 %</td>
<td>IRC8M: 2/8 MHz, 3 % temp drift;  IRC48M: fixed frequency, 1 % ~ 1.5 % temp drift;  Both IRC are non-user trimmable</td>
<td>SCG provides broad range of reference clock with more accuracy than MCG/Lite, more flexible to different applications</td>
</tr>
<tr>
<td>Independent clock source dividers able to be disabled</td>
<td>All 4 clock sources have independent standardized dividers to PCC to generate independent peripheral functional clocks for different peripherals; and divider output can be disabled which can be used to gate a group of peripheral functional clocks.</td>
<td>IRC48M has no divider; only IRC8M has 2 dividers, each shared with multiple peripherals, and divider output cannot be disabled</td>
<td>Standardized divider makes SCG easy for coding; Independent clock source and divider makes it easy to change peripheral bit rate/frequency/duty cycle on the fly;</td>
</tr>
<tr>
<td>Separate configuration register for each operating mode (RUN/VLPR/HSRUN)</td>
<td>Yes. SCG_RCCR/VCCR/HCCR</td>
<td>No. Only one set of MCG_Cn</td>
<td>With SCG, automatic clock configuration when mode switching (RUN/VLPR/HSRUN), no additional code effort for mode switch, user friendly feature. With MCG/Lite, need much code effort to do clock mode switch, not user friendly.</td>
</tr>
<tr>
<td>Separate peripheral functional clock from peripheral interface clock/bus clock</td>
<td>Yes. allows peripherals to operate either slower or faster than CPU platform; Allows different groups of peripherals to be clocked by different specific functional clocks, e.g. a group of low power peripherals to be clocked at lower frequency than high resolution timers/fast serial communication peripherals.</td>
<td>Yes, but does not allow peripheral to operate faster than CPU. Grouping peripheral functional clock need access each peripheral register and/or SIM control register</td>
<td>User friendly peripheral clock grouping with SCG plus PCC, simple for coding; Easy to reduce power consumption with peripheral clock grouping.</td>
</tr>
</tbody>
</table>
4. PCC (Peripheral Clock Control)

The Peripheral Clock Control module (PCC) provides peripheral clock control and configuration registers. The configuration including clock multiplexors select and clock dividers configuration. Unlike the old clock gate control method in SIM module, in PCC each peripheral has one identical clock option, which makes it easy for software or RTOS to manage all peripheral usage in real time, especially in multiple core platforms. In addition, the PCC can also provide the capability to check the peripheral exist and in-use status, which can be used for peripheral discovery.

The figure below shows the PCC module functional diagram:
To enable and configure the module’s interface and functional clock, you must carry out the following steps:

1. Check the peripheral exists (optional), by checking the PR bit in corresponding PCC register.

2. Check the peripheral bit is in-use (optional), if peripheral is in-use, software need to perform the correct action to stop peripheral module activity.

3. Clear the CGC field to gate from the peripheral functional clock.

4. Configure the PCS field to select correct peripheral functional clock.

5. Set the CGC bit to 1 to enable the clock of the peripheral.

Example: Enable the LPUART0 clock, functional clock source is FIRC:

```c
/* make sure the LPUART transmit and receive activity are stopped */
/* ... */
PCC_LPUART0 &= ~PCC_CLKCFG_CGC_MASK; /* gate off LPUART0 */
PCC_LPUART0 = PCC_CLKCFG_PCS(3); /* select functional clock to be FIRC */
PCC_LPUART0 |= PCC_CLKCFG_CGC_MASK; /* enable clock */
```

**NOTE**

1. Not all PCC peripherals have the PCS field.

2. The PCS field can only be written when the CGC bit is 0 (clock disabled). Likewise, if the INUSE flag is set, this field is locked.

3. The peripheral interface clock can be either DIVSLOW_CLK or DIVCORE_CLK. See each peripherals PCC register in the reference manual for details.
5. SCG Clock Mode Transitions

5.1. SCG valid clock mode

The SCG clock mode switch is much easier than the old MCG module. The following figure shows the valid clock mode transitions supported by SCG.

![SCG Clock Mode Transitions Diagram]

Figure 4. SCG clock mode transition
Table 3 defines each of the SCG clock modes shown in the previous figure:

<table>
<thead>
<tr>
<th>Mode</th>
<th>Description</th>
</tr>
</thead>
</table>
| Slow Internal Reference Clock (SIRC) | Slow Internal Reference Clock (SIRC) mode is entered when all the following conditions occur: \ 
  * RUN MODE: 0010 is written to RCCR[SCS]. \ 
  * VLRUN MODE: 0010 is written to VCCR[SCS] and 1 is written to SIRCCSR[SIRCLPEN]. \ 
  * HSRUN MODE: 0010 is written to HCCR[SCS]. \ 
  * SIRCEN = 1 \ 
  * SIRCVLD = 1 \ 
  In SIRC mode, SCSCLKOUT and system clocks are derived from the slow internal reference clock. \ 
  * Two frequency ranges are available for SIRC clock as described in the SIRCCFG[RANGE] register definition. Changes to SIRC range settings will be ignored when SIRC clock is enabled. |
| Fast Internal Reference Clock (FIRC)  | Fast Internal Reference Clock (FIRC) mode is entered when all the following conditions occur: \ 
  * RUN MODE: 0011 is written to RCCR[SCS]. \ 
  * VLRUN MODE: Invalid mode. Programming SCG into FIRC mode will be ignored. \ 
  * HSRUN MODE: 0011 is written to HCCR[SCS]. \ 
  * FIRCVLD = 1 \ 
  * FIRCEN = 1 \ 
  In FIRC mode, SCSCLKOUT and system clocks are derived from the fast internal reference clock. \ 
  * Two frequency range settings are available for FIRC clock as described in the FIRC[RANGE] Register definition. Changes to FIRC range settings will be ignored when FIRC clock is enabled. |
| System Oscillator Clock (SOSC)     | System Oscillator Clock (SOSC) mode is entered when all the following conditions occur: \ 
  * RUN MODE: 0001 is written to RCCR[SCS]. \ 
  * VLRUN MODE: 0001 is written to VCCR[SCS]. \ 
  * HSRUN MODE: 0001 is written to HCCR[SCS]. \ 
  * SOSCEN = 1 \ 
  * SOSCVLD = 1 \ 
  In SOSC mode, SCSCLKOUT and system clocks are derived from the external System Oscillator Clock (SOSC). |
| Sys PLL (SPLL)                     | Sys PLL (SPLL) mode is entered when all the following conditions occur: \ 
  * RUN MODE: 0110 is written to RCCR[SCS]. \ 
  * VLRUN MODE: Invalid mode. Programming SCG into SPLL mode will be ignored. \ 
  * HSRUN MODE: 0110 is written to HCCR[SCS]. \ 
  * SPLLEN = 1 \ 
  * S PLLVLD = 1 \ 
  In SPLL mode, the SCSCLKOUT and system clocks are derived from the output of PLL which is controlled by either the System Oscillator (SOSC) clock or the Fast internal reference clock (FIRC). \ 
  * The selected PLL clock frequency locks to a multiplication factor, as specified by its corresponding VDIV, times the selected PLL reference frequency. The PLL’s programmable reference divider must be configured to produce a valid PLL reference clock. The SPLL input clock should be at range 8M-16 MHz. |
5.2. SCG clock mode transitions examples

Example 1: Switching to SIRC mode (system power mode = RUN, SIRC output = 8M):

```c
#define SCG_SIRC 2
uint32_t tmp;
SCG->SIRCCSR |= SCG_SIRCCSR_SIRCEN_MASK; /* enable SIRC */
while(0 == (SCG->SIRCCSR & SCG_SIRCCSR_SIRCVLD_MASK)); /* wait until ready and stable */
tmp = SCG->RCCR;
tmp &= ~SCG_RCCR_SCS_MASK;
tmp |= SCG_RCCR_SCS(SCG_SIRC);
SCG->RCCR = tmp;
While (SCG_SIRC != ((SCG_CSR_SCS_MASK & SCG_CSR) >> SCG_CSR_SCS_SHIFT)); /* wait for system mode switch */
```

**NOTE**

RCCR can only be written using a 32-bit write.

Example 2: Switching to FIRC mode (system power mode = RUN, FIRC output = 48M):

```c
#define SCG_FIRC 3
uint32_t tmp;
SCG->FIRCCSR |= SCG_FIRCCSR_FIRCEN_MASK; /* enable RIRC */
while(0 == (SCG->FIRCCSR & SCG_FIRCCSR_FIRCVLD_MASK)); /* wait until ready and stable */
tmp = SCG->RCCR;
tmp &= ~SCG_RCCR_SCS_MASK;
tmp |= SCG_RCCR_SCS(SCG_FIRC);
SCG->RCCR = tmp;
While (SCG_FIRC != ((SCG_CSR_SCS_MASK & SCG_CSR) >> SCG_CSR_SCS_SHIFT)); /* wait for system mode switch */
```
Example 3: Switching to SOSC mode (system power mode = RUN, external reference clock = 8M, SOSC output = 8 MHz):

#define SCG_SOSC 1
uint32_t tmp;
SCG->SOSCCFG &= ~SCG_SOSCCFG_RANGE_MASK;
SCG->SOSCCFG |= SCG_SOSCCFG_RANGE(2) | SCG_SOSCCFG_EREFS_MASK;
SCG->SOSCCSR |= SCG_SOSCCSR_SOSCCEN_MASK; /* enable SOSC */
while(0 == (SCG->SOSCCSR & SCG_SOSCCSR_SOSCCVLD_MASK)); /* wait until ready and stable */
tmp = SCG->RCCR;
tmp &= ~SCG_RCCR_SCS_MASK;
tmp |= SCG_RCCR_SCS(SCG_SOSC);
SCG->RCCR = tmp;
While (SCG_SOSC != ((SCG_CSR_SCS_MASK & SCG_CSR) >> SCG_CSR_SCS_SHIFT)); /* wait for system mode switch */

Example 4: Switching to SPLL mode (system power mode = RUN, SPLL source is FIRC, SPLL output = 72M):

#define SCG_SPLL 6
/* make sure FIRC is functional */
/* ... */
/* SPLL source = FIRC, mult=2, prediv=6, SPLL output = 48/(6)*18/2 = 72M */
SCG->SPLLCFG = SCG_SPLLCFG_SOURCE(1) | SCG_SPLLCFG_MULT(2) |SCG_SPLLCFG_PREDIV(5);
SCG->SPLLCSR |= SCG_SPLLCSR_SPLLEN; /* enable SPLL */
while(0 == (SCG->SPLLCSR & SCG_SPLLCSR_SPLLVLD_MASK)); /* wait for ready */
tmp = SCG->RCCR;
tmp &= ~SCG_RCCR_SCS_MASK;
tmp |= SCG_RCCR_SCS(SCG_SPLL);
SCG->RCCR = tmp;
While (SCG_SPLL != ((SCG_CSR_SCS_MASK & SCG_CSR) >> SCG_CSR_SCS_SHIFT)); /* wait for system mode switch */
NOTE

1. The input range of SPLL is 8 – 32 MHz

2. SPLL has an output divider (/2) inside by default. So the final SPLL output = ((input clock / preDiv) * mult) / 2

Example 5: Switching to SPLL mode (system power mode = RUN, SPLL source is SOSC, SOSC = 8 MHz, SPLL output = 72M):

```c
#define SCG_SPLL 6
#define SCG_SOSC 1

/* make sure SOSC is enabled and functional */

/* ... */

/* SPLL source = SOSC, mult=2, prediv=1, SPLL output = 8/(1)*18/2 = 72M */

SCG->SPLLCFG = SCG_SPLLCFG_SOURCE(0) | SCG_SPLLCFG_MULT(2) | SCG_SPLLCFG_PREDIV(0);

SCG->SPLLCR |= SCG_SPLLCR_SPLLEN; /* enable SPLL */

while(0 == (SCG->SPLLCR & SCG_SPLLCR_SPLLVLD_MASK)); /* wait for ready */

tmp = SCG->RCCR;

tmp &= ~SCG_RCCR_SCS_MASK;

tmp |= SCG_RCCR_SCS(SCG_SPLL);

SCG->RCCR = tmp;

While (SCG_SPLL != ((SCG_CSR_SCS_MASK & SCG_CSR) >> SCG_CSR_SCS_SHIFT)); /* wait for system mode switch */
```

5.3. SCG configuration in HSRUN and VLPR mode

Configuring SCG for HSRUN and VLPR is just as easy as in RUN mode. However the user needs to pay attention to the clock limitation, as explained in Table 4:

<table>
<thead>
<tr>
<th>Clock Mode</th>
<th>Available SCG Source</th>
<th>Clock Limitation</th>
</tr>
</thead>
<tbody>
<tr>
<td>HSRUN</td>
<td>SOSC, SPLL SIRC, FIRC</td>
<td>DIVCORE 96 MHz max</td>
</tr>
<tr>
<td>VLPR</td>
<td>SOSC, SIRC</td>
<td>DIVCORE 8 MHz max</td>
</tr>
</tbody>
</table>

SCG has a separate clock control register for RUN/HSRUN/VLPR mode; making it easier for the user to switch between those modes.
To enter HSRUN/VLPR, perform the following steps:

1. Configure the SCG clock source as per the normal RUN mode
2. Configure the SCG’s RCCR/VCCR/HCCR according to the mode that you want to enter
3. Configure the System Mode Controller (SMC) to enter the specific RUN mode
4. Read SMC->PMSTAT register to check the current system mode

Example: Switching to SPLL mode (system power mode = HSRUN, SPLL source is SOSC, SOSC = 8 MHz, SPLL output = 96M, while LPUART functional clock is SOSC):

```c
#define SCG_SPLL 6
#define SCG_SOSC 1
/* make sure SOSC is enabled and functional */
/* ... */

/* SPLL source = SOSC, mult=8, prediv=1, SPLL output = 8/(1)*24/2 = 96M */
SCG->SPLLCFG = SCG_SPLLCFG_SOURCE(0) | SCG_SPLLCFG_MULT(8) |
               SCG_SPLLCFG_PREDIV(0);
SCG->SPLLCSR |= SCG_SPLLCFG_SPLLEN; /* enable SPLL */
while(0 == (SCG->SPLLCSR & SCG_SPLLCFG_SPLLVLD_MASK)); /* wait for ready */
tmp = SCG->HCCR;
tmp &= ~SCG_HCCR_SCS_MASK;
tmp |= SCG_HCCR_SCS(SCG_SPLL);
SCG->HCCR = tmp;
while(SCG_SPLL != ((SCG_CSR_SCS_MASK & SCG_CSR) >> SCG_CSR_SCS_SHIFT)); /* wait for system mode switch */

/* enter HSRUN */
SMC->PMPROT |= SMC_PMPROT_AHSRUN_MASK;
SMC->PMCTRL |= SMC_PMCTRL_RUNM(3);
while((SMC->PMSTAT & 0x80) == 0);

/* set LPUART source to be SOSC */
PCC_LPUART0 &= ~PCC_CLKCFG_CGC_MASK;
PCC_LPUART0 = PCC_CLKCFG_PCS(SCG_SOSC);
PCC_LPUART0 |= PCC_CLKCFG_CGC_MASK;
```
5.4. Clock configuration in STOP mode

Many clock sources in SCG mode can be functional in various STOP modes. Each clock source has a stop enable bit in their control register, Table 5 details each clock’s behavior in STOP mode.

Table 5. Different clock source supported in STOP mode

<table>
<thead>
<tr>
<th>Modules</th>
<th>STOP</th>
<th>VLPS</th>
<th>LLSx</th>
<th>VLLSx</th>
</tr>
</thead>
<tbody>
<tr>
<td>SCG</td>
<td>SOSC SIRC FIRC SPLL can be enabled</td>
<td>SOSC SIRC can be enabled</td>
<td>SOSC can be enabled</td>
<td>SOSC can be enabled</td>
</tr>
</tbody>
</table>

Table 6 describes how to enable each clock source in STOP mode.

Table 6. How to enable clock in STOP mode

<table>
<thead>
<tr>
<th>SCG clock source</th>
<th>How to enable clock in STOP mode</th>
</tr>
</thead>
<tbody>
<tr>
<td>SIRC</td>
<td>SIRCCLK is available in Normal Stop and VLPS mode when all the following conditions become true: SIRCCSR[SIRCEN] = 1 SIRCCSR[SIRCSTEN] = 1 SIRCCSR[SIRCEN] = 1 in VLPS</td>
</tr>
<tr>
<td>FIRC</td>
<td>FIRCCLK is available only in Normal Stop mode when all the following conditions become true: FIRCCSR[FIRCEN] = 1 FIRCCSR[FIRCESTEN] = 1</td>
</tr>
<tr>
<td>SOSC</td>
<td>SOSCLK is available in following low power stop modes (Normal Stop, VLPS, LLS) when all the Below conditions are true. In VLLS stop mode, SOSCLK is disabled. SOSCCSR[SOSCEN] = 1 SOSCCSR[SOSCSTEN] = 1 SOSCCSR[SOSCLPEN] = 1 (required only for Low Power Stop modes (VLPS and LLS))</td>
</tr>
<tr>
<td>SPLL</td>
<td>SPLLCLK is available in Normal Stop mode when all the following conditions are true: SPLLCUR[SPLLEN] = 1 SPLLCUR[SPLLESTEN] = 1</td>
</tr>
</tbody>
</table>

6. References

The following references are available on nxp.com:

- KL28 Data Sheet

7. Revision History

Table 7. Revision history

<table>
<thead>
<tr>
<th>Revision number</th>
<th>Date</th>
<th>Substantive changes</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>06/2016</td>
<td>Initial release</td>
</tr>
</tbody>
</table>
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