

Freescale Semiconductor

APR22/D

Application Conversion from the DSP56100 Family to the DSP56300/600 Families

by Tom Zudock





How to Reach Us:

Home Page:

www.freescale.com

E-mail:

support@freescale.com

USA/Europe or Locations Not Listed:

Freescale Semiconductor Technical Information Center, CH370 1300 N. Alma School Road Chandler, Arizona 85224 +1-800-521-6274 or +1-480-768-2130 support@freescale.com

Europe, Middle East, and Africa:

Freescale Halbleiter Deutschland GmbH Technical Information Center Schatzbogen 7 81829 Muenchen, Germany +44 1296 380 456 (English) +46 8 52200080 (English) +49 89 92103 559 (German) +33 1 69 35 48 48 (French) support@freescale.com

Japan:

Freescale Semiconductor Japan Ltd. Headquarters ARCO Tower 15F 1-8-1, Shimo-Meguro, Meguro-ku, Tokyo 153-0064 Japan 0120 191014 or +81 3 5437 9125 support.japan@freescale.com

Asia/Pacific:

Freescale Semiconductor Hong Kong Ltd.
Technical Information Center
2 Dai King Street
Tai Po Industrial Estate
Tai Po, N.T., Hong Kong
+800 2666 8080
support.asia@freescale.com

For Literature Requests Only:

Freescale Semiconductor Literature Distribution Center P.O. Box 5405
Denver, Colorado 80217
1-800-441-2447 or 303-675-2140
Fax: 303-675-2150
LDCForFreescaleSemiconductor@hibbertgroup.com

Information in this document is provided solely to enable system and software implementers to use Freescale Semiconductor products. There are no express or implied copyright licenses granted hereunder to design or fabricate any integrated circuits or integrated circuits based on the information in this document. Freescale Semiconductor reserves the right to make changes without further notice to any products herein. Freescale Semiconductor makes no warranty, representation or any products neight. Fleescale Semiconductor makes no warranty, representation or guarantee regarding the suitability of its products for any particular purpose, nor does Freescale Semiconductor assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters which may be provided in Freescale Semiconductor data sheets and/or specifications can and do vary in different applications and actual performance may vary over time. All operating parameters, including "Typicals" must be validated for each customer application by customer's technical experts. Freescale Semiconductor does not convey any license under its patent rights nor the rights of others. Freescale Semiconductor products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which the failure of the Freescale Semiconductor product could create a situation where personal injury or death may occur. Should Buyer purchase or use Freescale Semiconductor products for any such unintended or unauthorized application, Buyer shall indemnify and hold Freescale Semiconductor and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claim alleges that Freescale Semiconductor was negligent regarding the design or manufacture of the part.





TABLE OF CONTENTS

SECTIO	ON 1	INTRODUCTION	1-1
1.1			
1.2	TERMS	AND DEFINITIONS	1-2
SECTIO	ON 2	DSP56100 AND DSP56300/ DSP56600 DIFFERENCES	2-1
2.1	ARCHIT	ECTURE	
2.1.1		ory Organization	
2.1.2		Arithmetic Logic Unit (Data ALU)	
2.1.3		ware Stack	
2.2		SSING MODES	
2.3		ICTION SET	
SECTIO)N 3	SOFTWARE CONVERSION	3-1
3.1	CONVE	RTING UNSUPPORTED INSTRUCTIONS	3-2
3.2	INSTRU	ICTION TRANSLATIONS	3-2
3.2.1	ASL4	I, ASR4, ASR16	3-3
3.2.2	BFCI	HG	3-3
3.2.3	BFCI	_R	3-4
3.2.4	BFSE	ET	3-5
3.2.5	BFTS	STH	3-6
3.2.6	BFTS	STL	3-7
3.2.7	CHK	AAU	3-8
3.2.8	DEC	24	3-8
3.2.9	EXT		3-8
3.2.10	IMAC	C, IMPY	3-9
3.2.11	INC2	4	3-10
3.2.12	MAC	, MACR, MPY, and MPYR with MSP as Source .	3-10
3.2.13	NEG	C	3-11
3.2.14	REP	CC	3-11



3.2.15	SWAP
3.2.16	SWI
3.2.17	TFR of an entire DALU register
3.2.18	TFR2
3.2.19	TFR3
3.2.20	TST2
3.2.21	ZERO
3.2.22	Immediate Short Data
	EMULATIONS ISSUES SPECIFIC TO THE DSP566003-15
3.3.1	NORM Rn,D



LIST OF TABLES

Table 2-1	Comparison of DSP56100 and DSP56300/600 Addressing Modes	2-4
Table 2-2	DSP56100, DSP56300, and DSP56600 Instruction Set Differences	2-6





SECTION 1 INTRODUCTION

This document summarizes information needed by a user to estimate the effort required to convert an application from the DSP56100 to the DSP56300/600 and the details involved in translating the software.



ıntroduction

Scope

1.1 SCOPE

The Motorola DSP56100 family and DSP56300/600 families are similar in many ways, but the parts are not fully compatible. Hence, using a DSP56300/600 in place of a DSP56100 requires modification to the software and the hardware. This document summarizes information needed by a user to estimate the effort required to convert an application and the details involved in translating the software

There are many compatibility issues that are beyond the scope of this document. This document focuses on differences that relate to software translation. Attempting to include all the differences would distract from this intent. For details on any aspect not included in this document, please refer to the DSP56100, DSP56300, and DSP56600 family manuals. For details on peripherals or specifics for a given part in the family, refer to the manual or data sheet for the DSP product of interest (e.g., DSP56302, DSP56303, DSP56603, etc.).

1.2 TERMS AND DEFINITIONS

Definitions for abbreviations or acronyms used throughout the document are provided in the following list.

AGU	Address Generation Unit
CCR	Condition Code Register
Data ALU	Data Arithmetic Logic Unit
DSP	Digital Signal Processor
LSP	Least Significant Portion
I/O	Input/Output
MIPS	Million Instructions Per Second
MSP	Most Significant Portion
RAM	Random Access Memory
ROM	Read Only Memory
SR	Status Register



ıntroduction

Terms and Definitions

dsp



introduction

Terms and Definitions



SECTION 2 DSP56100 AND DSP56300/DSP56600 DIFFERENCES

The primary difference in architecture between the DSP56100 and the DSP56300/600 families lies in the organization of data memory.



DSP56100 and DSP56300/DSP56600 Differences

Architecture

Although there are more similarities than differences between the DSP56100 and the DSP56300/600 families, some of the differences are fundamental and require careful attention. In this section, the differences are organized into three categories: the architecture, the addressing modes, and the instruction set. A brief examination of these categories will help an engineer estimate the amount of effort that will be required to translate an application.

2.1 ARCHITECTURE

2.1.1 Memory Organization

The primary difference in architecture between the DSP56100 and the DSP56300/600 families lies in the organization of data memory. DSP56100 family parts have a single data memory, X memory, that supports dual accessed reads. In the DSP56300/600 family, data memory is divided into X and Y memory, which can be simultaneously read or written. Since the DSP56300/600 does not allow dual read access to X or Y memory *individually*, dual accesses to X memory in the DSP56100 software must be split into accesses to X memory in parallel with accesses to Y memory.

The instruction width on the DSP56300/600 is 24 bits as opposed to 16 bits on the DSP56100. If an application will require external RAM, the larger width of the instructions must be accounted for in the external RAM. If the final application will reside internal on ROM implementations, this is of little consequence.

2.1.2 Data Arithmetic Logic Unit (Data ALU)

The DSP56100 is a 16-bit machine while the DSP56300 is a 24-bit machine. To generate bit-exact output using a DSP56300 family part, 16-bit Arithmetic mode must be used. All of the code examples in this document assume that if the DSP56300 is the target, it will be executing the code in 16-bit Arithmetic mode. The DSP56600 is a 16-bit machine, so this is not an issue.

Although Data ALUs provide the same register set, they differ in some of the mathematical operations they provide. The DSP56100 Data ALU allows the Most Significant Portion (MSP) of the accumulator to be used as an argument for an integer multiply accumulate, whereas the DSP56300/600 does not. Shifting capabilities also differ. The DSP56100 provides single bit shifting and shifting in larger fixed increments (ASR4, ASR16, ASL4). The DSP56300/600 Data ALU includes



DSP56100 and DSP56300/DSP56600 Differences

Addressing Modes

a barrel shifter, which allows shifting in any increment over the range of the accumulator size. This also provides single cycle normalization, which is useful for maintaining dynamic range efficiently. Finally, the DSP56100 supports bit-field operations with immediate data. On the DSP56300/600, this must be performed using logical ANDs, ORs, or individual bit-position operations (i.e., BCLR).

2.1.3 Hardware Stack

Both processor families provide a hardware stack to support nested DO loops, subroutine calls, and interrupt processing. On the DSP56100, the stack is fifteen levels deep while the DSP56300/600 provides sixteen levels. Additionally, the DSP56300/600 supports stack extension. Because the DSP56300/600 provides substantially more (Million Instructions Per Second) MIPS, it is possible that applications executed on a single DSP56300/600 will be the consolidation of multiple single DSP applications. This may result in a need for a single DSP56300/600 to support more interrupts and increasingly complex software. Often, this software requires more stack space. Stack extension fills that void.

2.2 ADDRESSING MODES

Although there are several subtle differences between the AGUs, the DSP56100 addressing mode that will need the most attention for conversion is upper word accumulator addressing (e.g., X:(A1) or X:(B1)). As due compensation for lack of this addressing mode, the DSP56300/600 has twice as many address register sets, eight total. In the majority of cases (those using simple integer addition), an extra address register provides a simple solution.

One distinct advantage of the DSP56300/600 is that it allows more address register combinations for parallel memory accesses. When performing a parallel read on the DSP56100, one of the address registers is required to be R3. On the DSP56300/600, any of the R0–R3 registers may be used in parallel memory accesses with any of the R4–R7 registers. The DSP56300/600 additionally supports multiple wrap around modulo addressing. In this mode, if an index offset is used that is larger than the buffer modulus (as dictated by the value in the Mn register), the address is properly calculated as having wrapped around multiple times.

The table below summarizes differences in the addressing modes. It is a combination of the tables taken from the DSP56100 and DSP56300/600 family manuals. Check the notes below the table for a full description. The table clearly indicates that there are far more new options with DSP56300/600 addressing modes (marked with an N)



DSP56100 and DSP56300/DSP56600 Differences

Addressing Modes

than those that are unsupported (marked with a U). The modes common to both are marked with B. Hence, there are sufficient options on the DSP56300/600 to work around the unsupported DSP56100 addressing modes.

Table 2-1 Comparison of DSP56100 and DSP56300/600 Addressing Modes

Addressing Mode		Operand Reference						Syntax			
	s	С	D	A	P	X	Y	L	XY	xx	_
Register Direct		•	•	•			•				
Data or Control Register	U	В	В	_	_	_	_	_	_	_	_
Address Register Rn	_		_	В	_	_	_	_	_	_	_
Address Modifier Register Mn	_	_	U	N	_	_	_	_		_	_
Address Offset Register Nn	_	_	_	В	_	_	_	_		_	_
Address Register Indirect											
No Update	_	_	_	_	В	В	N	N	N	_	(Rn)
Postincrement by 1	_	_	_	_	В	В	N	N	N	U	(Rn)+
Postdecrement by 1	_				В	В	N	N	N	_	(Rn)–
Postincrement by Offset Nn	_		_		В	В	N	N	N	U	(Rn) + Nn
Postdecrement by Offset Nn	_		_	_	N	N	N	N	_	_	(Rn) – Nn
Indexed by Offset Nn	_				N	В	N	N		_	(Rn + Nn)
Predecrement by 1	_		_		N	В	N	N	_	_	–(Rn)
Short Displacement	_		_	_	_	В	N	N	_	_	(Rn + displ)
Long Displacement	_		_	_	_	N	N	N	_	_	(Rn + displ)
PC Relative	_		_		_			_		_	
Short Displacement PC Relative	_	U	_	_	В	_	_	_		_	(PC + displ)
Long Displacement PC Relative	_	U	_	_	N	_	_	_		_	(PC + displ)
Address Register	_	U	_	U	N	_	_	_		_	(PC + Rn)
Special											



DSP56100 and DSP56300/DSP56600 Differences

Instruction Set

Table 2-1 Comparison of DSP56100 and DSP56300/600 Addressing Modes (Continued)

Addressing Mode		Operand Reference						Syntax			
	s	С	D	A	P	X	Y	L	XY	xx	_
Upper Word Accumulator	_	_	_	_	_	U	_	_		_	
Immediate Short Data	_				В	_			_	_	_
Immediate Long Data	-		_	_	В		_	_	_	_	_
Absolute Address	_				В	В	N	N	_		_
Absolute Short Address	_				U	В	N	N	_	_	_
Short Jump Address	-		_	_	В		_	_	_	_	_
I/O short Address			_			В	N	_			_
Implicit	В	В		_	В			_	_		_

Note:

- S = System Stack Reference
- C = Program Control Unit Register Reference
- D = Data ALU Register Reference
- A = Address ALU Reference
- P = Program Memory Reference
- X = X Memory Reference
- Y = Y Memory Reference
- L = L Memory Reference
- XY = XY Memory Reference
- XX = XX Memory Reference
- U = Unsupported by DSP56300/600
- B = Supported by both the DSP56100 and the DSP56300/600
- N = New on DSP56300/600 or unsupported by the DSP56100

2.3 INSTRUCTION SET

Translating DSP56100 software requires replacing unsupported instructions with their DSP56300/600 equivalents. Additionally, some instructions supported on both processors should be replaced with more efficient DSP56300/600 versions. For



DSP56100 and DSP56300/DSP56600 Differences

Instruction Set

example, repeated shift operations can be replaced by an instruction that uses the barrel shifter.

The table that follows summarizes the differences in the instruction sets of all three processors. The left column contains instructions that will need to be converted to DSP56300/600 equivalents, while the right column shows additional instructions provided by the DSP56300/600. Footnotes indicate additional information regarding specific instructions.

Table 2-2 DSP56100, DSP56300, and DSP56600 Instruction Set Differences

DSP56100 Instructions Unsupported or Modified by the DSP56300/600	Instructions Added by Using the DSP56300/600
ADC ¹	
	ADDL
	ADDR
ASL4	
ASR4	
ASR16	
	BCHG
	BCLR
BFCHG	
BFCLR	
BFSET	
BFTSTH	
BFTSTL	
	BRCLR ²
	BRSET ²

Instruction Set

Table 2-2 DSP56100, DSP56300, and DSP56600 Instruction Set Differences

DSP56100 Instructions Unsupported or Modified by the DSP56300/600	Instructions Added by Using the DSP56300/600
	BSCLR ²
	BSET
	BSSET ²
	BTST
	CLB
СНКААИ	
CLR24	
DEC ¹	
DEC24	
DIV ¹	
	DOR ²
	DOR FOREVER ²
EXT	
	EXTRACT
	EXTRACTU
	IFcc
	IFcc.U
IMAC	
IMPY	
INC24	
	INSERT
	JCLR



DSP56100 and DSP56300/DSP56600 Differences

Instruction Set

 Table 2-2
 DSP56100, DSP56300, and DSP56600 Instruction Set Differences

DSP56100 Instructions Unsupported or Modified by the DSP56300/600	Instructions Added by Using the DSP56300/600
	JSCLR
	JSET
	JSSET
	LRA
MAC ³	
MACR ³	
	MACI
	MACRI
	MAX
	MAXM
	MERGE
MOVE X: X:	
	MOVE Y:
	MOVE Y: R:
	MOVE L:
	MOVE X: Y:
MPY ³	
MPYR ³	
	MPYI
	MPYIR
NEG ⁴	
NEGC	



DSP56100 and DSP56300/DSP56600 Differences

Instruction Set

Table 2-2 DSP56100, DSP56300, and DSP56600 Instruction Set Differences

DSP56100 Instructions Unsupported or Modified by the DSP56300/600	Instructions Added by Using the DSP56300/600
NORM ²	
	NORMF
	PFLUSH ²
	PFLUSHUN ²
	PFREE ²
	PLOCKR ²
	PUNLOCK ²
	PUNLOCKR ²
REPcc	
	SUBR
SWAP	
SWI	
TFR(2)	
TFR(3)	
	TRAP
	TRAPcc
TST(2)	
ZERO	

Note: 1. The DSP56300/600 does not allow a parallel move with this instruction.

- 2. The DSP56600 does not support this instruction.
- 3. Some registers are not supported as arguments for this instruction on the DSP56300/600.
- 4. CCR behavior is not identical on both the DSP56100 and the DSP56300/600.



DSP56100 and DSP56300/DSP56600 Differences

Instruction Set

dsp



SECTION 3 SOFTWARE CONVERSION

This section examines unsupported DSP56100 instructions and provides a functionally equivalent DSP56300/600 solution.



Software Conversion

Converting Unsupported Instructions

3.1 CONVERTING UNSUPPORTED INSTRUCTIONS

Converting unsupported instructions is the primary focus of the code conversion effort. The approach taken is to maintain the functionality of the DSP56100 software rather than fully emulate the unsupported DSP56100 instructions. *This will maintain efficiency, but requires the software engineer to examine the code being translated.* Globally replacing unsupported instructions with complete emulations would yield inefficient software and emulate aspects of an unsupported instruction not required by the DSP56100 code being converted.

As stated earlier in this document, all DSP56300 code portions must be executed with the DSP56300 in 16-bit Arithmetic mode.

3.2 INSTRUCTION TRANSLATIONS

This section examines unsupported DSP56100 instructions and provides a functionally equivalent DSP56300/600 solution. The intent is provide solutions for the typical use of the DSP56100 instruction rather than support complete emulation (e.g., emulating all the condition codes). In short, the exact behavior of all the registers and condition codes is not exactly duplicated in many cases. All of the emulation code is written in macro form.

Since macros accept arguments, they are useful for instances in which different arguments are used for the same instruction that needs to emulated. *None of the macros preserve registers that are destroyed performing the emulation*. This approach was chosen because it may introduce unnecessary inefficiency. For instance, the registers used may be available. The software engineer may easily remedy this, if desired, by using push and pop macros with a user-defined stack.

The software conversion engineer has options on how these emulation macros may be used. First, they may be used directly in place of the unsupported instruction. This will be the most inefficient approach, but it will require the minimum effort by the software engineer. Second, they may serve as guides on the functionality that needs to be supported to translate an instruction. The software engineer may then use a variation of the emulation macro that is most efficient for that particular section of code.



Instruction Translations

3.2.1 ASL4, ASR4, ASR16

These DSP56100 instructions perform arithmetic shifts on an accumulator by fixed amounts. The DSP56300/600 macro uses an immediate data value argument to perform the desired shift.

```
Registers Destroyed: None
     MACRO D
∆ST.4
     ASL #4,D,D ; Shift accum left 4 bits
     FNDM
;*****************
     Registers Destroyed: None
ASR4
     MACRO D
     ASR #4,D,D ; Shift accum right 4 bits
     ENDM
; ********************
:*****************
     Registers Destroyed: None
     MACRO D
ASR16
     ASR #16,D,D ; Shift accum right 16 bits
```

3.2.2 BFCHG

This DSP56100 instruction performs a test and change on bits specified by an 8-bit mask. The DSP56300/600 macro will correctly perform the bit changes. *Care has not been taken to maintain the condition code behavior.*

If the mask itself only specifies changing one bit, this macro may be largely improved by using a BCHG instruction. *Note that the BCHG instruction takes a bit position as an argument rather than the bit mask.* The macro that follows is challenging to read since it



Software Conversion

Instruction Translations

contains many assembler functions and directives to convert the bit mask to a bit position. An example of the resulting instruction is provided for clarification. *The C bit is correctly calculated by this macro*.

3.2.3 **BFCLR**

This DSP56100 instruction clears the bits in a destination operand specified by an 8-bit mask. The DSP56300/600 macro will correctly perform the bit clearing. *Care has not been taken to maintain the condition code behavior.*

This macro may be shortened if additional care is taken when using the macro. For instance, if the MASK argument contains the forcing operator, then the move to R7 is not needed to ensure integer alignment of the data. The first move would be of the MASK to A.

If the mask itself only specifies clearing one bit, this macro may be further improved by using a BCLR instruction. *Note that the BCLR instruction takes a bit position as an argument rather than the bit mask.* The macro that follows is challenging to read since it contains many Assembler functions and directives to convert the bit mask to a bit



Instruction Translations

position. An example of the resulting instruction is provided for clarification. *The C bit behaves in the opposite fashion of that on the DSP56100*. If the software following the macro depends upon the state of the C bit, the conditional behavior needs to be inverted (i.e., convert a BCS to BCC).

3.2.4 BFSET

This DSP56100 instruction sets the bits in a destination operand specified by an 8-bit mask. The DSP56300/600 macro will correctly perform the bit setting. *Care has not been taken to maintain the condition code behavior*.

If the mask itself only specifies clearing one bit, this macro may be improved by using a BSET instruction. *Note that the BSET instruction takes a bit position as an argument rather than the bit mask.* The macro that follows is challenging to read since it contains many Assembler functions and directives to convert the bit mask to a bit position. An example of the resulting instruction is provided for clarification. *The C bit is correctly calculated by this macro.*

```
;*******
; Registers Destroyed: None
BFSET_1 MACRO MASK,D
    DEFINE MVAL ["MASK",1,@LEN("MASK")]; Strip off # character
    BSET #@CVI(@L10(MVAL)/@L10(2)),D ; Convert to bit pos and use
    UNDEF MVAL
```



Software Conversion

Instruction Translations

3.2.5 BFTSTH

This DSP56100 instruction tests the bits in a destination operand specified by an 8-bit mask and sets the C bit of the Status Register (SR) if all of the bits in the destination operand were set. Otherwise the C bit is cleared. *This DSP56300/600 macro only maintains the functionality of the C bit since that is the most likely usage of this instruction.*

```
Registers Destroyed: A1
BFTSTH MACRO MASK,D
             D,A
                           ; Move target to accum
      TFR
      AND MASK, A
                           ; Clear bits not set in mask
      EOR MASK,A
                           ; Clear bits set in mask, z=1 if all cleared
      ANDI #$FE,CCR
                          ; Optional - Clear the C flag
              _EXIT
      BNE
                           ; Optional - If Z flag not set, exit
                         ; Optional - If Z flag set, set C flag
             #$01,CCR
      ORI
EXIT
      ENDM
```

This macro may be improved if the user may utilize the Z bit of the Condition Code Register (CCR). Since the last three instructions of the macro use the state of the Z bit to set the C bit, they may be potentially dropped if the state of the Z bit is used (i.e., for a conditional change of flow following the instruction).

If the mask itself only specifies testing one bit, this macro may be further improved by using a BTST instruction. *Note that the BTST instruction takes a bit position as an argument rather than the bit mask.* The macro that follows is challenging to read since it contains many Assembler functions and directives to convert the bit mask to a bit position. An example of the resulting instruction is provided for clarification. *The C bit is correctly calculated by this macro.*



Instruction Translations

3.2.6 BFTSTL

This DSP56100 instruction tests the bits in a destination operand specified by an 8-bit mask and sets the C bit of the SR if all of the bits in the destination operand were clear. Otherwise the C bit is cleared. *This DSP56300/600 macro only maintains the functionality of the C bit since that is the most likely usage of this instruction*.

```
Registers Destroyed: Al
BFTSTL MACRO MASK, D
       TFR D,A
                           ; Move target to accum
       NOT A AND MASK, A
                           ; Invert the target
       AND MASK,A ; Clear bits not set in mask

EOR MASK,A ; Clear bit set in mask, z=1 if all cleared

ANDI #$FE,CCR ; Optional - Clear the C flag

ENTE : Optional - If 7 flag not set exit
                           ; Clear bits not set in mask
       BNE
              _EXIT
                            ; Optional - If Z flag not set, exit
                          ; Optional - If Z flag set, set C flag
       ORI #$01,CCR
EXIT
       ENDM
```

This macro may be improved if the user may utilize the Z bit of the CCR. Since the last three instructions of the macro use the state of the Z bit to set the C bit, they may be potentially dropped if the state of the Z bit is used (i.e., for a conditional change of flow following the instruction).

If the mask itself only specifies testing one bit, this macro may be further improved by using a BTST instruction and an additional BCHG instruction. *Note that the BTST instruction takes a bit position as an argument rather than the bit mask.* The macro that follows is challenging to read since it contains many Assembler functions and directives to convert the bit mask to a bit position. An example of the resulting instruction is provided for clarification. *The C bit behaves in the opposite fashion of that on the DSP56100.* If the software following the macro depends upon the state of the C bit, the conditional behavior needs to be inverted (i.e., convert a BCS to BCC).



Software Conversion

Instruction Translations

3.2.7 **CHKAAU**

This DSP56100 instruction affects the N, Z, and V bits of the SR based upon the result of the address register calculation. On the DSP56300/600, a simple testing of the resulting value will *handle the N and Z bits only*.

3.2.8 **DEC24**

This DSP56100 instruction decrements by one the MSP of the accumulator specified. The DSP56300/600 macro is self explanatory.

3.2.9 **EXT**

This DSP56100 instruction sign extends the MSP of the specified accumulator. The DSP56300/600 macro achieves the same result through arithmetic shifts.



Instruction Translations

3.2.10 IMAC, IMPY

These DSP56100 instruction perform integer multiply accumulate and integer multiply. The DSP56300/600 macros perform the calculation including the sign extension of the result.

```
;*****************
      Registers Destroyed: LSP specified by argument D
IMAC
      MACRO S1,S2,D
            #15,D,D
      ASR
                        ; LSP = fract val
      MAC
            S1,S2,D
                        ; A = S1*S2+A in fract form
      ASR
                         ; A = S1*S2+A int form
      MOVE D\0,D
                        ; Truncate and sign extend result
;*******************
      Registers Destroyed: LSP specified by argument D
IMPY
      MACRO S1,S2,D
           S1,S2,D
      MPY
                        ; A = S1*S2+A in fract form
      ASR D
                        ; A = S1*S2+A int form
           D \setminus 0, D
                        ; Truncate and sign extend result
      MOVE
```

The IMAC and IMPY DSP56100 instructions support the MSP of the accumulator as a source argument. Hence, the above macros may be modified to move the accumulator source to a temporary register to be used in the DSP56300/600 MAC or MPY instructions. The macro requires that the user specify the temporary Data ALU register to be used so that it does not conflict with the second Data ALU included in the original IMAC or IMPY instruction.

```
;*******
; Registers Destroyed: Specified by TMP argument

IMAC_AS MACRO    S1,S2,D,TMP
         MOVE    S1,TMP
         ASR    #15,D,D    ; LSP = fract val
         MAC    TMP,S2,D     ; A = S1*Y0+A in fract form
         ASR    D     ; A = S1*Y0+A int form
         MOVE    D\0,D     ; Truncate and sign extend result
```



Software Conversion

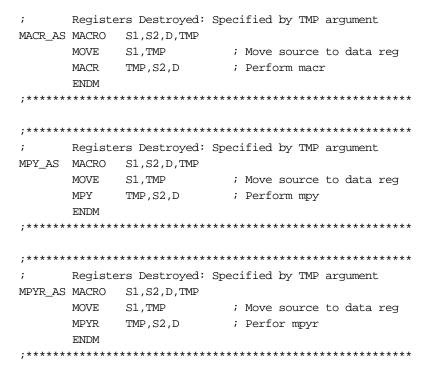
Instruction Translations

3.2.11 INC24

This DSP56100 instruction increments the MSP of the specified accumulator. The function of the macro is self-evident.

3.2.12 MAC, MACR, MPY, and MPYR with MSP as Source

The DSP56100 allowed the MSP of an accumulator to be used as a source for the MAC, MACR, MPY, and MPYR instructions. Supporting them simply requires moving the source accumulator to a temporary Data ALU register just prior to the original DSP56100 instruction. The user must specify the temporary Data ALU register used so that it does not conflict with second source in the original DSP56100 instruction.



3.2.13 **NEGC**

This DSP56100 instruction performs the mathematical function of 0-C-D (zero minus the Carry bit minus the accumulator value). The DSP56300/600 macro achieves this by testing the C bit and incrementing it before the negation.

3.2.14 REPcc

This DSP56100 instruction repeated an instruction until the specified condition code (cc) was true. *Translating this instruction should be carefully considered due to the*



Software Conversion

Instruction Translations

repetitive nature of the instruction. Perhaps the most common form is REPNR. Such instances should use CLB and NORMF for fast normalization on the DSP56300/600. Other uses should be examined for efficient implementation using the DSP56300/600 instruction set. For completeness, a general purpose DSP56300/600 macro follows, but is considerably more inefficient. Using the macro requires the condition be specified, as well as the instruction to be repeated. Since most instructions have more than one field, quotes will be required for the instruction argument.

```
;********
; Registers Destroyed: None

REPcc MACRO CC,INSTR

DO FOREVER,_LOOP; Do forever

BRK\CC; End the do if the condition is true

INSTR; Execute the instruction to repeat

NOP; NOP required for BRKcc near end of DO

NOP; NOP required for BRKcc near end of DO

LOOP

ENDM;
```

An improvement that is not simply converted into a macro, but may be utilized, involves using a conditional branch on the *opposite* condition code. For instance, if the original form was REPNE, the repeated instruction could be followed by a BREQ that branches back to the instruction to be repeated. When the condition is satisfied, the branch will not occur.

3.2.15 SWAP

This DSP56100 instruction simply swaps the MSP and LSP of the specified accumulator. The DSP56300/600 macro uses a Data ALU register as an intermediate location while the words are being swapped. The user may choose to use another less often used register for temporary storage.



Instruction Translations

3.2.16 SWI

This DSP56100 instruction initiates SWI exception processing. The equivalent DSP56300/600 processing is the TRAP instruction as shown in the macro.

3.2.17 TFR of an entire DALU register

This DSP56100 allows a transfer of the entire X or Y Data ALU register to an accumulator. The DSP56300/600 macro supports this by following a transfer of the MSP with sign extension with a move of the LSP to the accumulator.

3.2.18 TFR2

This DSP56100 instruction allowed transfer of an entire accumulator to a full 32-bit Data ALU register. The transfer also performed limiting on the resulting 32-bit value if necessary.

```
;******************
      Registers Destroyed: None
TFR2
      MACRO S.D
      MOVE S\0,D\0
                         ; Move LSP of accum to data req
      MOVE S,D\1
                         ; Move MSP to data REG, limit
           _EXIT
      BLC
                          ; If no limit, no limit on data range LSP
                         ; Test the accum for GT or LT
      TST
      MOVE #$FFFF,D\0
                        ; Extend limit value to LSP, assume positive
            _EXIT
      BGT
                          ; Exit if it was positive
            #$0,D\0
                          ; Else extend LSP for a negative limiting
      MOVE
EXIT
```



Software Conversion

Instruction Translations

3.2.19 TFR3

This DSP56100 instruction allows transfer of an accumulator to a Data ALU register along with a memory read/write to/from another Data ALU register. This may be supported on the DSP56300/600 by ensuring there are no conflicts on the XDB or YDB. For instance:

```
MOVE A, X1 Y:(R0)+,Y0
```

Hence, translating this instruction must be handled on a case-by-case basis by the software engineer since it is dependent upon the location of the data. If none of the data has been moved to an alternate memory, then this is very similar to splitting a parallel move into two move instructions.

3.2.20 TST2

This DSP56100 instruction provides testing of a Data ALU register for the purpose of setting the CCR based on its contents. The DSP56300/600 macro simply moves the Data ALU register to an accumulator where the TST instruction may be used.

3.2.21 ZERO

This DSP56100 instruction ZERO extends the specified accumulator. The DSP56300/600 macro accomplishes this by moving immediate data into the extension portion of the specified accumulator.

Software Conversion

Emulations Issues Specific to the DSP56600

3.2.22 Immediate Short Data

On the DSP56100, immediate short data is right justified when moved into a Data ALU register. On the DSP56300/600, this data will be left justified. This may be corrected by using the forcing operator recognized by the Assembler. The expense of this difference is that the instruction becomes two words (the data is now full size).

```
DSP56100MOVE #3,X0
DSP56300/600MOVE#>3,X0
```

3.3 EMULATIONS ISSUES SPECIFIC TO THE DSP56600

Other than the instruction set differences specified earlier, there are few differences between the DSP56300 and DSP56600 that need to be considered.

3.3.1 **NORM** Rn,D

The DSP56600 does not support the single iteration NORM instruction. Typically, the NORM instruction is repeated to fully normalize an accumulator. In these instances, using the CLB instruction followed by NORMF will provide the equivalent normalized result.

```
DSP566100:REPNR

NORM R0,A

DSP56300/600CLBA,B

NORMF B1.A,A
```

There are a few issues to be aware of in this emulation. First, an additional accumulator is required. Second, the address register is not updated as in the DSP56100 code. If the address register is not used elsewhere in the code, this is of no consequence. Otherwise, the result of the CLB instruction must be moved into the address register. If the address register was nonzero before the DSP56100 NORM



Software Conversion

Emulations Issues Specific to the DSP56600

instruction was executed, the value in the address register must be added to the result of the CLB instruction. This correction must be performed after the NORMF so that the accumulator is normalized properly.

Another situation to address is a single iteration of the NORM instruction. Although the occurrence of this is *highly* unlikely, it should be mentioned. An equivalent emulation of this situation follows.

```
DSP56600:BNR <_SKIPNR
BES <_SHIFTRT
ASL A (R0)-
BRA <_SKIPNR
_SHIFTRT
ASR A (R0)+
SKIPNR
```

In these situations, it is clearly most efficient to consider the specific situation. For example, code may be reduced greatly if the address register is not of interest and the direction of normalization, if needed, is known. Other reductions are simplifications by case from the example above.

DSP56600:ASL A IFNN

dsp