# **Product Preview**

# 3.3 Volt Only Driver/Receiver with an Integrated Standby Mode

EIA-232-E and CCITT V.28

The MC145583 is a CMOS transceiver composed of three drivers and five receivers that fulfills the electrical specifications of EIA–232–E, EIA–562, and CCITT V.28 while operating from a single + 3.3 or + 5.0 V power supply. This transceiver is a high–performance, low–power consumption device that is equipped with a standby function.

A voltage tripler and inverter converts the + 3.3 V to  $\pm$  8.8 V, or a voltage doubler and inverter converts the + 5.0 V to  $\pm$  8.8 V. This is accomplished through an on–chip 40 kHz oscillator and five inexpensive external capacitors.

#### **Drivers:**

- ±5 V Minimum Output Swing at 3.3 or 5.0 V Power Supply
- 300 Ω Power-Off Impedance
- Output Current Limiting
- Three-State Outputs During Standby Mode

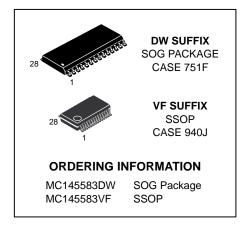
#### Receivers:

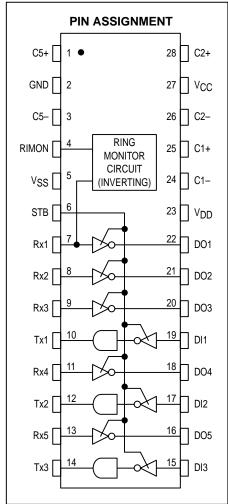
- ± 25 V Input Range
- 3 to 7 kΩ Input Impedance
- 0.8 V Hysteresis for Enhanced Noise Immunity
- Three-State Outputs During Standby Mode

#### **Ring Monitor Circuit:**

 Invert the Input Level on Rx1 to Logic Output Level on RIMON at Standby Mode

### MC145583





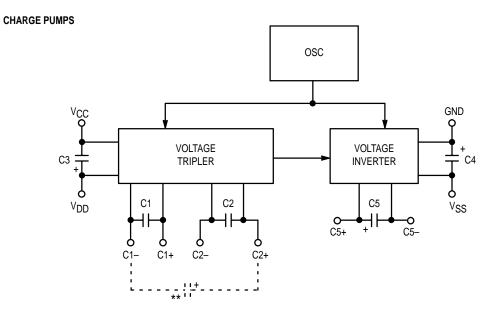
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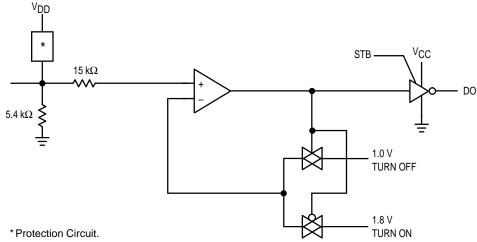




#### **FUNCTION DIAGRAM**

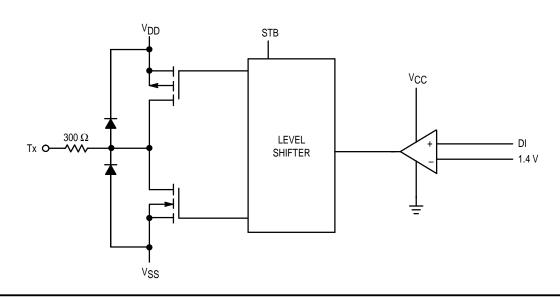


#### **RECEIVER**



\*\*Capacitors C1 and C2 are replaced by a 1  $\mu$ F capacitor at V<sub>CC</sub> = 5.0 V supply.

#### DRIVER



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#### MAXIMUM RATINGS (Voltage polarities referenced to GND)

Rating		Symbol	Value	Unit
DC Supply Voltage		Vcc	- 0.5 to + 6.0	V
Input Voltage Rx1 – Rx5 Inputs DI1 – DI3 Inputs		VIR	V <sub>SS</sub> - 15 to V <sub>DD</sub> + 15 - 0.5 to V <sub>CC</sub> + 0.5	V
DC Current per Pin		I	± 100	mA
Power Dissipation		PD	1	W
Operating Temperature Range		TA	- 40 to + 85	°C
Storage Temperature Ra	ange	T <sub>stg</sub>	- 85 to + 150	°C

This device contains protection circuitry to guard against damage due to high static voltages or electric fields. However, precautions must be taken to avoid applications of any voltage higher than maximum rated voltages to this high–impedance circuit. For proper operation, it is recommended that the voltage at the DI and DO pins be constrained to the range GND  $\leq$  VDI  $\leq$  VCC and GND  $\leq$  VDO  $\leq$  VCC. Also, the voltage at the Rx pin should be constrained to (VSS - 15 V)  $\leq$  VRx1 - Rx5  $\leq$  (VDD + 15 V), and Tx should be constrained to VSS  $\leq$  VTx1 - Tx3  $\leq$  VDD.

Unused inputs must always be tied to an appropriate logic voltage level (e.g., GND or V<sub>CC</sub> for DI, and GND for Rx).

#### RECOMMENDED OPERATING LIMITS

Parameter	Symbol	Min	Тур	Max	Unit
Power Supply	VCC*	3.0 4.5	3.3 5.0	3.6 5.5	V
Operating Temperature Range	TA	- 40		85	°C

<sup>\*</sup> Capacitors C1 and C2 are replaced by a 1  $\mu$ F capacitor at V<sub>CC</sub> = 5 V.

#### **DC ELECTRICAL CHARACTERISTICS** (Voltage polarities referenced to GND = 0 V; C1 – C5 = 1 $\mu$ F; T<sub>A</sub> = 25°C)

Parameter		Symbol	Min	Тур	Max	Unit
DC Power Supply		VCC	3.0	3.3	3.6	V
Quiescent Supply Current (Output Unloaded, Input Low)		Icc	_	2.8	6.0	mA
Quiescent Supply Current (Standby Mode; STB = 1, Output Unloaded)		ICC(STB)	_	< 5	10	μΑ
Control Signal Input Voltage (STB)		V <sub>IL</sub> VIH	— V <sub>CC</sub> – 0.5	_ _	0.5 —	V
Control Signal Input Current (STB)		I <sub>IL</sub>	_ _	_ _	10 10	μА
Charge Pumps Output Voltage (V <sub>CC</sub> = 3 V; C1, C2, C3, C4, C5 = 1 $\mu$ F) Output Voltage (V <sub>DD</sub> ) I <sub>load</sub> = 0 mA I <sub>load</sub> = 6 mA		V <sub>DD</sub>	8.5 7.5	8.8 7.9	_ _	V
Output Voltage (VSS)	$I_{load} = 0 \text{ mA}$ $I_{load} = 6 \text{ mA}$	VSS	_ _	- 8.8 - 7.8	- 8.5 - 7.0	

#### RECEIVER ELECTRICAL SPECIFICATIONS

(Voltage polarities referenced to GND = 0 V; V<sub>CC</sub> = + 3.3 V  $\pm$  10%; C1 – C5 = 1  $\mu$ F; T<sub>A</sub> = 25°C)

Parameter		Symbol	Min	Тур	Max	Unit
Input Turn–On Threshold (V <sub>DO1</sub> – DO5 = V <sub>OL</sub> ; Rx1 – Rx5)	3.3 V 5.0 V	V <sub>on</sub>	1.35 2.00	1.8 2.5	2.35 3.10	V
Input Turn–Off Threshold ( $V_{DO1} - DO5 = V_{OH}$ ; Rx1 – Rx5)	3.3 V 5.0 V	V <sub>off</sub>	0.75 1.20	1.0 1.5	1.25 1.80	V
Input Resistance		R <sub>in</sub>	3	5.4	7	kΩ
High-Level Output Voltage (DO1 – DO5) $V_{Rx1} - Rx5 = -3 \text{ to } -25 \text{ V}$	$I_{\text{out}} = -20 \mu\text{A}$ $I_{\text{out}} = -1 \text{mA}$	VOH	V <sub>CC</sub> - 0.1 V <sub>CC</sub> - 0.6	 2.7	_ _	V
Low-Level Output Voltage (DO1 – DO5) VRx1 – Rx5 = + 3 to + 25 V	$I_{out} = + 20 \mu A$ $I_{out} = + 1.6 \text{ mA}$	VOL	_ _	0.01 0.5	0.1 0.7	V
Ring Monitor Circuit (Input Threshold)		V <sub>TH</sub>	_	1.1	_	V
High-Level Output Voltage (RIMON)	$I_{\text{out}} = -20 \mu\text{A}$ $I_{\text{out}} = -1 \text{mA}$	VOH	V <sub>CC</sub> - 0.1 V <sub>CC</sub> - 0.6	 2.7	_	V
Low-Level Output Voltage (RIMON)	$I_{out} = +20 \mu A$ $I_{out} = +1.6 \text{ mA}$	V <sub>OL</sub>	_ _	0.01 0.5	0.1 0.7	V

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#### **DRIVER ELECTRICAL SPECIFICATIONS**

(Voltage polarities referenced to GND = 0 V; V<sub>CC</sub> = + 3.3 V or + 5.0 V  $\pm$  10%; C1 – C5 = 1  $\mu$ F; T<sub>A</sub> = 25°C)

Parameter	Symbol	Min	Тур	Max	Unit
Digital Input Voltage DI1 – DI3					V
Logic Low	VIL	l –	_	0.7	
Logic High	VIH	1.8	_	_	
Digital Input Current DI1 – DI3					μΑ
V <sub>DI</sub> = GND	Iլ∟	l —	7	_	
V <sub>DI</sub> = V <sub>CC</sub>	lιΗ	_	_	± 1.0	
Output High Voltage	Voн				V
Load on All Tx1 – Tx3, $R_L = 3 \text{ k}\Omega$ ; $C_P = 2500 \text{ pF}$ , $V_{Dl1} - Dl3 = \text{Logic Low}$		5.0	7.0	_	
No Load		8.5	8.8	_	
Output Low Voltage	VOL				V
Load on All Tx1 – Tx3, R <sub>L</sub> = 3 k $\Omega$ ; C <sub>P</sub> = 2500 pF, V <sub>Dl1 – Dl3</sub> = Logic High	0_	l —	- 7.0	- 5.0	
No Load		l —	- 8.8	- 8.5	
Ripple (Refer to V <sub>DD</sub> – V <sub>SS</sub> Value) ***	V <sub>RF</sub>	_	_	± 5%	
Off Source Impedance Tx1 – Tx3	Z <sub>off</sub>	300	_	_	Ω
Output Short Circuit Current (V <sub>CC</sub> = 3.3 V or 5.5 V)	ISC				mA
Tx1 – Tx3 Shorted to GND*	30	l –	l —	± 60	
Tx1 – Tx3 Shorted to ± 15 V**		-	_	± 100	

<sup>\*</sup> Specification is for one Tx output to be shorted at a time. Should all three driver outputs be shorted simultaneously, device power dissipation limits could be exceeded.

## SWITCHING CHARACTERISTICS (V $_{CC}$ = + 3.3 V or + 5 V, $\pm$ 10%; C1 – C5 = 1 $\mu$ F; TA = 25°C)

Parameter		Symbol	Min	Тур	Max	Unit
Drivers				•		
Propagation Delay Time Low-to-High	Tx1 – Tx3	<sup>t</sup> DPLH		0.5		μs
$(R_L = 3 \text{ k}\Omega, C_L = 50 \text{ pF or } 2500 \text{ pF})$			_	0.5	1	
High–to–Low $(R_L = 3 kΩ, C_L = 50 pF or 2500 pF)$		<sup>t</sup> DPHL	_	0.5	1	
Output Slew Rate (Source R = $300 \Omega$ ) Loading: R <sub>L</sub> = $3-7 k\Omega$ ; C <sub>L</sub> = $2500 pF$	Tx1 – Tx3	SR	± 4	_	± 30	V/µs
Output Disable Time*		<sup>t</sup> DAZ	_	4	10	μs
Output Enable Time*		<sup>t</sup> DZA	_	25	50	ms
Receivers						
Propagation Delay Time Low-to-High	DO1 – DO5	<sup>t</sup> RPLH	_	_	1	μs
High-to-Low		t <sub>RPHL</sub>	_	_	1	
Output Rise Time	DO1 – DO5	t <sub>r</sub>	_	120	200	ns
Output Fall Time	DO1 – DO5	t <sub>f</sub>	_	40	100	ns
Output Disable Time*		<sup>t</sup> RAZ	_	4	10	μs
Output Enable Time*		<sup>t</sup> RZA	_	25	50	ms

<sup>\*</sup> Including the charge pump setup time.

# TRUTH TABLES Drivers

DI	STB	Tx
Х	Н	Z*
Н	L	L
L	L	Н

 $<sup>^*</sup>V_{SS} \le V_{Tx} \le V_{DD}$  X = Don't Care

#### Receivers

Rx	STB	DO
Х	Н	Z*
Н	L	L
L	L	Н

<sup>\*</sup> GND  $\leq$  V<sub>DO</sub>  $\leq$  V<sub>CC</sub> X = Don't Care

<sup>\*\*</sup> This condition could exceed package limitations.

<sup>\*\*\*</sup> Ripple  $V_{RF}$  would not exceed  $\pm$  5% of  $(V_{DD} - V_{SS})$ .



#### PIN DESCRIPTIONS

#### **VCC**

#### **Digital Power Supply (Pin 27)**

This digital supply pin is connected to the logic power supply. This pin should have a not less than 0.33  $\mu F$  capacitor GND.

#### **GND**

#### Ground (Pin 2)

Ground return pin is typically connected to the signal ground pin of the EIA–232–E connector (Pin 7) as well as to the logic power supply ground.

#### $V_{DD}$

#### Positive Power Supply (Pin 23)

This is the positive output of the on–chip voltage tripler and the positive power supply input of the driver/receiver sections of the device. This pin requires an external storage capacitor to filter the 50% duty cycle voltage generated by the charge pump.

#### VSS

#### **Negative Power Supply (Pin 5)**

This is the negative output of the on-chip voltage tripler/inverter and the negative power supply input of the driver/ receiver sections of the device. This pin requires an external storage capacitor to filter the 50% duty cycle voltage generated by the charge pump.

#### **RIMON**

#### **Ring Monitor Circuit (Pin 4)**

The Ring Monitor Circuit will convert the input level on Rx1 pin at standby mode and output on the RIMON pin.

#### **STB**

#### Standby Mode (Pin 6)

The device enters the standby mode while this pin is connected to the logic high level. During the standby mode,

driver and receiver output pins become high-impedance state. In this condition, supply current I<sub>CC</sub> is below 5 µA (typ).

#### C5+, C5-, C2+, C2-, C1+, C1-Voltage Tripler and Inverter (Pins 1, 3, 28, 26, 25, 24)

These are the connections to the internal voltage tripler and inverter, which generate the V<sub>DD</sub> and V<sub>SS</sub> voltages.

#### Rx1, Rx2, Rx3, Rx4, Rx5 Receive Data Inputs (Pins 7, 8, 9, 11, 13)

These are the EIA-232–E receive signal inputs. A voltage between + 3 and + 25 V is decoded as a space, and causes the corresponding DO pin to swing to GND (0 V). A voltage between -3 and -25 V is decoded as a mark, and causes the DO pin to swing up to V<sub>CC</sub>.

#### DO1, DO2, DO3, DO4, DO5 Data Outputs (Pins 22, 21, 20, 18, 16)

These are the receiver digital output pins, which swing from V<sub>CC</sub> to GND. Output level of these pins is high impedance while in standby mode.

#### DI1, DI2, DI3 Data Inputs (Pins 19, 17, 15)

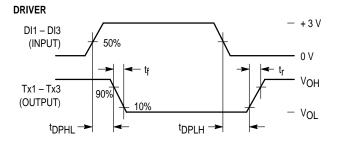
These are the high impedance digital input pins to the drivers. Input voltage levels on these pins must be between  $V_{\hbox{\footnotesize{CC}}}$  and GND.

#### Tx1, Tx2, Tx3 Transmit Data Output (Pins 10, 12, 14)

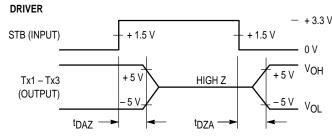
These are the EIA–232–E transmit signal output pins, which swing toward  $V_{DD}$  and  $V_{SS}$ . A logic 1 at a DI input causes the corresponding Tx output to swing toward  $V_{SS}$ . The actual levels and slew rate achieved will depend on the output loading (RL/CL).

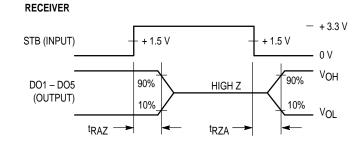
The minimum output impedance is 300  $\Omega$  when turned off.

#### SWITCHING CHARACTERISTICS



# RECEIVER Rx1 – Rx5 (INPUT) 50% 0 V TRPHL 90% VOH 10% VOH VOH





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#### **ESD PROTECTION**

ESD protection on IC devices that have their pins accessible to the outside world is essential. High static voltages applied to the pins when someone touches them either directly or indirectly can cause damage to gate oxides and transistor junctions by coupling a portion of the energy from the I/O pin to the power supply buses of the IC. This coupling

will usually occur through the internal ESD protection diodes which are designed to do just that. The key to protecting the IC is to shunt as much of the energy to ground as possible before it enters the IC. Figure 1 shows a technique which will clamp the ESD voltage at approximately  $\pm\ 15\ V$  using the MMBZ15VDLT1. Any residual voltage which appears on the supply pins is shunted to ground through the capacitors C1 and C2.

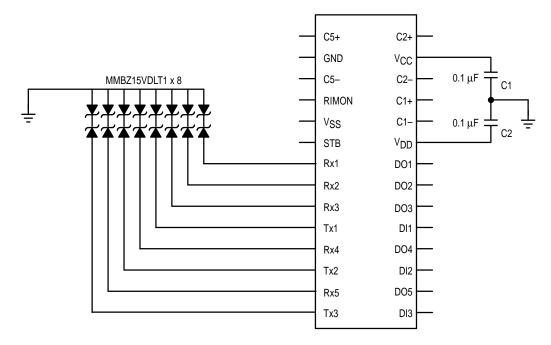


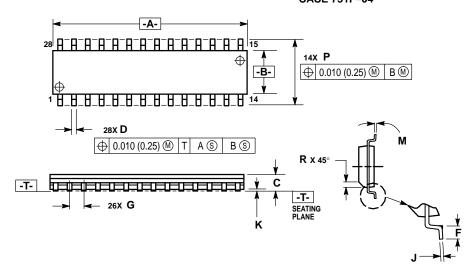
Figure 1. ESD Protection Scheme

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#### **PACKAGE DIMENSIONS**

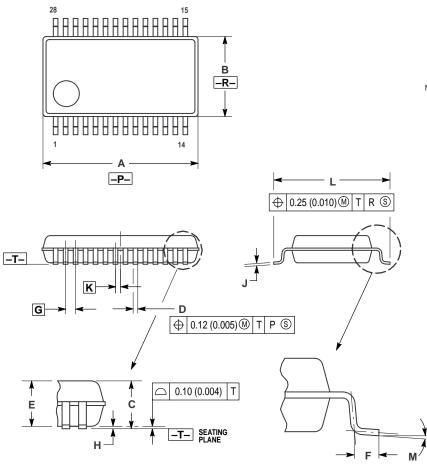
#### **DW SUFFIX SOG PACKAGE** CASE 751F-04



- NOTES:
  1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  2. CONTROLLING DIMENSION: MILLIMETER.
  3. DIMENSION A AND B DO NOT INCLUDE MOLD PROTRUSION.
  4. MAXIMUM MOLD PROTRUSION 0.15
- MAXIMUM MIDLD PROTRUSION 0.13
  (0.006) PER SIDE.
  DIMENSION D DOES NOT INCLUDE
  DAMBAR PROTRUSION. ALLOWABLE
  DAMBAR PROTRUSION SHALL BE 0.13
  (0.005) TOTAL IN EXCESS OF D
  DIMENSION AT MAXIMUM MATERIAL

	MILLIM	ETERS	INC	HES
DIM	MIN	MAX	MIN	MAX
Α	17.80	18.05	0.701	0.711
В	7.40	7.60	0.292	0.299
С	2.35	2.65	0.093	0.104
D	0.35	0.49	0.014	0.019
F	0.41	0.90	0.016	0.035
G	1.27	BSC	0.050	BSC
J	0.23	0.32	0.009	0.013
K	0.13	0.29	0.005	0.011
М	0°	8°	0°	8°
Р	10.05	10.55	0.395	0.415
R	0.25	0.75	0.010	0.029

#### **VF SUFFIX SSOP** CASE 940J-01



#### NOTES:

- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
- CONTROLLING DIMENSION: MILLIMETER. DIMENSIONS A AND B DO NOT INCLUDE MOLD PROSTRUSION. MOLD PROTRUSION IS 0.15 (0.006) MAX PER SIDE.

	MILLIN	IETERS	INC	HES
DIM	MIN	MAX	MIN	MAX
Α	10.10	10.20	0.398	0.402
В	5.20	5.30	0.205	0.209
С		2.00	_	0.079
D	0.20	0.40	0.008	0.016
Е	1.75	1.85	0.069	0.073
F	0.45	0.75	0.018	0.030
G	0.65	BSC	0.025	6 BSC
Н	0.00	0.15	0.000	0.006
J	0.10	0.20	0.004	0.008
K	0.325	BSC	0.0128 BSC	
L	7.50	7.90	0.295	0.311
М	1°	7 °	1°	7 °



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