

# iMX7ULP\_2N54W

## Mask Set Errata

Rev. 2.1 — 14 November 2024

Errata

## 1 Mask Set Errata for Mask 2N54W

### 1.1 Revision History

This report applies to mask 2N54W for these products:

- MCIMX7U3CVP06SD
- MCIMX7U3DVK07SD
- MCIMX7U5CVP06SD
- MCIMX7U5DVK07SD
- MCIMX7U5DVP07SD

Table 1. Revision History

Revision	Release Date	Significant Changes
2.1	11/2024	The following errata were revised. <ul style="list-style-type: none"><li>• ERR052515</li></ul>
2	11/2024	The following errata were added. <ul style="list-style-type: none"><li>• ERR052515</li></ul>
1	5/2023	Initial Revision

### 1.2 Errata and Information Summary

Table 2. Errata and Information Summary

Erratum ID	Erratum Title
<a href="#">ERR010469</a>	ARM A7: A7 core reset as a source for the M4 core
<a href="#">ERR010472</a>	MSMC: Reset delay on A7 domain when interrupt is enabled for Core0 reset sources
<a href="#">ERR010473</a>	uSDHC: Data Timeout Counter Value may be insufficient for HS400 mode
<a href="#">ERR010740</a>	QuadSPI: Insufficient read data may be received in the RX Data Buffer register
<a href="#">ERR011097</a>	LPSPi: Command word not loaded correctly when TXMSK=1
<a href="#">ERR011372</a>	Power: High leakage current on VDD18_IOREF when VDD supplies for PORT segments are turned off in VLLS modes
<a href="#">ERR011403</a>	CA7: LLS/VLPS wakeup time is longer when PMC1_CTRL[LDOOKDIS]=0
<a href="#">ERR011432</a>	SNVS: TAMPER pin does not retain pull-up/down configuration in VBAT mode
<a href="#">ERR011433</a>	DAC: Transfer error generated when accessing offset addresses 0x19-0x1B
<a href="#">ERR011439</a>	MIPI DSI: Checksum is incorrect for DCS command long packet writes with zero-length data payload
<a href="#">ERR050134</a>	GPIO: GPIO pull-ups/pull-downs may become enabled during reset
<a href="#">ERR050138</a>	PMC: PMC0 PM_STAT[PMC0CURRPM] stuck at VLPR after reset in VLPS/LLS/VLLS modes



Table 2. Errata and Information Summary...continued

Erratum ID	Erratum Title
<a href="#">ERR051560</a>	SNVS: State machine stuck in CHECK after resume from VLLS
<a href="#">ERR052515</a>	FSGPIO: A parametric shift over time is observed on FSGPIO output driver when it is powered above 1.98V

## 2 Known Errata

### ERR010469: ARM A7: A7 core reset as a source for the M4 core

#### Description

The i.MX 7ULP provides the following reset options between the two ARM cores:

- 1) M4 core reset of A7 core: There is hardware capability on the SoC for the M4 core to reset the A7 core directly.
- 2) A7 core reset of M4 core: There is no hardware capability for the A7 to reset the M4 directly. This is achieved through the Messaging Unit (MU). The MU A-side Control Register field MUA\_CR[RAIE] provides a software mechanism for the M4 to detect that the A7 has been reset.

#### Workaround

The A7 reset is mapped as an interrupt to the M4 core so anytime the A7 is reset, an interrupt is triggered to the M4 core. The M4 core can then reset as required using an ISR.

### ERR010472: MSMC: Reset delay on A7 domain when interrupt is enabled for Core0 reset sources

#### Description

The Multicore System Mode Controller (MSMC) System Reset Interrupt Enable (SRIE) feature allows that some reset sources can be delayed to service an interrupt request.

For the A7 domain, this feature can be enabled for Core 0 (M4) reset sources. This can cause potential issues because when the M4 resets, the A7 domain will lose its clock references from the PLLs and will not be able to service the interrupt. Even when the M4 returns from reset, it is not guaranteed that the PLLs will relock without reconfiguration.

#### Workaround

Do not use the Core 0 reset interrupt function available to the A7 domain.

### ERR010473: uSDHC: Data Timeout Counter Value may be insufficient for HS400 mode

#### Description

When the Data Timeout Counter Value programmed in SYS\_CTRL[DTOCV] is set to the maximum value (0xF), the maximum busy timeout is  $[2^{29} * 2.5 \text{ ns}] = 1.34 \text{ s}$  because the root clock is 400 MHz for HS400 mode. For other speed modes, the maximum busy timeout time is longer because the root clock is slower.

Some eMMC datasheets show maximum busy timeout specifications of 1.6 s, so the programmable timeout in the uSDHC will not be long enough for HS400 mode.

This issue only affects HS400 mode with a 200 MHz SD clock. If the SD clock is reduced to 150 MHz, the timing requirements for 1.6 s can be met.

#### Workaround

- 1) Reduce the SD clock to 150 MHz

2) Disable hardware timeout and use a software timeout mechanism to generate a 1.6 s timeout

## **ERR010740: QuadSPI: Insufficient read data may be received in the RX Data Buffer register**

### **Description**

Data read from flash through QuadSPI using Peripheral Bus Interface (IPS) may return insufficient data in the RX Buffer Data register (QuadSPI\_RBDRn) when the read data size of a flash transaction is programmed to be greater than 32 bytes.

### **Workaround**

For data size greater than 32 bytes, program the IP data transfer size in the IP configuration register (QuadSPI\_IPCR[IDATSZ]) to be in multiples of 8 bytes.

## **ERR011097: LPSPi: Command word not loaded correctly when TXMSK=1**

### **Description**

When the Transmit Command Register is written with TCR[TXMSK]=1 and the next write to the TX FIFO is another command, then the first command may not load correctly.

### **Workaround**

When writing the Transmit Command Register with TCR[TXMSK]=1, wait for the TX FIFO to go empty (FSR[TXCOUNT] = 0) before writing another command to the Transmit Command Register.

## **ERR011372: Power: High leakage current on VDD18\_IOREF when VDD supplies for PORT segments are turned off in VLLS modes**

### **Description**

Excessive current around 370µA on VDD18\_IOREF is observed when both the M4 and A7 cores are in VLLS mode and VDD\_PTA, VDD\_PTC or VDD\_PTE are turned off.

### **Workaround**

VDD\_PTA, VDD\_PTC and VDD\_PTE should remain powered when the M4 and A7 are both in VLLS mode. The expected leakage current for keeping these supplies powered is approximately 2 µA at 3.3V.

## **ERR011403: CA7: LLS/VLPS wakeup time is longer when PMC1\_CTRL[LDOOKDIS]=0**

### **Description**

The CA7 wakeup time from LLS/VLPS is significantly longer when PMC1\_CTRL[LDOOKDIS]=0. This bitfield selects whether the PMC will check the regulated output from the LDO Regulator during a mode transition.

Approximate wakeup time from LLS when PMC1\_CTRL[LDOOKDIS]=1: 41.5 µs

Approximate wakeup time from LLS when PMC1\_CTRL[LDOOKDIS]=0: 80 µs

Approximate wakeup time from VLPS when PMC1\_CTRL[LDOOKDIS]=1: 23 µs

Approximate wakeup time from VLPS when PMC1\_CTRL[LDOOKDIS]=0: 46 us

This issue does not affect systems designed for CA7 LDO Bypass Mode.

### Workaround

Set PMC1\_CTRL[LDOOKDIS]=1 before entering LLS/VLPS modes. This setting keeps the register asserted when returning to RUN mode. After RUN mode is reached, the register may be de-asserted.

PMC1\_CTRL[LDOOKDIS]=0 reduces the response time of the LDO voltage adjustments in RUN mode, while PMC1\_CTRL[LDOOKDIS]=1 sets a fixed timing interval for any voltage adjustment. When moving to LLS or VLPS modes, there are no side effects if PMC1\_CTRL[LDOOKDIS]=1 is used.

In CA7 LDO Bypass Mode, always set PMC1\_CTRL[LDOOKDIS]=1.

## ERR011432: SNVS: TAMPER pin does not retain pull-up/down configuration in VBAT mode

### Description

The TAMPER pin has the capability to enable an internal pull-up or pull-down resistor. The internal pull-up / pull-down configuration is not retained when the SoC enters VBAT mode.

### Workaround

Use an external pull-up or pull-down resistor if the TAMPER function is desired during VBAT mode.

## ERR011433: DAC: Transfer error generated when accessing offset addresses 0x19-0x1B

### Description

The DAC generates a transfer error for both read and write accesses to offset addresses 0x19-0x1B. These offsets are part of the ITRM register which is 32 bits and starts at offset address 0x18. Accesses to offset address 0x18 work properly.

### Workaround

Use only 32-bit accesses to offset address 0x18 to read/write the IRTM register.

## ERR011439: MIPI DSI: Checksum is incorrect for DCS command long packet writes with zero-length data payload

### Description

According to the MIPI DSI specification, long packets are comprised of a Packet Header and a payload of 0 to  $2^{16}-1$  bytes. For the special case of a zero-length payload, the specification requires the checksum must be set to 0xFFFF.

The MIPI DSI controller produces an incorrect checksum for DCS commands issued via long packets with zero-length payloads in DSI Low-Power mode (LP). There is no issue for similar commands issued in DSI High-Power mode (HP).

This issue should not affect normal application operation because packets with zero data length will normally be sent using the short packet format. However, because the MIPI DSI spec specifically states this behavior, MIPI DSI certification will fail with long packets of zero-length.

### Workaround

Use short packet format to send DCS commands with zero length data payloads.

## ERR050134: GPIO: GPIO pull-ups/pull-downs may become enabled during reset

### Description

During reset, the failsafe GPIOs (Ports A, B, C, E, and F) are supposed to be in the input/H-Z state. Due to a reset issue, the GPIO buffers may come up as Hi-Z with an internal pull-up or pull-down being enabled. The issue persists until the associated internal core supply is on (VDD\_DIG0 for Ports A and B; VDD\_DIG1 for Ports C, E, and F). After the internal core supply is present, the issue is cleared and the GPIOs will behave as expected.

Ports A and B are susceptible to this issue, however it will only occur until VDD\_DIG0 is on. In this case, the GPIO issue will clear before RESET0\_b is released.

On Ports C, E, and F, the issue will persist until VDD\_DIG1 is turned on internally by the M4. Therefore, the issue will persist after RESET0\_b is released until the boot ROM process enables VDD\_DIG1 to the A7 domain.

This issue occurs only on power-on reset (POR). After the core supplies have been turned on, the issue will not occur on subsequent resets (including when the A7 exits VLLS mode).

Port D GPIOs are not affected.

### Workaround

- 1) For critical signals that must be controlled during reset, choose GPIOs on ports A, B, or D.
- 2) For critical signals on ports C, E, and F, include a strong enough pull-up or pull-down on the board to overdrive the internal pull-up or pull-down if it occurs. The internal pull-up/pull-downs may be as strong as approximately 20k ohms.

## ERR050138: PMC: PMC0 PM\_STAT[PMC0CURRPM] stuck at VLPR after reset in VLPS/LLS/VLLS modes

### Description

The Real-Time Domain PMC0 Current Power Mode status bits (PMC0 PM\_STAT[PMC0CURRPM]) become stuck indicating VLPR mode (0x3) if a reset occurs when the Real-Time Domain is in VLPS, LLS, or VLLS mode and those power modes were reached from VLPR mode (i.e. RUN -> VLPR -> VLPS/LLS/VLLS). Notice that VLLS wake-up always includes a reset regardless of the wakeup source (RESET0\_B, GPIO, NMI, etc.) so this issue is always seen after a wake-up via GPIO/NMI pin events.

### Workaround

If PMC0 PM\_STAT[PMC0CURRPM] is not used, no action is required.

If the Real-Time Domain needs to go from VLPR to one of the affected modes (i.e. VLPS/LLS/VLLS), go from VLPR to RUN first, and then go to the target mode (VLPS, LLS, or VLLS).

**ERR051560: SNVS: State machine stuck in CHECK after resume from VLLS****Description**

SNVS state machine stays in CHECK state after M4 core resumes from VLLS low power modes when silicon lifecycle is OPEN/RETURN. In CHECK state, you cannot write the SNVS registers except HPCOMR. This impacts the operations to RTC and others.

**Workaround**

Set the SSM\_ST bit in HPCOMR to start state machine transition, and then reset the SNVS LP by set LP\_SWR in HPCOMR. This workaround makes SNVS state machine transit from CHECK to TRUSTED state.

**ERR052515: FSGPIO: A parametric shift over time is observed on FSGPIO output driver when it is powered above 1.98V****Description**

When FSGPIO is powered above 1.98V, a parametric shift over time is observed on FSGPIO output driver, where the output low drive current (IOL) is degraded, leading to a longer fall time and output low voltage level (VOL) is increased. Analog and input functionality is not impacted.

PTA, PTC, PTE and PTF are impacted. PTB is FSGPIO, but it is powered with 1.8V mode (1.71-1.98V) only, therefore PTB is not impacted.

For new or updated designs use 1.8V mode (1.71-1.98V) for the FSGPIO power supply. For the legacy designs, refer to Technote TN00188 for IOL and fall time degradation information when operating above 1.98V. If it is determined that IO does not meet the mission profile requirement of the end application, implement the workaround.

**Workaround**

The I/O power supplies, VDD\_PTA, VDD\_PTC, VDD\_PTE and VDD\_PTF should be connected to 1.8V mode (1.71-1.98V).

The voltage range is controlled by PT\*\_RANGE\_CTRL of SIM\_DGO\_GP11(Address 0x 410A3080).

00b – Continuous Mode

01b – Low Range Mode

10b – High Range Mode

Both 00b and 01b are allowed. Recommend to set the field to 01b to use low voltage range 1.8V for better delay performance and power consumption if the power supply is 1.8V.

Note these SIM\_DGO\_GP11 registers update requires the special sequence documented in the System Integration Module(SIM) chapters of iMX7ULP RM.

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