

Mask Set Errata for Mask 2N10D

This report applies to mask 2N10D for these products:

- MPC5606E

ID after 28 JULY 2014	Errata Title
5569	ADC: The channel sequence order will be corrupted when a new normal conversion chain is started prior to completion of a pending normal conversion chain
7322	FlexCAN: Bus Off Interrupt bit is erroneously asserted when soft reset is performed while FlexCAN is in Bus Off state
7394	MC_ME: Incorrect mode may be entered on low-power mode exit.
6239	eTimer: When counter is not enabled, capture flags can be set but capture register values are not updated.
6802	eTimer: Extra input capture events can set unwanted DMA requests
6583	eTimer: Incorrect updating of the Hold Register

e5569: ADC: The channel sequence order will be corrupted when a new normal conversion chain is started prior to completion of a pending normal conversion chain

Errata type: Errata

Description: If One shot mode is configured in the Main Configuration Register (MCR[MODE] = 0) the chained channels are automatically enabled in the Normal Conversion Mask Register 0 (NCMR0). If the programmer initiates a new chain normal conversion, by setting MCR[NSTART] = 0x1, before the previous chain conversion finishes, the new chained normal conversion will not follow the requested sequence of converted channels.

For example, if a chained normal conversion sequence includes three channels in following sequence: channel0, channel1 and channel2, the conversion sequence is started by MCR[NSTART] = 0x1. The software re-starts the next conversion sequence when MCR[NSTART] is set to 0x1 just before the current conversion sequence finishes.

The conversion sequence should be: channel0, channel1, channel2, channel0, channel1, channel2.

However, the conversion sequence observed will be: channel0, channel1, channel2, channel1, channel1, channel2. Channel0 is replaced by channel1 in the second chain conversion and channel1 is converted twice.

Workaround: Ensure a new conversion sequence is not started when a current conversion is ongoing. This can be ensured by issuing the new conversion setting MCR[NSTART] only when MSR[NSTART] = 0.

Note: MSR[NSTART] indicates the present status of conversion. MSR[NSTART] = 1 means that a conversion is ongoing and MSR[NSTART] = 0 means that the previous conversion is finished.

e7322: FlexCAN: Bus Off Interrupt bit is erroneously asserted when soft reset is performed while FlexCAN is in Bus Off state

Errata type: Errata

Description: Under normal operation, when FlexCAN enters in Bus Off state, a Bus Off Interrupt is issued to the CPU if the Bus Off Mask bit (CTRL[BOFF_MSK]) in the Control Register is set. In consequence, the CPU services the interrupt and clears the ESR[BOFF_INT] flag in the Error and Status Register to turn off the Bus Off Interrupt.

In continuation, if the CPU performs a soft reset after servicing the bus off interrupt request, by either requesting a global soft reset or by asserting the MCR[SOFT_RST] bit in the Module Configuration Register, once MCR[SOFT_RST] bit transitions from 1 to 0 to acknowledge the soft reset completion, the ESR[BOFF_INT] flag (and therefore the Bus Off Interrupt) is re-asserted.

The defect under consideration is the erroneous value of Bus Off flag after soft reset under the scenario described in the previous paragraph.

The Fault Confinement State (ESR[FLT_CONF] bit field in the Error and Status Register) changes from 0b11 to 0b00 by the soft reset, but gets back to 0b11 again for a short period, resuming after certain time to the expected Error Active state (0b00). However, this late correct state does not reflect the correct ESR[BOFF_INT] flag which stays in a wrong value and in consequence may trigger a new interrupt service.

Workaround: To prevent the occurrence of the erroneous Bus Off flag (and eventual Bus Off Interrupt) the following soft reset procedure must be used:

1. Clear CTRL[BOFF_MSK] bit in the Control Register (optional step in case the Bus Off Interrupt is enabled).
2. Set MCR[SOFT_RST] bit in the Module Configuration Register.
3. Poll MCR[SOFT_RST] bit in the Module Configuration Register until this bit is cleared.
4. Wait for 4 peripheral clocks.
5. Poll ESR[FLTCONF] bit in the Error and Status Register until this field is equal to 0b00.
6. Write "1" to clear the ESR[BOFF_INT] bit in the Error and Status Register.
7. Set CTRL[BOFF_MSK] bit in the Control Register (optional step in case the Bus Off Interrupt is enabled).

e7394: MC_ME: Incorrect mode may be entered on low-power mode exit.

Errata type: Errata

Description: For the case when the Mode Entry (MC_ME) module is transitioning from a run mode (RUN0/1/2/3) to a low power mode (HALT/STOP/STANDBY*) if a wake-up or interrupt is detected one clock cycle after the second write to the Mode Control (ME_MCTL) register, the MC_ME will exit to the mode previous to the run mode that initiated the low power mode transition.

Example correct operation DRUN->RUN1-> RUN3->STOP->RUN3

Example failing operation DRUN->RUN1-> RUN3->STOP->RUN1

*Note STANDBY mode is not available on all MPC56xx microcontrollers

Workaround: To ensure the application software returns to the run mode (RUN0/1/2/3) prior to the low power mode (HALT/STOP/STANDBY*) it is required that the RUNx mode prior to the low power mode is entered twice.

The following example code shows RUN3 mode entry prior to a low power mode transition.

```
ME.MCTL.R = 0x70005AF0; /* Enter RUN3 Mode & Key */
ME.MCTL.R = 0x7000A50F; /* Enter RUN3 Mode & Inverted Key */
while (ME.GS.B.S_MTRANS) {} /* Wait for RUN3 mode transition to complete */
ME.MCTL.R = 0x70005AF0; /* Enter RUN3 Mode & Key */
ME.MCTL.R = 0x7000A50F; /* Enter RUN3 Mode & Inverted Key */
while (ME.GS.B.S_MTRANS) {} /* Wait for RUN3 mode transition to complete */
/* Now that run mode has been entered twice can enter low power mode */
/* (HALT/STOP/STANDBY*) when desired. */
```

e6239: eTimer: When counter is not enabled, capture flags can be set but capture register values are not updated.

Errata type: Errata

Description: If counter is not enabled (ETIMER_CHn_CTRL1[CNTMODE]==000) and a capture event happens (as defined by ETIMER_CHn_CCCTRL[CPTxMODE]), capture flags (ETIMER_CHn_STS[ICF1 or ICF2]) are set. But at the same time the capture registers (ETIMER_CHn_CAPTx) are not updated.

Workaround: There is no workaround for this. The user's software should make sure not to initiate anything using the ETIMER_CHn_STS[ICF1] or ETIMER_CHn_STS[ICF2] flags if the eTimer module is disabled.

e6802: eTimer: Extra input capture events can set unwanted DMA requests

Errata type: Errata

Description: When using the DMA to read the eTimer channel capture registers (ETIMER_CHn_CAPTn) and the DMA has completed its programmed number of transfers an extra input capture event will set the eTimers input capture flag bit in the status register (ETIMER_CHn_STS[ICFn]) and also set the internal DMA request signal. While the input capture flag status bits (ICFn) can be

cleared by writing a 1 to their bit positions the DMA request can only be cleared by the DMA done signal. This means that when a new DMA transfer is programmed the eTimer will request a DMA read with possibly unwanted data.

This behavior occurs once the DMA requests are disabled on the side of eDMA (DMA_ERQ[ERQn] = 0), but are still enabled in eTimer (ETIMER_CHn_INTDMA[ICFnDE] = 1), and the active edge is detected

Workaround: In cases where extra eTimer input capture events might occur the following procedure can be used to prevent unwanted DMA read requests:

1. Upon completion of the DMA transfer, disable the DMA requests by clearing the ETIMER_CHn_INTDMA[ICFnDE] bits.
2. If ETIMER_CHn_STS[ICFn] bits are clear then there are no extra input capture events and the eTimer is ready for further operation.
3. If the ICFn bits are set then read the ETIMER_CHn_CAPTn registers until the ETIMER_CHn_CTRL3[CnFCNT] fields are both 0 indicating the the capture FIFO's are empty. Then write a 1 to the ICFn bits to clear them. Next, create a dummy DMA read transfer to read the CAPTn registers. The DMA done signal will clear any pending DMA request.

e6583: eTimer: Incorrect updating of the Hold Register

Errata type: Errata

Description: The eTimer's Hold Registers (ETIMER_CHn_HOLD) are incorrectly updated when a Compare and Capture Control Register (ETIMER_CHn_CCCTRL) is read.

Workaround: The eTimer's Hold Registers are supposed to be updated with the Counter Registers (ETIMER_CHn_CNTR) value whenever a Counter Register is read. Recognize that the Hold Registers values will also be updated if a Compare and Capture Control Register is read.



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