Kinetis SDK v1.1.0 Release Notes for TWR-K21F120M Freescale Tower System Development Platform

1 Overview

These are the release notes for the TWR-K21F120M Tower System KSDK standalone release, based on Kinetis SDK (KSDK) 1.1.0. The core of the Kinetis SDK is a set of drivers architected in two layers: the Hardware Abstraction Layer (HAL) and the Peripheral Driver Layer.

The HAL abstracts the hardware register accesses into a set of stateless functional primitives which provide the building blocks for high-level Peripheral Drivers or applications. The Peripheral Driver Layer implements use-case driven drivers by utilizing one or more HAL layer components, system services, and possibly other Peripheral Drivers.

The Kinetis SDK includes a set of example applications demonstrating the use of the Peripheral Drivers and other integrated software modules such as a Real-Time Operating System (RTOS) through an RTOS abstraction layer. The Kinetis SDK also integrates middleware such as the Freescale USB stack to provide an easy-to-use Software Development Kit for Kinetis microcontroller (MCU) product families.

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2 Development Tools

The Kinetis SDK for Freescale TWR-K21F120M Freescale Tower System development platform was compiled and tested with these development tools:

- Kinetis Design Studio (KDS) IDE v2.0
- IAR Embedded Workbench for ARM® version 7.30.3
- MDK-ARM Microcontroller Development Kit (Keil) 5.11
- Makefiles support with GCC revision 4.8.3 from ARMEmbedded
- Atollic TrueSTUDIO 5.2.0

The following table provides a list of default debugger configurations for Freescale TWR-K21F120M Freescale Tower System development platform.

<table>
<thead>
<tr>
<th>IDE</th>
<th>Tower</th>
</tr>
</thead>
<tbody>
<tr>
<td>IAR Embedded Workbench for ARM® version 7.30.3</td>
<td>P&amp;E Micro</td>
</tr>
<tr>
<td>MDK-ARM Microcontroller Development Kit (Keil) 5.11</td>
<td>P&amp;E Micro</td>
</tr>
<tr>
<td>Kinetis Design Studio IDE v2.0</td>
<td>P&amp;E Micro</td>
</tr>
<tr>
<td>Makefiles support with GCC revision 4.8.3 from ARM Embedded</td>
<td>J-Link</td>
</tr>
<tr>
<td>Atollic TrueSTUDIO 5.2.0</td>
<td>P&amp;E Micro</td>
</tr>
</tbody>
</table>
3 Supported Development Systems

This release supports boards and devices listed in this table. Boards and devices in boldface were tested in this release:

<table>
<thead>
<tr>
<th>Development boards</th>
<th>Kinetis MCU devices</th>
</tr>
</thead>
<tbody>
<tr>
<td>TWR-K21F120M</td>
<td>MK21FN1M0AVMC12, MK21FN1M0AVLQ12, MK21FN1M0AVMD12, MK21FX512AVLQ12, MK21FX512AVMC12, MK21FX512AVMD12</td>
</tr>
</tbody>
</table>

4 Release Contents

This table describes the release contents.

<table>
<thead>
<tr>
<th>Deliverable</th>
<th>Location</th>
</tr>
</thead>
<tbody>
<tr>
<td>Specific content for the evaluation boards</td>
<td>&lt;install_dir&gt;/boards/…</td>
</tr>
<tr>
<td>Demo applications</td>
<td>&lt;install_dir&gt;/demos/…</td>
</tr>
<tr>
<td>Documentation</td>
<td>&lt;install_dir&gt;/doc/…</td>
</tr>
<tr>
<td>File System</td>
<td>&lt;install_dir&gt;/filesystem/…</td>
</tr>
<tr>
<td>Projects to build libraries</td>
<td>&lt;install_dir&gt;/lib/…</td>
</tr>
<tr>
<td>Driver library, startup code and utilities</td>
<td>&lt;install_dir&gt;/platform/…</td>
</tr>
<tr>
<td>Cortex Microcontroller Software Interface Standard (CMSIS) ARM® Cortex®-M header files, DSP library source, and IP extension header files</td>
<td>&lt;install_dir&gt;/platform/CMSIS/…</td>
</tr>
<tr>
<td>Composite Drivers</td>
<td>&lt;install_dir&gt;/platform/composite/…</td>
</tr>
<tr>
<td>Peripheral Drivers</td>
<td>&lt;install_dir&gt;/platform/drivers/…</td>
</tr>
<tr>
<td>Hardware Abstraction Layer</td>
<td>&lt;install_dir&gt;/platform/hal/…</td>
</tr>
<tr>
<td>Linker control files for each supported tool chain</td>
<td>&lt;install_dir&gt;/platform/linker/…</td>
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<tr>
<td>OS Abstraction for Bare Metal and RTOS</td>
<td>&lt;install_dir&gt;/platform/osa/…</td>
</tr>
<tr>
<td>CMSIS compliant Startup Code</td>
<td>&lt;install_dir&gt;/platform/startup/…</td>
</tr>
<tr>
<td>System Services such as clock manager, interrupt manager, unified hardware timer, and low power manager</td>
<td>&lt;install_dir&gt;/platform/system/…</td>
</tr>
<tr>
<td>Utilities such as debug console</td>
<td>&lt;install_dir&gt;/platform/utilities/…</td>
</tr>
<tr>
<td>RTOS Kernel Code, RTOS abstraction implementations, and RTOS kernel folders</td>
<td>&lt;install_dir&gt;/rtos/…</td>
</tr>
<tr>
<td>A Processor Expert service pack and MQX RTOS task-aware plugins for tool chains.</td>
<td>&lt;install_dir&gt;/tools</td>
</tr>
<tr>
<td>USB stack and demos</td>
<td>&lt;install_dir&gt;/usb/…</td>
</tr>
</tbody>
</table>
5 Kinetis SDK Release Overview

The Kinetis SDK is intended for use with Freescale’s Kinetis MCU product family based on the ARM Cortex-M series architectures. The release consists of:

- Kinetis MCU platform support
- Board configuration support
- Demo applications
- The FatFs FAT File System
- USB Host and Device stacks
- RTOS support components
- Documentation (Kinetis SDK reference manual and various user’s guides)

5.1 Kinetis MCU platform support

The Kinetis SDK platform directory contains the startup code, operating system abstraction, system services, driver libraries for peripherals, header files, linker files, and utilities such as the debug console implementation.

5.1.1 Startup code

The Kinetis SDK includes simple CMSIS-compliant startup code for the supported Kinetis MCUs which efficiently delivers the code execution to the `main()` function. An application can either include the startup code directly in the project space or include a prebuilt startup code library for a cleaner project space.

5.1.2 Operating system abstraction

The drivers are designed to work with or without an operating system through the Operating System Abstraction layer (OSA). The OSA defines a common set of services that abstract most of the OS kernel functionalities. The OSA either maps an OSA service to the target OS function, or implements the service when no OS is used (bare metal) or when the service does not exist in the target OS. The Kinetis SDK implements the OSA for Freescale MQX™ RTOS, FreeRTOS, µC/OS-II, µC/OS-III, and for OS-less “bare metal” usage. The bare metal OSA implementation is selected as the default option.

5.1.3 System Services

The system services contain a set of software entities that can be used either by the Peripheral Drivers or with the HAL to build either Peripheral Drivers or an application directly. The system services include the interrupt manager, clock manager, low power manager, and the unified hardware timer interface.
5.1.4 Driver library

The Kinetis SDK provides a set of drivers for the Kinetis MCU product family on-chip peripherals. The drivers are designed and implemented around the peripheral hardware blocks rather than for a specific Kinetis MCU, and work with or without an OS through the OS Abstraction layer. The drivers are architected into two layers: the Hardware Abstraction Layer and the Peripheral Driver Layer.

The HAL is designed to abstract hardware register accesses into functional accesses. It is stateless and is intended to cover the entire hardware functionality.

The Peripheral Drivers are built on top of the HAL to provide a set of easy-to-use interfaces that handle high-level data and stateful transactions. They are designed for the most common use cases identified for the underlying hardware block and are reasonably efficient in terms of memory and performance. They are written in C language and can be easily ported from product to product as they are designed to be initialized at runtime based on the driver configuration passed in by the user. In most cases, the Peripheral Drivers can be used as is. However, if the Peripheral Driver does not address a particular target use case, it can either be modified/enhanced or completely rewritten to meet the target functionality and other requirements. In this case, the existing Peripheral Driver can be used as a reference to build a custom driver based on the HAL. For more details, see the Architectural Overview chapter in the Kinetis SDK v.1.1 API Reference Manual.

Detailed implementation of hardware peripheral functionality, for both the HAL and Peripheral Driver, is implemented in stages. For example, the current version of the UART driver does not support modem control and smart card features. Likewise, the current version of the I2C driver does not support the SMBUS feature. The features which are missing from the current driver versions may be implemented in future releases.

5.1.5 Header files

The Kinetis SDK CMSIS directory contains CMSIS-compliant device-specific header files which provide direct access to the Kinetis MCU peripheral registers. Each supported Kinetis MCU device in the Kinetis SDK has an overall System-on-Chip (SoC) memory-mapped header file. In addition to the overall SoC memory-mapped header file, the Kinetis SDK includes extension header files for each peripheral instantiated on the Kinetis MCU. Along with the SoC header files and peripheral extension header files, the Kinetis SDK also includes common CMSIS header files for the ARM Cortex-M core and DSP library from the ARM CMSIS version 4.0 release.

5.1.6 Linker files

The Kinetis SDK contains linker control files (or simply linker files) for each supported tool chain and Kinetis MCU device.

5.1.7 Utilities

The utilities directory contains useful software utilities such as a debug console.
5.2 Board configuration

The board directory in the Kinetis SDK is mainly used for the board-specific configuration and pin muxing. The board directory also contains software components specific to the boards such as Audio Codecs.

5.3 Demo applications

The example applications demonstrate the usage of the driver libraries and other integrated software solutions on supported development systems. For details, see the Kinetis SDK v.1.1 Demo Applications User’s Guide (document KSDK11K201MDEMOUG).

5.4 Other integrated software solutions

The Kinetis SDK is designed for easy integration with other software solutions such as OS kernels, USB stacks, and file systems.

5.4.1 USB stack

A Freescale USB stack is integrated with the Kinetis SDK and was tested both with and without an OS through the OS abstraction layer. For details, see the Integration of the USB Stack and Kinetis SDK.

5.4.2 File System

A FAT file system is integrated with Kinetis SDK and can be used to access either the SD card or the USB memory stick when the SD card driver or the USB Mass Storage Device class implementation is used.

5.4.3 RTOS

The Kinetis SDK is pre-integrated with Freescale MQX RTOS, FreeRTOS, µC/OS-II, and µC/OS-III. OS abstraction layers are implemented for these RTOSes.

6 Known Issues

6.1 Maximum file path length in Windows® OS 7

Windows® OS 7 imposes a 260 character maximum length for file paths. When installing the Kinetis SDK, place it in a directory close to the root to prevent file paths from exceeding the maximum character length specified by Windows® OS. The recommended location is the C:\Freescale folder.
6.2 No spaces in the Kinetis SDK installation

The Freescale MQX RTOS build uses batch files, which do not work when there are spaces in the file path.

6.3 USB HUB Power Supply

The external power supply of the USB HUB must be provided before it can be used.

6.4 IAR 7.20.2 Download Issue

Downloading will fail using the flash loader provided by IAR in versions prior to 7.20.5. K21F120M is not supported publicly before version 7.20.5.

6.5 Installer Issue

Note that the Linux® operating system installer was tested only on a host with Ubuntu 12.04 and Ubuntu 14.04.

6.6 USB Audio Device Noise

There is noise when running the USB audio device example in K21F120M due to poor clock accuracy of the CSTCE8M00G55-R0 crystal oscillator.
7 Revision History

This table summarizes revisions to this document.

<table>
<thead>
<tr>
<th>Revision number</th>
<th>Date</th>
<th>Substantive changes</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>1/2015</td>
<td>Initial release</td>
</tr>
</tbody>
</table>
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