

# TIPS FOR SILICON BRING-UP OF QORIQ LS1 PROCESSOR FAMILY

APPLICATIONS ENGINEERING



PUBLIC



SECURE CONNECTIONS  
FOR A SMARTER WORLD

# Agenda

- Chip Feature comparison
- Interface specific compatibility
  - Clocking
  - DDR
  - IFC
  - Boot Sources
  - SerDes
  - Other
- Board Design Phase
  - Design Considerations
- Pre-Boot Phase
  - RCW
  - DDR Validation
- SDK Phase
  - Introduction
  - Build
  - Deployment
- Final Phase: Board Boot Up and Beyond ....

# Introduction

- Intended Audience
  - Hardware and software engineers bringing up new boards based on NXP QorIQ LS Family
- Key feature comparison and consideration for common board design for LS1043/LS1046/LS1088
- Brief introduction to pre-boot requirements
- Board debug and validation
- Software development for silicon enablement

# Assumptions

- NOR flash is primary boot location
  - location for RCW, bootloader, Linux
- Bootloader relocates to DDR after initial execution
- Primary Core: Core0
- NXP debug tools used: CodeWarrior, CodeWarriorTAP
- NXP software used: NXP SDK
- No Secure Boot
- Attendees have prior silicon bring up experience

# Frequently Used Acronyms

|      |   |
|------|---|
| IFC  | Integrated Flash Controller                         |
| DDR  | Double Data Rate<br>(interchangeably used with DDR) |
| DDRV | DDR Validation Tool                                 |
| LS   | LayerScape  |
| PBI  | Pre-Boot Initialization                             |
| PBL  | Pre-Boot Loader                                     |
| QCVS | QorIQ Configuration and Validation Suite            |
| RCW  | Reset Configuration Word                            |
| SDK  | Software Development Kit                            |

# CodeWarrior Development Suites for Networked Applications

- **Overview**

- Enhance the success of your networked design by utilizing one of the suites from the CodeWarrior Development Suites for Networked Applications. The following are the benefits you will gain from our networking-focused suites

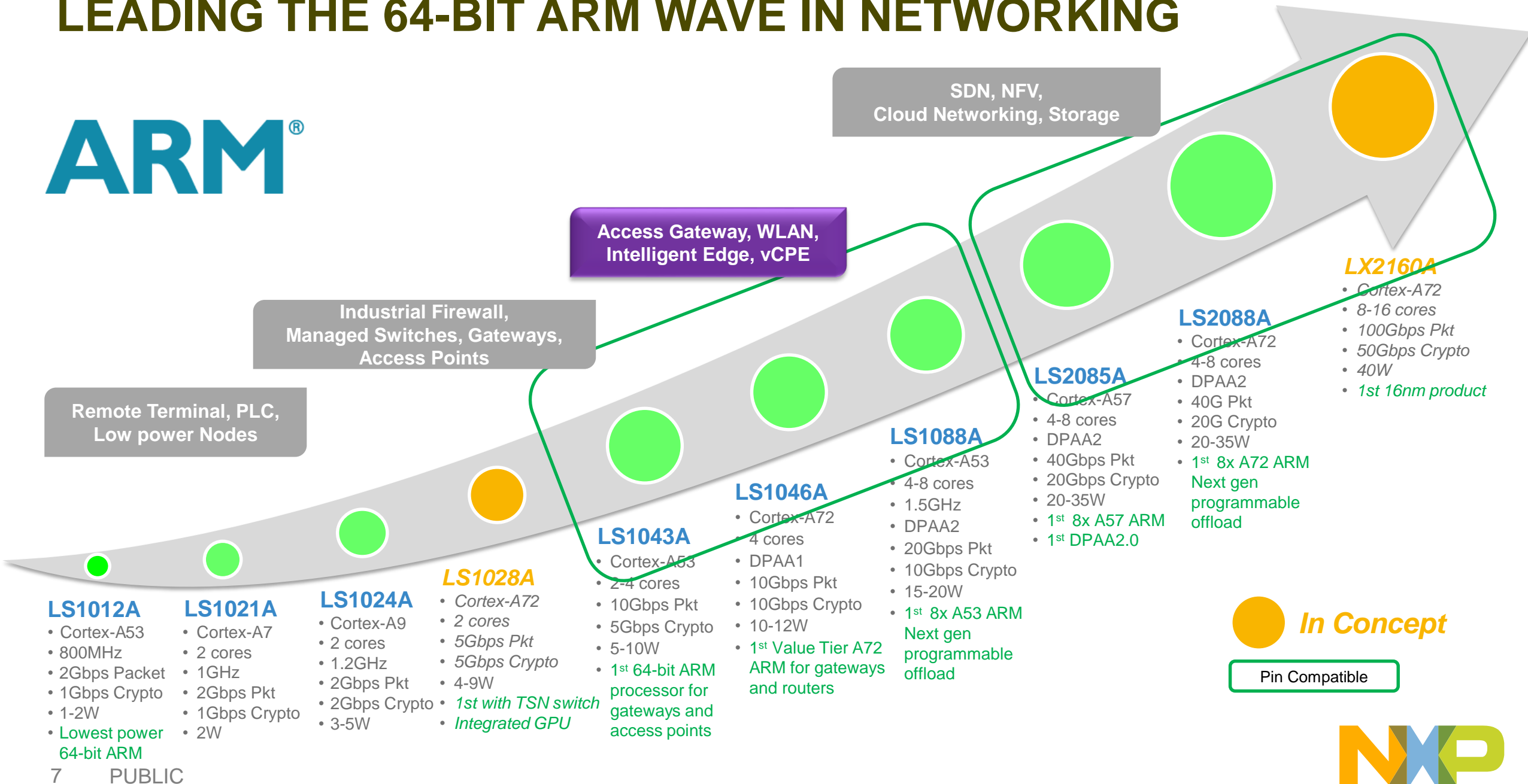
- **Benefit**

- The development suites support multiple architectures including Power Architecture® technology, ARM® technology and StarCore DSP cores
  - Merges the best aspects of Eclipse, GDB, GCC & NXP into a single IDE
  - Use the tools that NXP uses to simplify & speed support
  - Far easier bring-up than uboot brute force
  - Registers name/info from users manual by reg/bit field available in debugger
  - Continuity with all NXP QorIQ processors using CW
  - Multiple debug configs possible to fit every situation
- For more information please visit <http://nxp.com/cw4net>.

# CHIP FEATURE COMPARISON



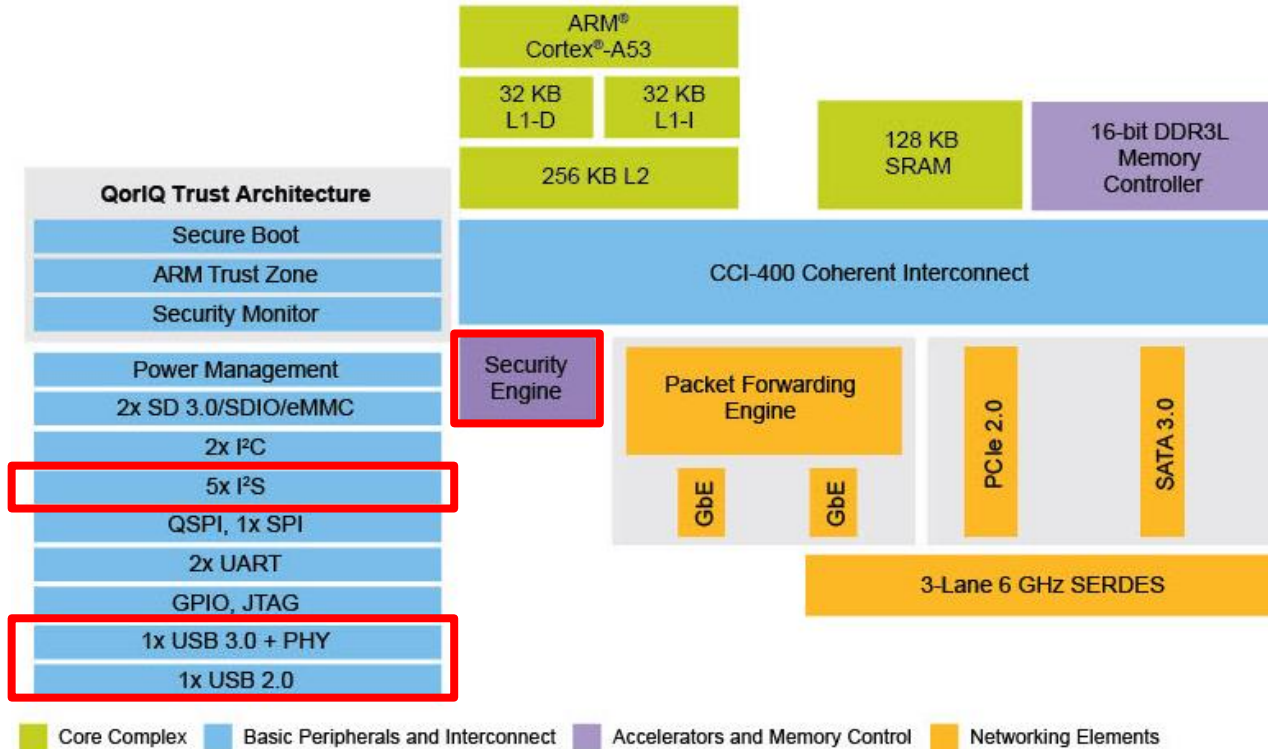
# LEADING THE 64-BIT ARM WAVE IN NETWORKING





# LS1012A: First 64-bit single core ARM Cortex A53 Processor

World's lowest power 64-bit ARM based processor



## Target Applications

- Trust-enabled IoT Gateways
- Consumer NAS
- Mobile NAS
- Ethernet drives for data center storage
- Entry-level broadband Ethernet gateways
- Building and Factory automation

## Development platforms:

- [LS1012A-RDB](#)
- [FRDM-LS1012A](#)

## Core complex

- 1x 64-bit Cortex-A53 with Neon SIMD engine
- Speed up to 800 MHz
- Parity-protected 32 KB L1 instruction and 32 KB L1 data cache
- 256 KB L2 cache with ECC protection

## Basic peripheral and Interconnect

- 1x USB 3.0/2.0 controller with integrated PHY
- 1x USB 2.0 controller with ULPI
- 2x eSDHC controllers supporting SD 3.0, eMMC 4.4 and eMMC 4.5 modes
- Five SAI supporting I2S

## Networking elements

- 2x quad-speed Ethernet MACs supporting 2.5G, 1G, 100M, 10M
- Supports RGMII, SGMII 1G, SGMII 2.5G
- Up to 2 x SGMII supporting 1 or 2.5 Gbps
- 1x PCI Express Gen 2 controller
- 1x SATA Gen 3.0 controller

## Accelerators and Memory Control

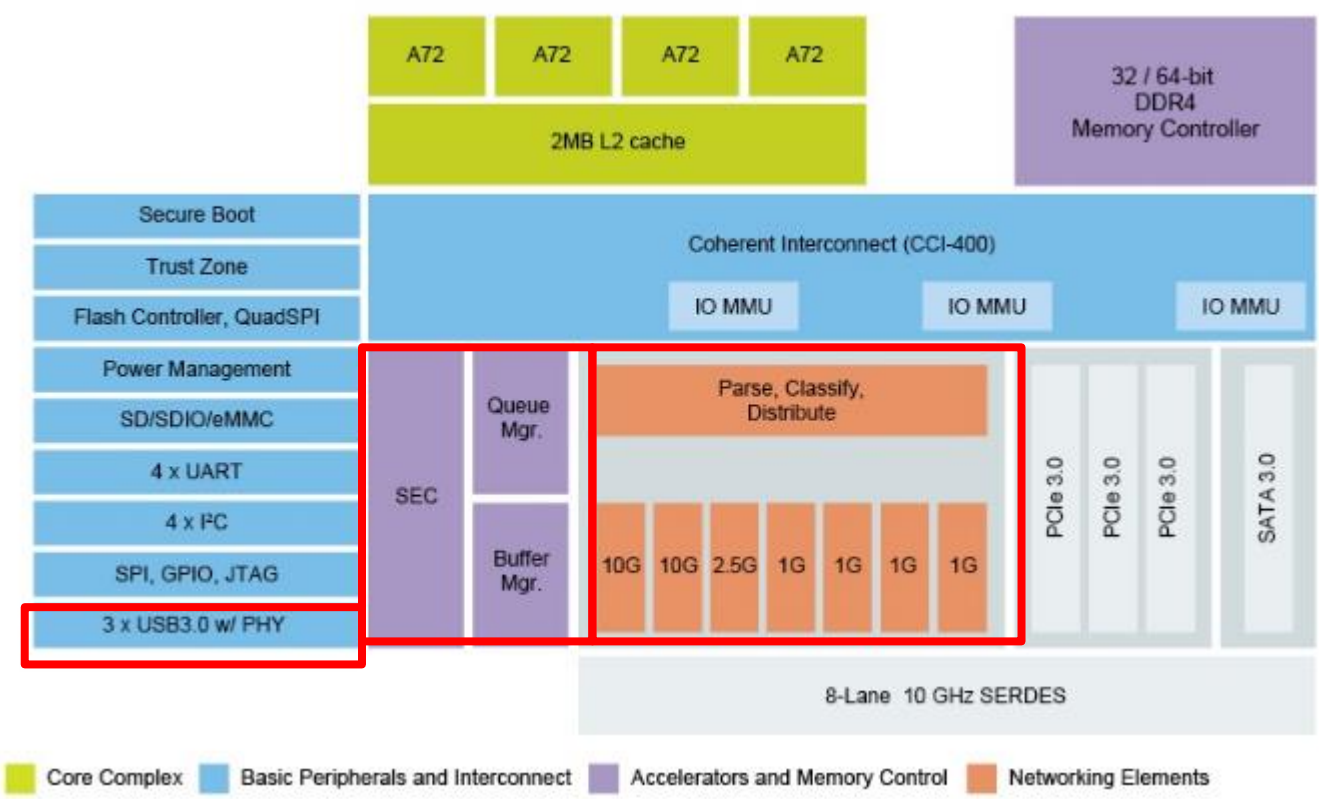
- 1x 16-bit DDR3L Controller up to 1.0 GT/s
- Security Engine (SEC)
- QorIQ Trust architecture: Secure boot, ARM Trust zone and security monitor

## Qualification

- Commercial and extended temperature

# LS1026/46A: Dual/Quad ARM Cortex A72 Processor

High Performance SoC for Virtualization



**Target Applications:**

- Enterprise routers and switches
- Linecard controllers
- Network attached storage
- Security appliances
- Virtual customer premise equipment (vCPE)
- Service provider gateways
- Single board computers

**Development platforms:**

- [LS1046A-RDB](#)

**Core complex**

- 4x 32/64-bit Cortex-A72 with Neon SIMD engine
- Speed up to 1800 MHz
- Parity and ECC protected 48 KB L1 instruction and 32 KB L1 data cache
- 2 MB L2 cache with ECC protection

**Basic peripheral and Interconnect**

- 3x USB 3.0 controllers with integrated PHY
- 1x eSDXC controllers supporting SD 3.0, and eMMC 4.5 modes

**Networking elements**

- Packet parsing, classification, and distribution
- Queue Management for scheduling, packet sequencing and congestion management
- Hardware buffer management for buffer allocation and de-allocation
- Up to five SGMII supporting 1 Gbps
- Up to three SGMII supporting 2.5 Gbps
- Up to two XFI supporting 10 Gbps
- Up to one QSGMII
- 3x PCI Express Gen 3 controller
- 1x SATA Gen 3.0 controller

**Accelerators and Memory Control**

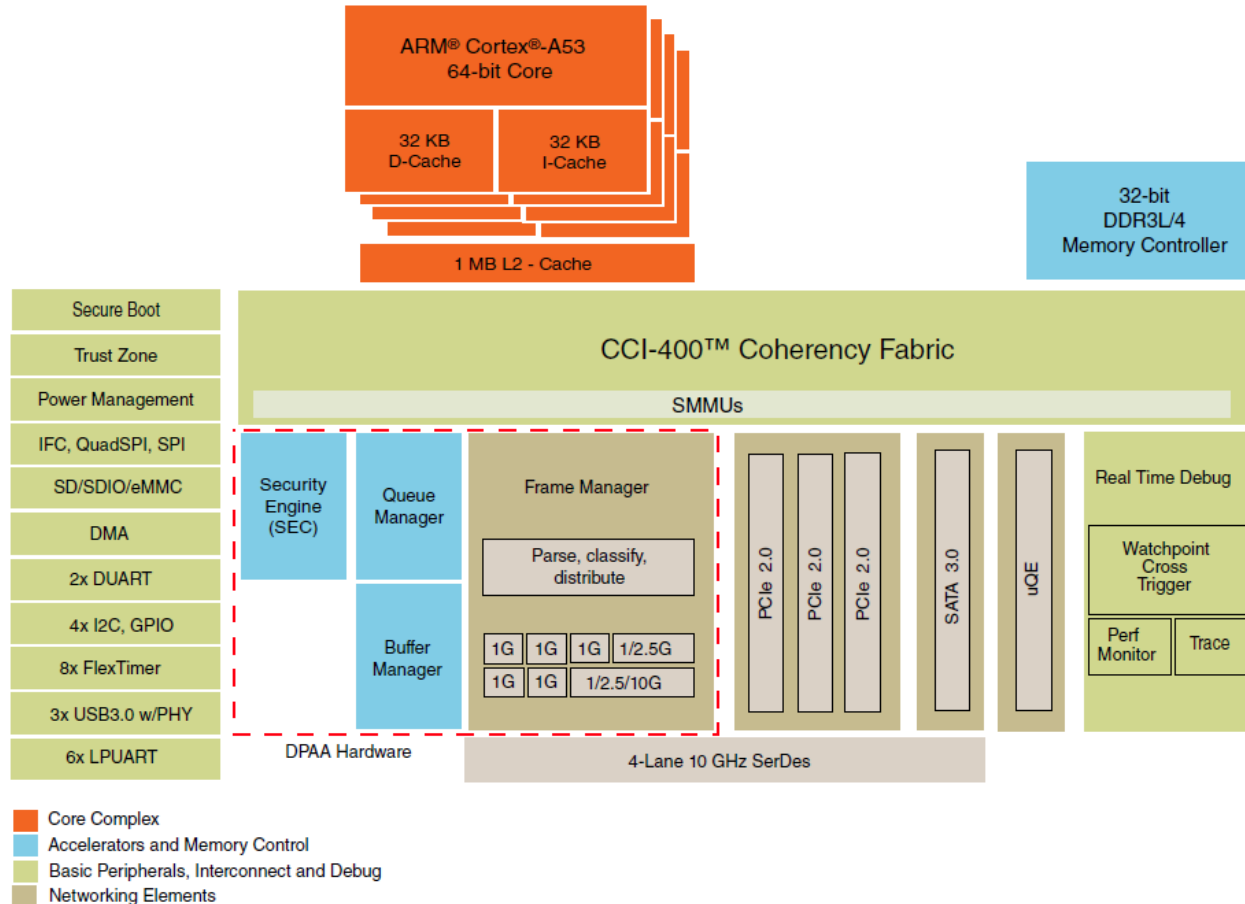
- 1x 32-bit DDR4 Controller with ECC support up to 2.1 GT/s
- Security Engine (SEC)
- QorIQ Trust architecture: Secure boot, ARM Trust zone and security monitor

**Qualification**

- Commercial and extended temperature



# LS1043A



## Processor

- 4x A53, 64b, up to 1.6GHz
- 1MB L2 cache shared by all cores (and platform elements)

## Memory Subsystem

- 32b DDR3L/4 Controller with ECC up to 1600MHz

## CCI-400 Switch Fabric

- Advanced VM hardware support

## High Speed Serial IO

- 3x PCIe Gen2 Controllers
- 1x SATA 3.0
- 3x USB 3.0 with PHY

## Network IO

- 1x10G; 1x QSGMII; 2x 2.5G SGMII; 4x 1G SGMII; 2x RGMII
- Proven Packet Parse/Classify/Distribute
  - Up to 2.5Gbps IMIX
  - IPSec, GRE, CAPWAP, DTLS Offload
  - Lossless Flow Control

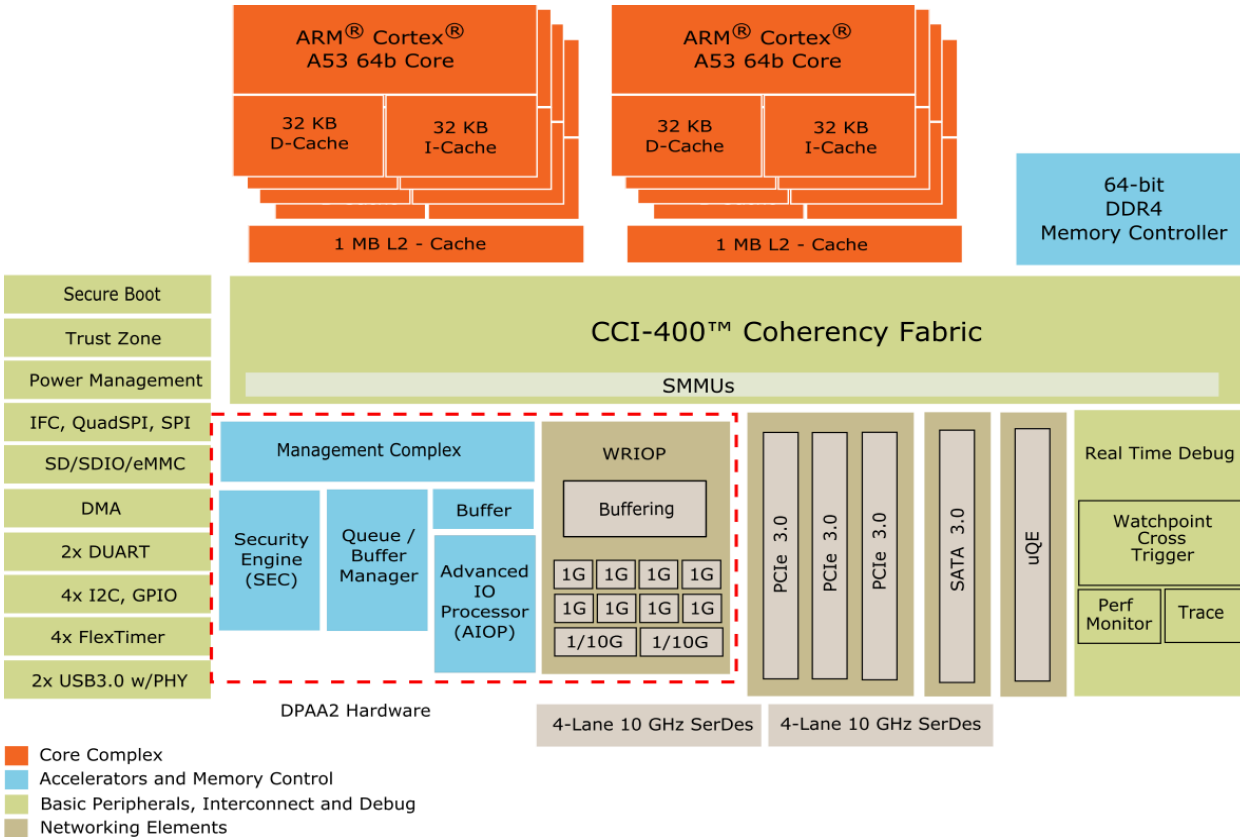
## Device

- 28HPM Process
- 21x21 mm, 621 FC-PBGA, 0.8mm pitch
- 23x23 mm, 780 FC-PBGA, 0.8mm pitch

## Datapath Acceleration

- SEC- crypto acceleration
- L2/3 & Custom Classification
- Tunnel Header Offload
- Reassembly
- Traffic Management & Shaping

# LS1088A



## General Purpose Processing Layer

- 4 or 8 x ARM A53 CPUs, 64b, 1.6GHz
  - 1MB L2 cache/ cluster
- HW L1 & L2 Prefetch Engines
- Neon SIMD in all CPUs

## Memory Subsystem

- 64b DDR4 up to 2.1GT/s

## CCI-400 Switch Fabric

- Advanced VM hardware support

## Advanced I/O Processor

- Programmable packet handling

## High Speed I/O

- 3x PCIe Gen3 controllers
- SATA 3.0, 2 x USB 3.0 with PHYs

## Network I/O

- 2x 10GbE + 8x1G
- 2x10G; 2x QSGMII; 2x 2.5G SGMII; 4x 1G SGMII; 2x RGMII
- XFI/KR and SGMII/KX
- MACSec on up to 4x 1GbE
- uQE for HDLC, T1/E1 support

## Industrial connectivity

- Ethernet, Serial (RS485/422), uQE (for additional serial fieldbus apps)

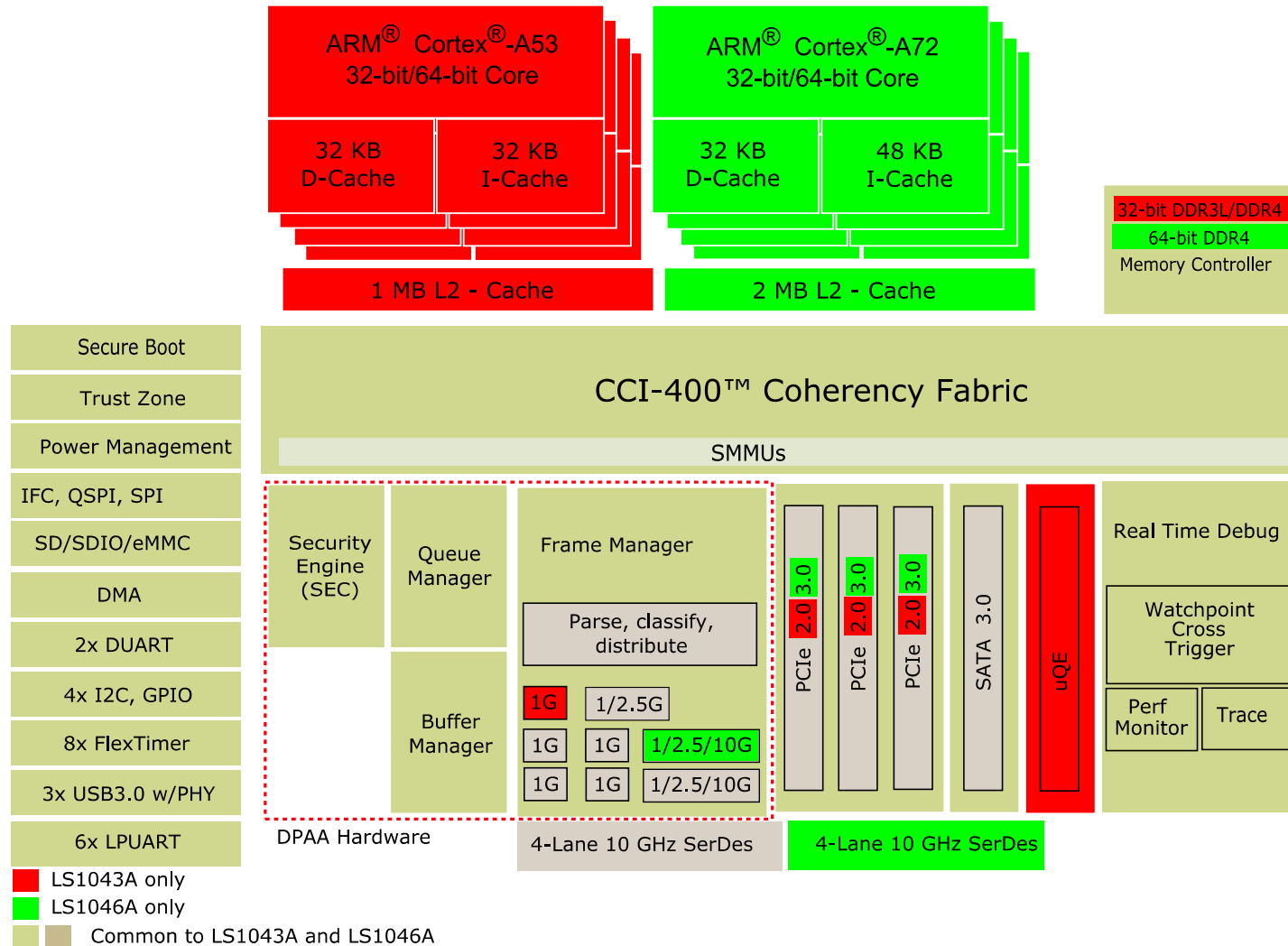
## Device

- 28HPM Process
- 23x23 mm, 780 FC-PBGA, 0.8mm pitch

## Security

- Hardware – Encryption (IPSec)
- Secure Boot
- Trust Zone & Trust Architecture
- MACSec support

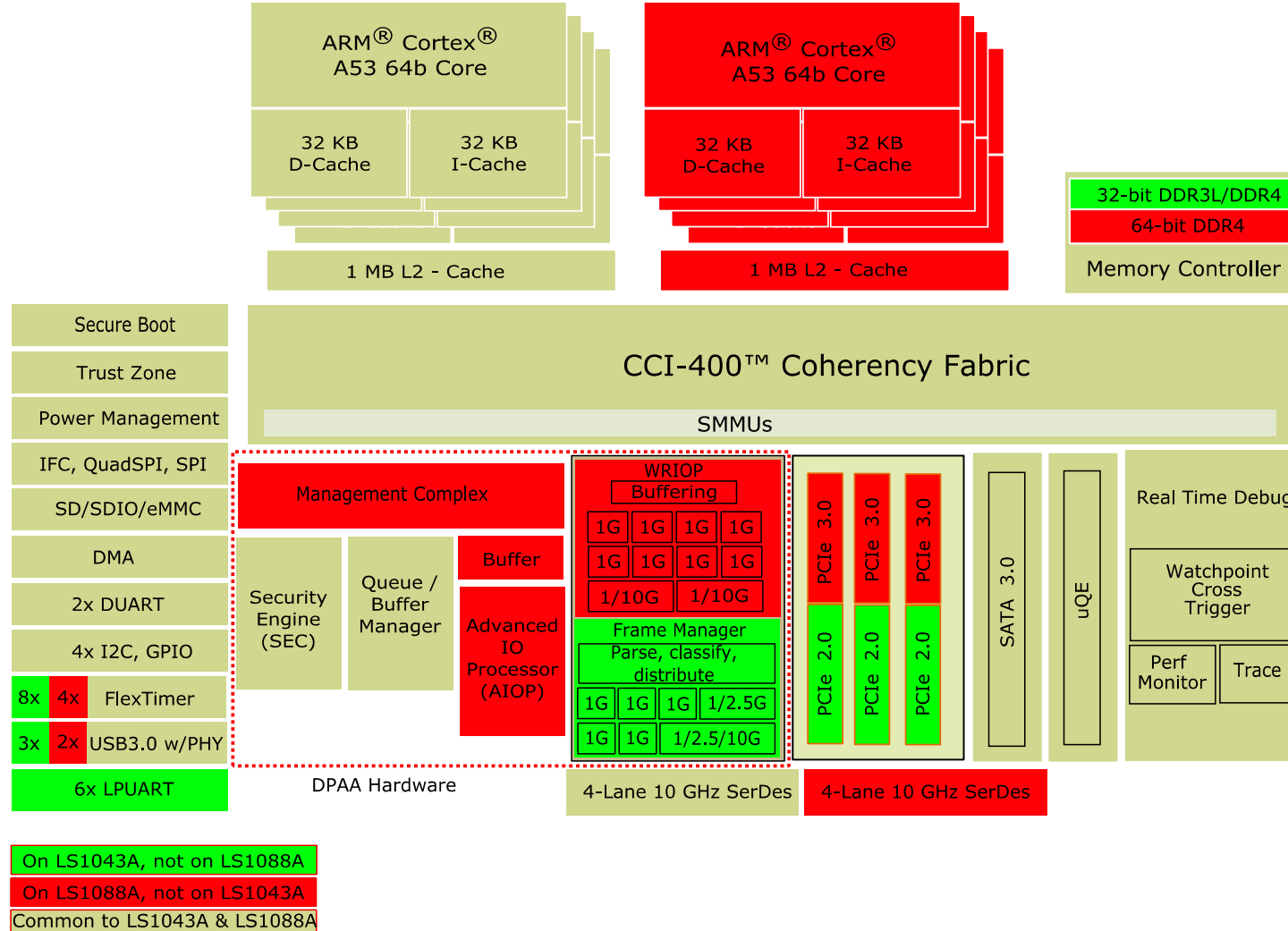
# Comparison of LS1043A and LS1046A



## Major highlights

- LS1043A has four A53 cores
- LS1046A has four A72 cores
- LS1043A has 32 bit DDR3L/4 controller w/ ECC
- LS1046A has 64 bit DDR4 controller w/ ECC
- LS1043A supports three controllers of PCIe Gen 2.0, RC mode only
- LS1046A supports three controllers of PCIe Gen 3.0, with RC and EP mode
- LS1043A has 4 lane SerDes
- LS1046A has 8 lane SerDes

# Comparison of LS1043A and LS1088A



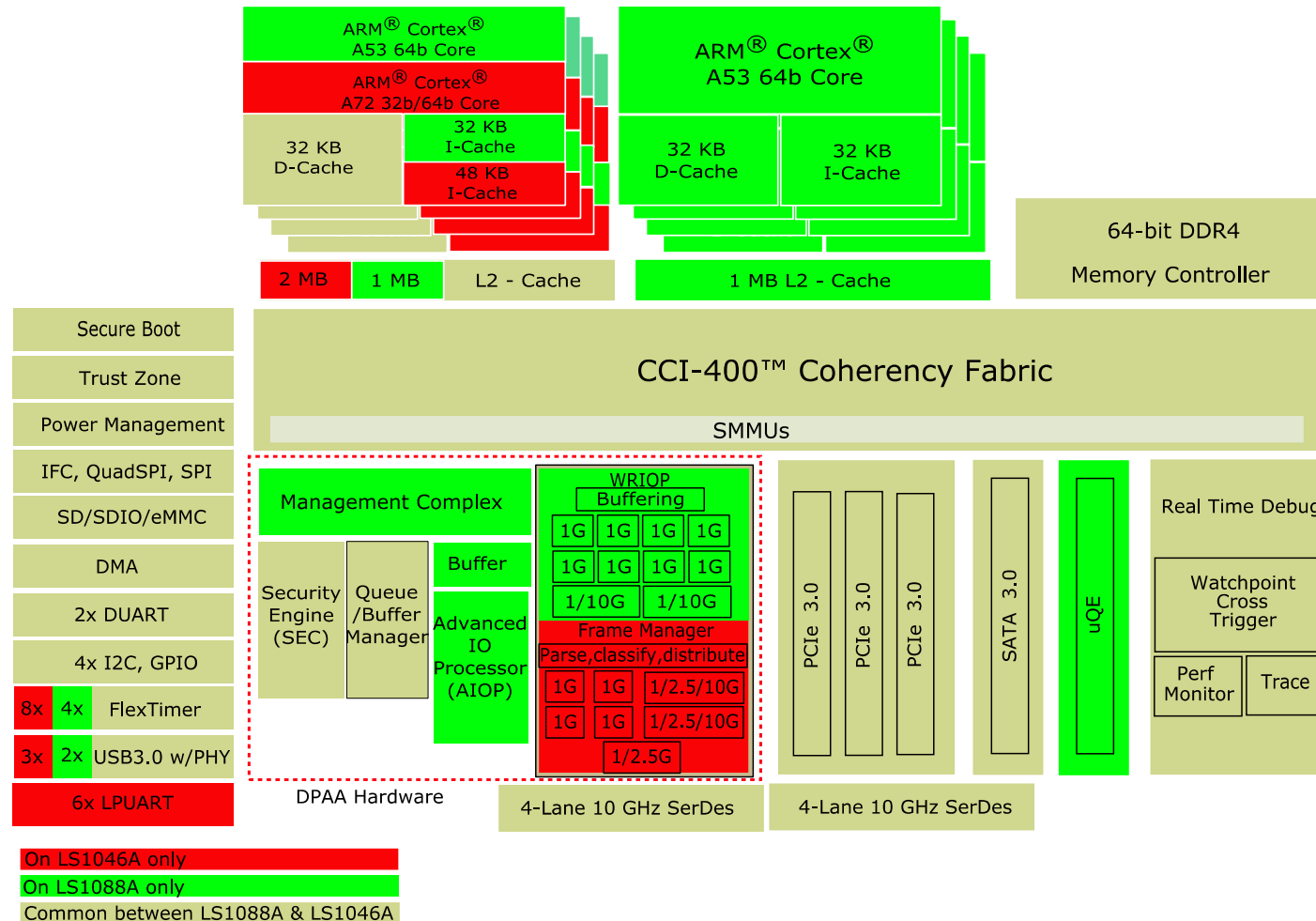
## Major highlights

- LS1043A has four A53 cores
- LS1088A has eight A53 cores
- LS1043A has 32 bit DDR3L/4 controller w/ ECC
- LS1088A has 64 bit DDR4 controller w/ ECC
- LS1043A supports three controllers of PCIe Gen 2.0, RC mode only
- LS1088A supports three controllers of PCIe Gen 3.0, with RC and EP mode
- LS1043A has 4 lane SerDes
- LS1088A has 8 lane SerDes
- LS1043A has DPAA 1.x
- LS1088A has DPAA 2.0
- LS1043A has IFC 1.x
- LS1088A has IFC 2.x

# Comparison of LS1046A and LS1088A

## Major highlights

- LS1046A has four A72 cores
- LS1088A has eight A53 cores
- LS1046A has IFC 1.x
- LS1088A has IFC 2.x
- LS1043A has DPAA 1.x
- LS1088A has DPAA 2.0



# BOARD DESIGN PHASE



# Finding the right collateral

- All information is available on NXP.com
- [Product page](#)
- [Reference design board](#)
- [Collateral needed](#)
  - *QorIQ LS1043A Reference Manual*
  - *QorIQ LS1046A Reference Manual*
  - *QorIQ LS1088A Reference Manual*
  - *QorIQ LS1043A, LS1023A Data Sheet*
  - *QorIQ LS1046A, LS1026A Data Sheet*
  - *QorIQ LS1088A Data Sheet*
  - *AN5012 - LS1043A Design Checklist*
  - *AN5252 - LS1046A Design Checklist*
  - *AN5144 - LS1088A Design Checklist*
  - *AN5097 - Hardware and Layout Design Considerations for DDR4 SDRAM memory interfaces*
  - *AN5226 – Common Board Design for LS1046A, LS1043A and LS1088A Processor*

# Design Considerations

- Power supply requirements
- Boot source
  - IFC: NOR Flash, NAND Flash
  - QSPI
  - eSDHC/MMC
- Using CPLD/FPGA for reset and signal routing
  - Reset\_req\_b to be connected to FPGA/CPLD
- Clock sources
  - SYSCLK and DDRCLK must always be driven
  - ECn\_GTX\_CLK125 must be driven if RGMII mode is used on the respective ECn port
  - SerDes reference clocks (SDn\_REF\_CLKn and SDn\_REF\_CLKn\_B) must be driven if the corresponding SerDes bank is enabled in the RCW
  - Optional input clock sources include RTC, USBCLK, and TSEC\_1588\_CLK\_IN

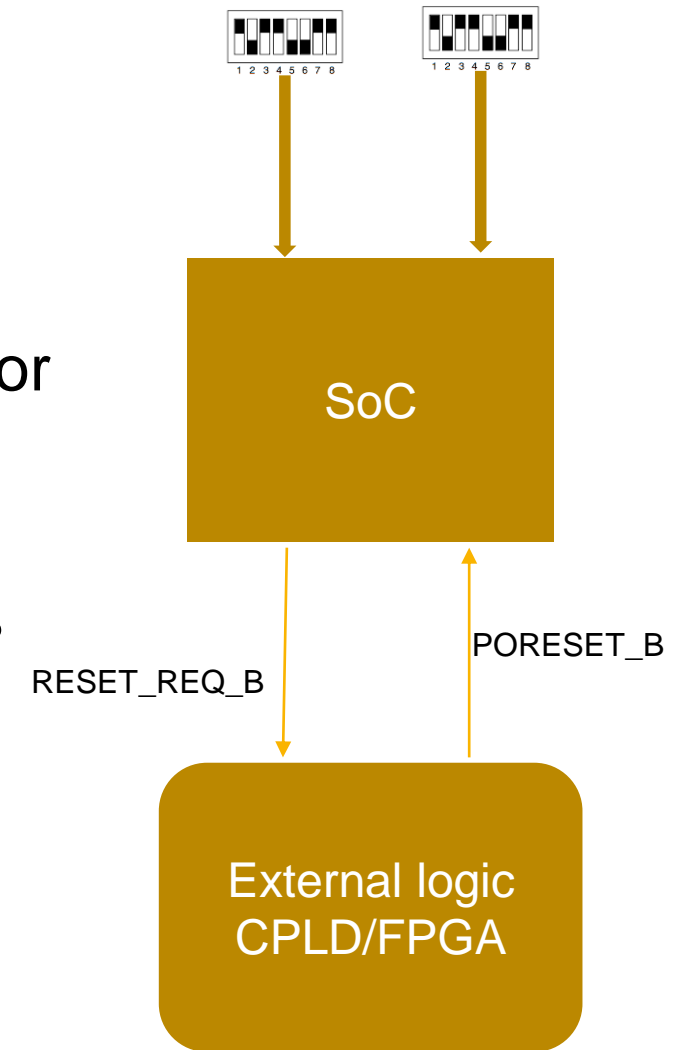
# PRE-BOOT PHASE



# PORESET Signals

- Various chip functions are initialized by sampling certain signals during the assertion of PORESET\_B.
- These power-on reset (POR) inputs are pulled either high or low during this period.
- While these pins are generally output pins during normal operation, they are treated as inputs while PORESET\_B is asserted.

| Reset configuration name | Functional interface | Functional Signal Name | Default        |
|--------------------------|----------------------|------------------------|----------------|
| cfg_rcw_src[0:7]         | IFC                  | IFC_AD[8:15]           | 1111 1111      |
| cfg_rcw_src[8]           | IFC                  | IFC_CLE                | 1 <sup>1</sup> |
| cfg_ifc_te               | IFC                  | IFC_TE                 | 1              |
| cfg_dram_type            | IFC                  | IFC_A[21]              | 1              |
| cfg_gpinput[0:7]         | IFC                  | IFC_AD[0:7]            | 1111 1111      |
| cfg_eng_use0             | IFC                  | IFC_WE0_B              | 1              |



# RCW, PBI and PBL

- **PBL:** Preboot loader, a state machine logic responsible for reading RCW and PBI from external memory source, checking their integrity and loading the registers with information contained in RCW and PBI prior to boot. PBL can read RCW and PBI from IFC (NOR and NAND FCM), eSDHC/eMMC and qSPI.
- **RCW:** 512 bit long sequence of data containing configuration information. Read from external memory(normal operation). Ex: PLL, SerDes, DDR and pin muxing information
- **PBI:** PBI are set of commands/instructions that can be used to set up DDR and other interfaces, implement errata etc.
- **Note:** You can perform a RCW override using CodeWarrior. This will write RCW values from a file on your PC to the SoC before HRESET thus overriding RCW fetched from `cfg_rcw_src` configuration

# Description of PBL functionality

- **PBL RCW phase**
  - PBL starts to load RCW data from specified source (cfg\_rcw\_src[0:n])
  - PLLs begin to lock
  - All 512 bits of RCW are loaded
  - Sequence completes
- **PBL PBI phase**
  - PBL switches to platform clock
  - PBL checks RCW[PBI\_SRC]
    - **If PBI is disabled**, then PBL is done
    - **If PBI is enabled**, proceed to fetch PBI data from the source.
  - PBL finishes the PBI
  - System Ready state
  - Peripheral interfaces are released to accept external requests
  - Release the core0 to fetch instruction if RCW[BOOT\_HO] is 0.
    - The boot code location is specified in SCRATCHRW2 (for non-secure boot) and SCRATCHRW1 should be 0
    - PBI should write the boot location to scratch registers in LS1 devices
  - ASLEEP negates
- For both RCW and PBI phase, if there is any error, the boot stops and /RESET\_REQ is asserted
- PBI can also be used to implement any features or errata
- FTF-DES-N1832 on how to build and deploy RCW and PBI

# POR Configs

| Significant POR configs | LS1046A  | LS1043A | LS1088A |
|-------------------------|--|---------|---------|
| Cfg_rcw_src             | cfg_rcw_src[0:8] of LS1046A/ LS1043A is mapped to cfg_rcw_src[1:8, 0] of LS1088A.<br>For common board <i>cfg_rcw_srcn</i> should have provision for both pull up/down. |         |         |
| Cfg_eng_use[0:2]        | Mapped to same balls on all three devices. Pull high or low as per input clock selection.  |         |         |
| Cfg_dram_type           | Should be pulled low for DDR4 in LS1043A.<br>Pull low in LS1046A and LS1088A   |         |         |

# Boot Sources

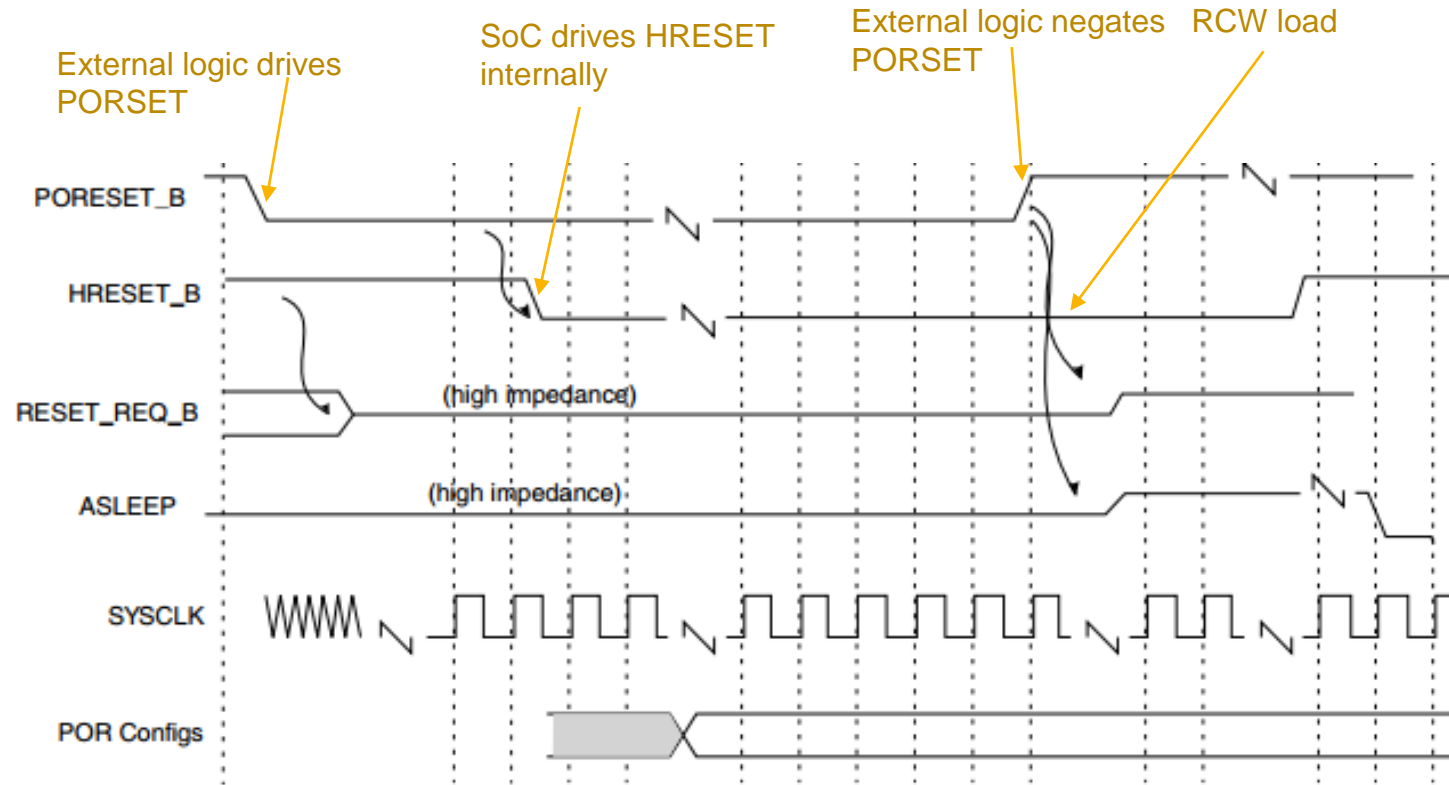
| Boot Sources              | LS1046A | LS1043A | LS1088A | Remarks   |
|---------------------------|---------|---------|---------|---|
| NOR Flash memory (8 bit)  | ✓       | ✓       | ×       |   |
| NOR Flash memory (16 bit) | ✓       | ✓       | ✓       | 16 bit NOR flash is not pin compatible across the three devices, it will require a complex on board logic to provision booting. |
| NAND Flash Memory         | ×       | ✓       | ×       | Bootting from NAND device is not supported on LS1046A and LS1088A   |
| SD/eMMC                   | ✓       | ✓       | ✓       | Fully compatible  |
| QSPI                      | ✓       | ✓       | ✓       | Fully compatible  |

Since only 8 bit NAND interface is pin compatible, hence no IFC boot mechanism is common across the three devices. It is recommended to use SD/eMMC or QSPI as boot source and storage device on the common board.

However if a common board is designed to support LS1043A and LS1046A only, IFC NOR may be considered.



# Power up sequence



- The successful completion of the reset sequence is indicated by the ASLEEP signal being driven low as shown in the timing diagram
- If this does not occur, then there is an issue with the reset sequence – usually with some basic hardware function – and it must be debugged using low-level hardware debug tools and techniques (logic analyzer and oscilloscopes)

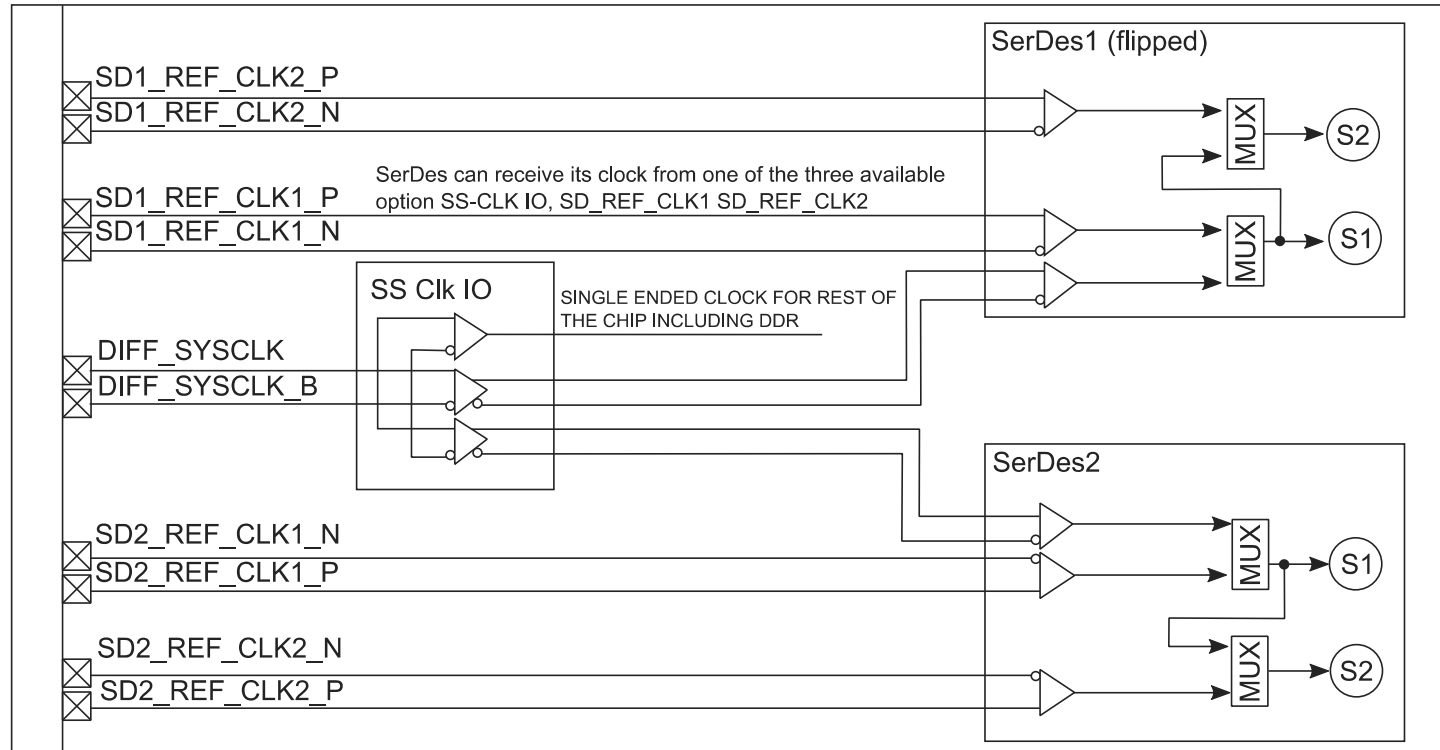
# Power up Sequence (continued)

- Things to check if the Power up sequence does not complete include:
  - **Voltage Rails:** Ensure the all the required voltage levels are provided and meet the specified levels and tolerances
    - Ensure that the recommended power rail sequence is followed
  - **SYSCLK:** Ensure it is present and meets the voltage level, slew rate, frequency, duty cycle, and jitter requirements specified
  - **Reset Signals:** Ensure PORESET is driven for a minimum of 1 ms and that it is driven before the core and platform voltages are powered up
    - If HRESET is driven externally, ensure it is released as expected; if driven just by the SoC, confirm it is released after PORESET desertion
  - Confirm the **RCW device is being read** after ASLEEP is driven high
    - If not, check that the cfg\_rcw\_src signals are driven as expected when the PORESET signal is released
  - **Confirm RCW contents are as expected.** The specifics of the RCW must match the system configuration
  - If the RCW device is blank, a tool such as CodeWarrior must be used to program this. Instructions for doing this are provided in later in another session. However, it is recommended to confirm the hardware operation as much as possible before connecting this tool. Confirming that the LS1043A at least attempts to read the RCW device is a good checkpoint
  - Also good to have a mechanism like a switch, that can stop external logic to assert PORESET on assertion of RESET\_REQ by SoC



# CLOCKING DIFFERENCES

# Clocking - Single source clocking scheme as in LS1088A

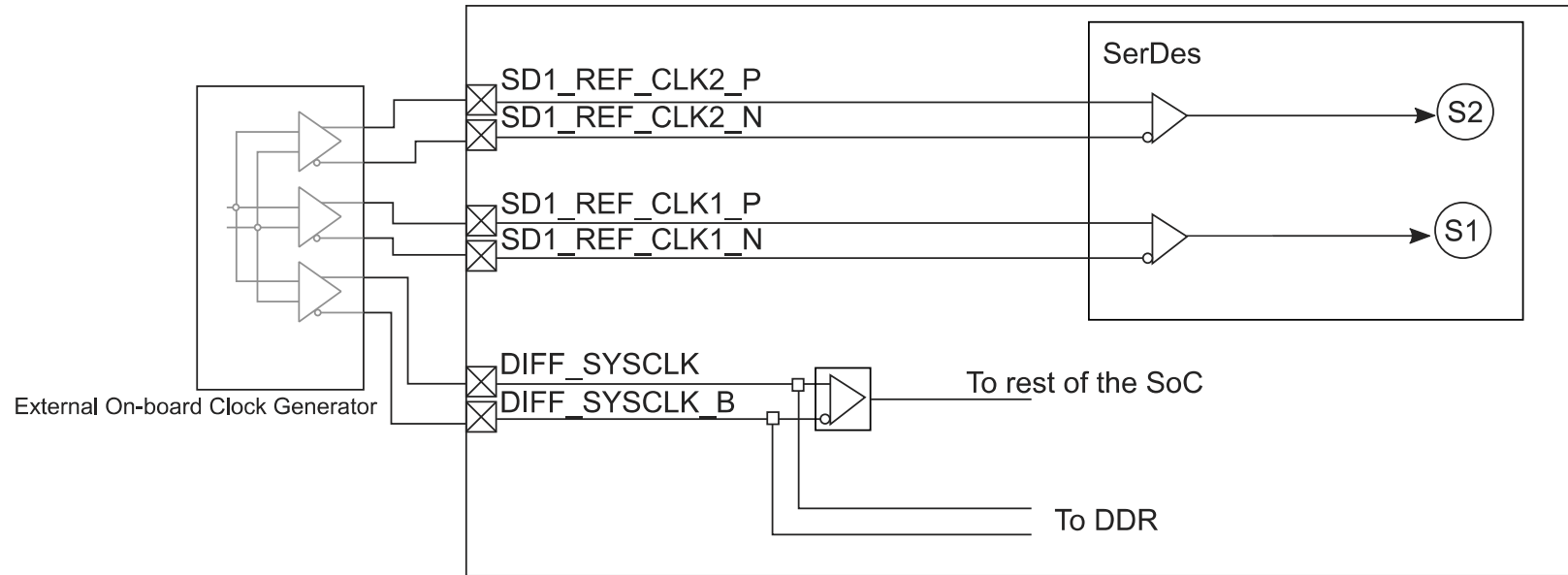


Single clocking scheme in LS1088A

The Differential SYSCLK clock input can feed Core PLLs, Platform PLL, DDR PLL and USB PLL .

Additionally it can be used to feed the four SerDes PLL, selectable option through RCW bits 952, 953, 954 and 955

# Clocking - Single source clocking scheme as in LS1043A

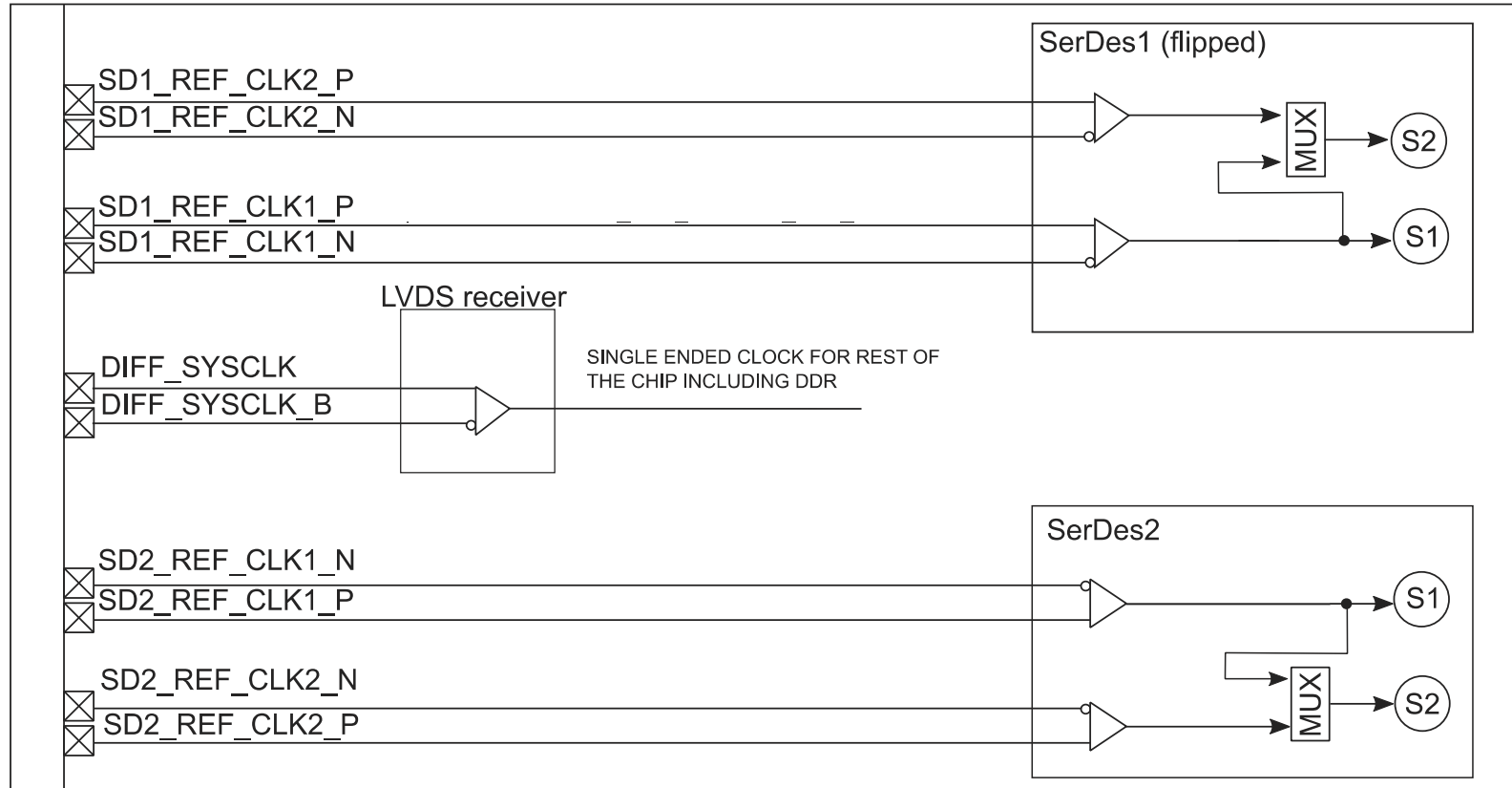


Single clocking scheme in LS1043A

The Differential SYSCLK clock input can feed Core PLLs, Platform PLL, DDR PLL and USB PLL .

The two SerDes PLL require individual clock inputs from board.

# Clocking - Single source clocking scheme as in LS1046A



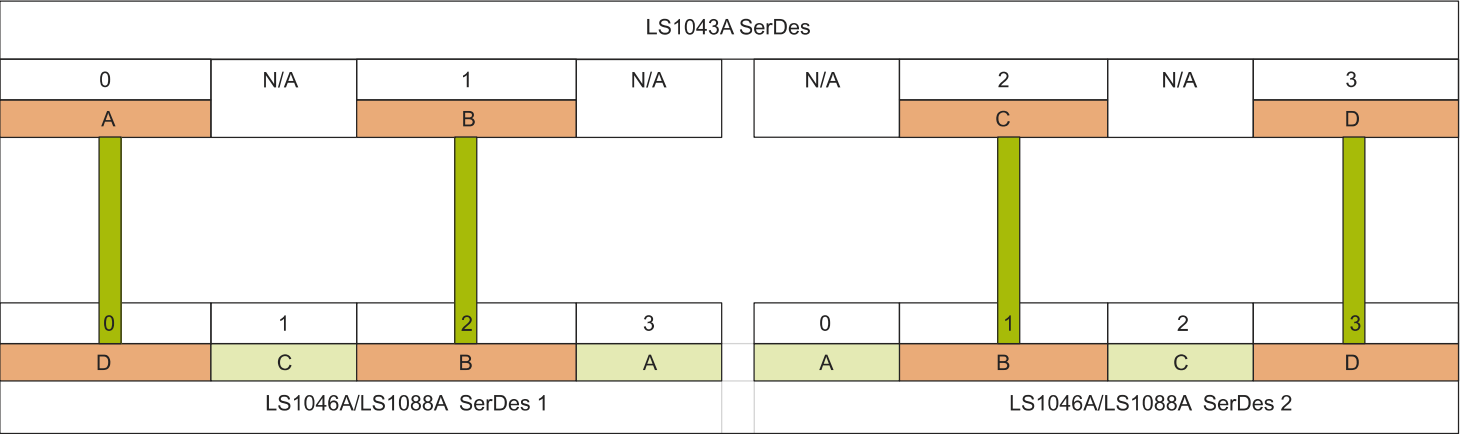
Single clocking scheme in LS1046A

The Differential SYSCLK clock input can feed Core PLLs, Platform PLL, DDR PLL and USB PLL.  
SerDes PLL1 clock input can be used to clock the SerDes PLL2, selectable through RCW bits.

# SERDES

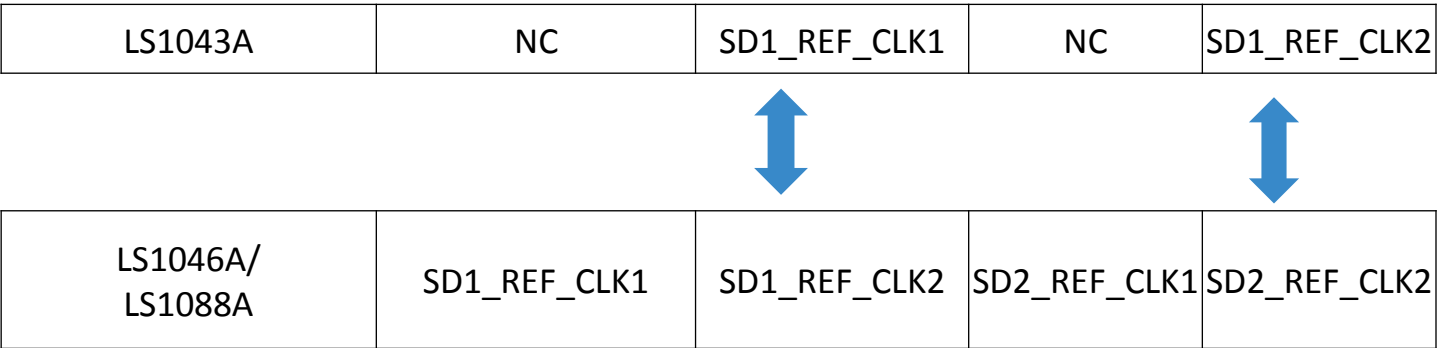
# SerDes

## SerDes Lane mapping



- LS1046A and LS1088A SerDes are pin compatible
- Connect the SerDes reference clocks as per the requirements of chosen SerDes protocol for common board
- Terminate unused SerDes lanes and reference clocks as per the guidelines in design checklist
- SD2\_IMP\_CAL\_RX and SD1\_IMP\_CAL\_TX pins in LS1046A/LS1088A are mapped to NC pins in LS1043A. They should be terminated as per the guidelines in LS1046A/LS1088A datasheet
- SD1\_PLL2\_TPA/TPD and SD2\_PLL1\_TPA/TPD pins in LS1046A/LS1088A are mapped to NC pins in LS1043A. They can be left as NC or terminated to a test point

## SerDes Clock mapping

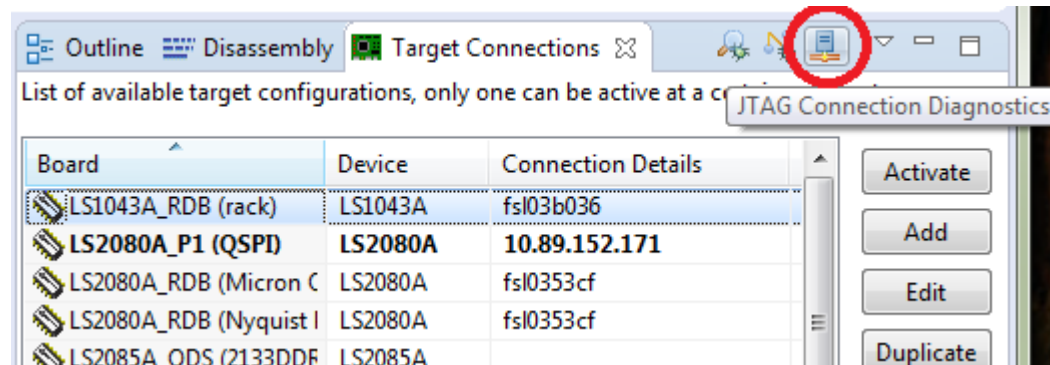




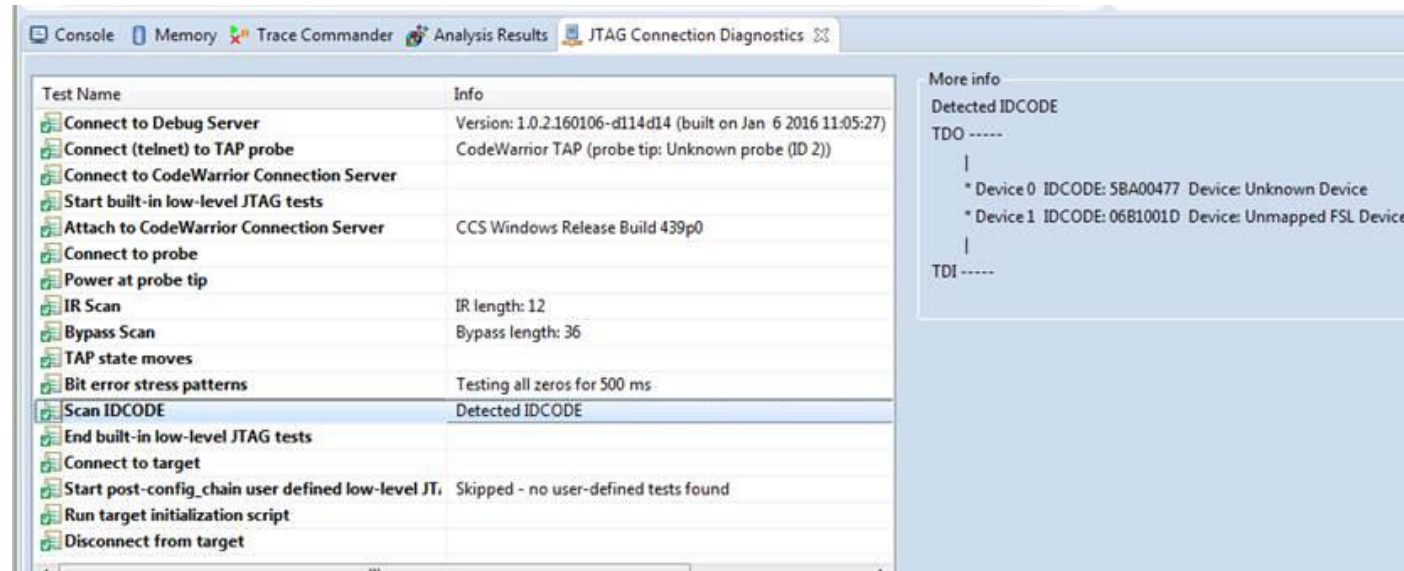
# TOOLS

# CodeWarrior Debug

- Checking your SoC using CCS
- Board must be powered with CodeWarriorTAP connected
- In CW4NET ARMv8 v2016.01, open the Target Connections view, select the Target Connection from the menu (“LS1043A\_RDB (rack)”, in the example below) and click on ‘JTAG Connection Diagnostics’.



# CodeWarrior Debug..contd..



- Clicking on any line of the report will display more information, if available. “Scan IDCODE” shown here.
- This is the recommended method for running JTAG diagnostics in CW ARMv8.

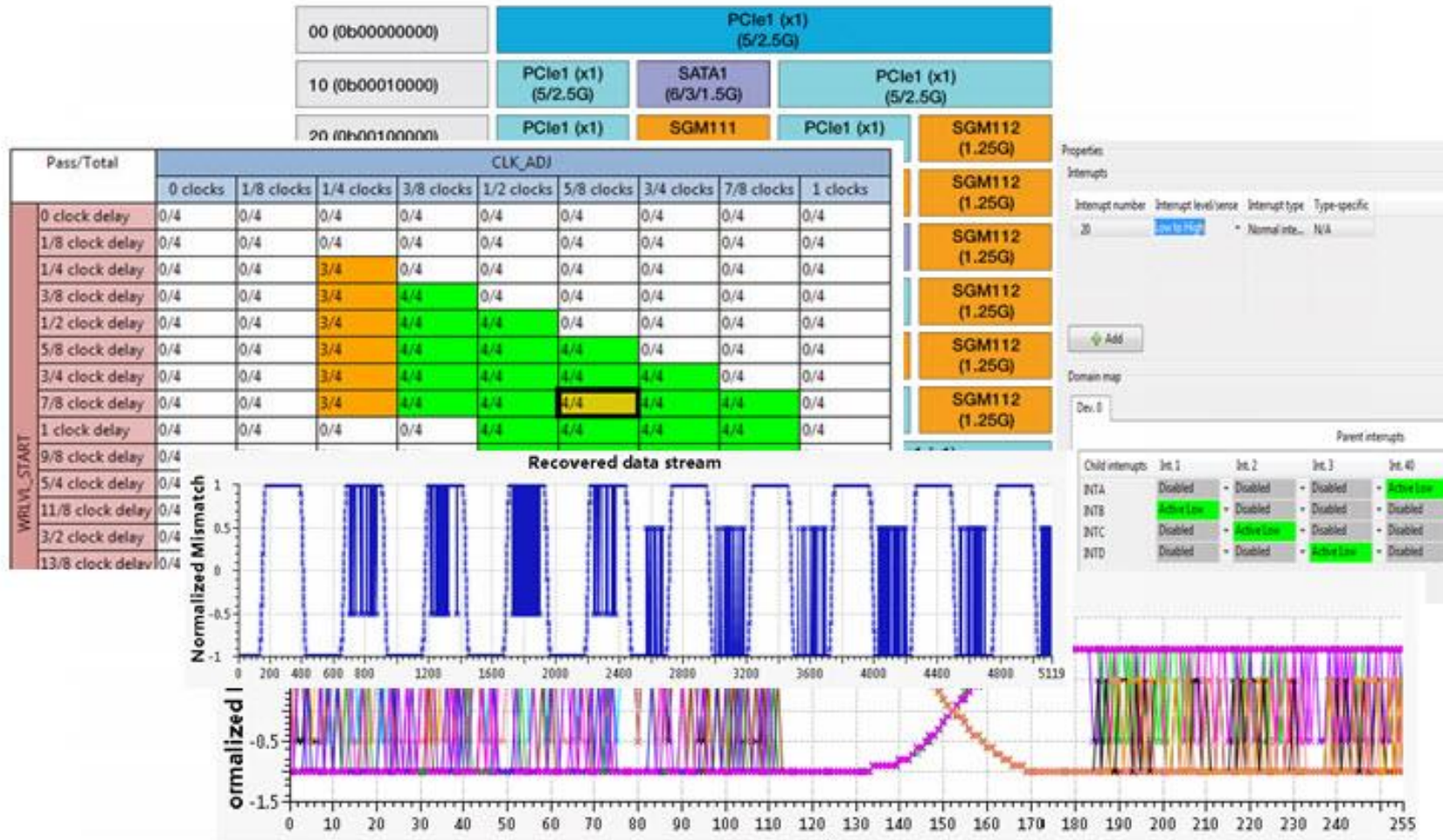
# CodeWarrior Debug contd..

- Create a RCW override file using information in the video link below
  - <http://www.nxp.com/video/how-to-create-a-rcw-override-configuration-file-for-use-in-a-CodeWarrior-qorik-debugger:RCW-QORIQ-DEBUGGER>
- Use the RCW override file to override the RCW using CodeWarrior
  - <http://www.nxp.com/video/how-to-use-qorik-rcw-override-feature-in-codewarrior:HOW-TO-USE-QORIQ-RCW-CODEWARRIOR>
- More details can be found in the User guide for CodeWarrior ARM v8
  - [http://cache.nxp.com/files/soft\\_dev\\_tools/doc/user\\_guide/CWARMv8TM.pdf?fpsp=1&WT\\_TYPE=Users%20Guides&WT\\_VENDOR=FREESCALE&WT\\_FILE\\_FORMAT=pdf&WT\\_ASSET=Documentation&fileExt=.pdf](http://cache.nxp.com/files/soft_dev_tools/doc/user_guide/CWARMv8TM.pdf?fpsp=1&WT_TYPE=Users%20Guides&WT_VENDOR=FREESCALE&WT_FILE_FORMAT=pdf&WT_ASSET=Documentation&fileExt=.pdf)

# DDRv

- Allows configuration of DDR controller memory mapped (in CCSR) registers
- View DDR controller memory mapped registers on a bit field level
- Can read DDR configuration from various sources (memory dump, DIMM's SPD, directly from target [in the making...])
- Generates DDR initialization code in various formats: uBoot data structure, plain C code, GDB script
- Exports DDR registers configuration dump to various formats
- Same advantages as PBL tool
  - Same user experience across processors
  - No need for reference manual
  - Incorporates errata
  - Validates input against known constraints
- DDR validation should be done before SDK phase so as to plug in the right DDR register settings for optimum and stable performance of DDR. Performing DDRv will eliminate border cases where certain boards work while others do not

# Processor Expert Software: QorIQ Configuration and Validation Suite



[http://www.nxp.com/products/software-and-tools/software-development-tools/codewarrior-development-tools/suite-for-networked-applications/qorIQ-configuration-and-validation-suite:PE\\_QORIQ\\_SUITE#](http://www.nxp.com/products/software-and-tools/software-development-tools/codewarrior-development-tools/suite-for-networked-applications/qorIQ-configuration-and-validation-suite:PE_QORIQ_SUITE#)



# DDR Controller

| DDR SDRAM<br>Byte lane | LS1046A<br>LS1088A | LS1043A              |
|------------------------|--------------------|----------------------|
| Byte lane 0            | MDQ[0:7]           | MECC[0:3]<br>+ 4x NC |
| Byte lane 1            | MDQ[8:15]          | MDQ[24:31]           |
| Byte lane 2            | MDQ[16:23]         | MDQ[16:23]           |
| Byte lane 3            | MDQ[24:31]         | MDQ[8:15]            |
| Byte lane 4            | MDQ[32:39]         | 8x NC                |
| Byte lane 5            | MDQ[40:47]         | 8x NC                |
| Byte lane 6            | MDQ[48:55]         | 8x NC                |
| Byte lane 7            | MDQ[56:63]         | 8x NC                |
| ECC lane               | MECC[0:7]          | MDQ[0:7]             |

- LS1043A supports a 32-bit DDR3L/DDR4
- LS1046A/LS1088A support a 64-bit DDR4
- 32-bit DDR4 w/ECC memory is common

Note that one of the byte lane of LS1043A is connected to ECC lane of memory. If user chooses to not use ECC, one of the byte lanes will be unused. Unpopulated byte lane will create stub which can affect signal integrity. User should either use 32-bit DDR4 with ECC OR do a thorough simulation to analyze affects of stubs

- References:
  - AN5226
  - AN5097

# SDK PHASE

Suggested sessions: FTF-DES-N1851,N1834,N1843





# Introduction to SDK

- Software development kit: Linux based dev kit
  - Evaluate and explore SoC processors' features
  - Develop Linux-based solutions
- Contains
  - boot loader: U-Boot
  - Linux kernel
  - user space components
  - tool chain
  - build system
  - package manager
- Based on Yocto project and Poky
- More details can be found at <http://www.nxp.com/knowledgecenter>

# Using Pre-built Images

- Pre-built images for each SDK version are release in the IMAGE ISO
- Download SDK from [www.nxp.com/sdk](http://www.nxp.com/sdk)
- Download, mount and install IMAGE ISO
  - \$ sudo mount -o loop QorIQ-SDK-<version>-<target>-IMAGE-<yyyymmdd>-yocto.iso /mnt/cdrom
  - **For LS1043A:** QorIQ-SDK-V2.0-AARCH64-IMAGE-20160527-yocto.iso
- Contains all images necessary to boot to Linux are available

# Download and install SDK

- Download SDK from [www.nxp.com/sdk](http://www.nxp.com/sdk)
- See “Getting Started with Yocto Project” Section on KnowledgeCenter
- Download, mount and install Source ISO
  - **For LS1043A:** QorIQ-SDK-V2.0-SOURCE-20160527-yocto.iso
  - `$ sudo mount -o loop QorIQ-SDK-<version>-<target>-<yyyymmdd>-yocto.iso /mnt/cdrom`
  - As super user install “install” from /mnt/cdrom (./install)
- Download mount and install cache ISO (\* The *cache* ISO contains the pre-built cache binaries)
  - **For LS1043A:** QorIQ-SDK-V2.0-AARCH64-CACHE-20160527-yocto.iso
- Set up host environment according to Yocto project requirements
- Setup poky for specific board (Assuming we are setting up LS1043RDB)
  - In the build directory execute the following command
  - `. ./fsl-setup-env -m <machine>` (ex: `. ./fsl-setup-env -m ls1043rdb`)
- Perform Builds with bitbake
  - `cd <sdk-install-dir>/build_<machine>`
  - `bitbake <image-target>` ex: `bitbake fsl-image-core`



# Content of the Built Images Directory

- Yocto build produces images for booting U-Boot and Linux
- You can find the built images under:
  - <sdk-install-dir>/build\_<machine>/tmp/deploy/images/<machine>/
- Following images will be available
  - fsl-image-<machine>.ext2.gz.u-boot - ramdisk image that can be loaded with U-Boot
  - fsl-image-<machine>.ext2.gz - gzipped ramdisk image
  - fsl-image-<machine>.tar.gz - gzipped tar archive of the image
  - ulmage-<machine>.bin - kernel binary of the image
  - u-boot-<machine>.bin - U-Boot binary image that can be programmed into board Flash
  - ulmage-<machine>.dtb - device tree binary (dtb)
  - fsl\_fman\_ucode\_<machine>\_<version>.bin - fman ucode for <machine> board
  - hv/hv.ulmage - ulmage for hypervisor
  - hv-cfg/\*/hv.dtb - dtb for hypervisor
  - rcw/\*/rcw\_\*.bin - rcw

# Building kernel itb FIT image

- LS1043A uses Flattened Image Tree (FIT) format for booting to Linux
- Contains the following:
  - Linux Kernel
  - Device tree blob
  - Root file system
- Build Instructions:
  - `bitbake -c compile -f fsl-image-kernelitb`
  - `bitbake fsl-image-kernelitb`
- New itb can be found in the build directory
  - `build_<machine>/tmp/deploy/images/<machine>/`

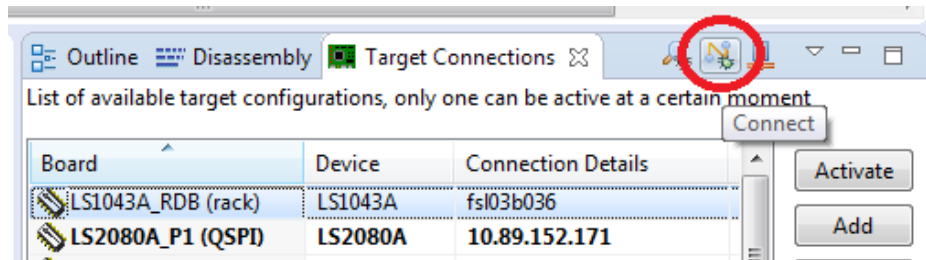
# Memory Map

| Start address | End address | Image   | Max size |
|---------------|-------------|---|----------|
| 0x60000000    | 0x6001FFFF  | RCW (current bank)  | 128KB    |
| 0x60100000    | 0x6017FFFF  | u-boot (current bank)   | 512KB    |
| 0x60300000    | 0x6031FFFF  | Fman ucode (current bank)                                       | 128KB    |
| 0x61100000    | 0x6203FFFF  | Linux.ulimage, Device Tree and Ramdisk (current bank) FIT Image | 15MB     |
| 0x64000000    | 0x6401FFFF  | RCW (alt bank)  | 128KB    |
| 0x64100000    | 0x6417FFFF  | u-boot (alt bank)   | 512KB    |
| 0x64300000    | 0x6431FFFF  | Fman ucode (alt bank)   | 128KB    |
| 0x65100000    | 0x6603FFFF  | Linux.ulimage, Device Tree and Ramdisk (alt bank) FIT Image     | 15MB     |

- Two ways to transfer images to the board
  - CodeWarrior
    - If you have a blank board
  - TFTP
    - Assume working U-Boot in current bank
    - Flash to altbank from current bank

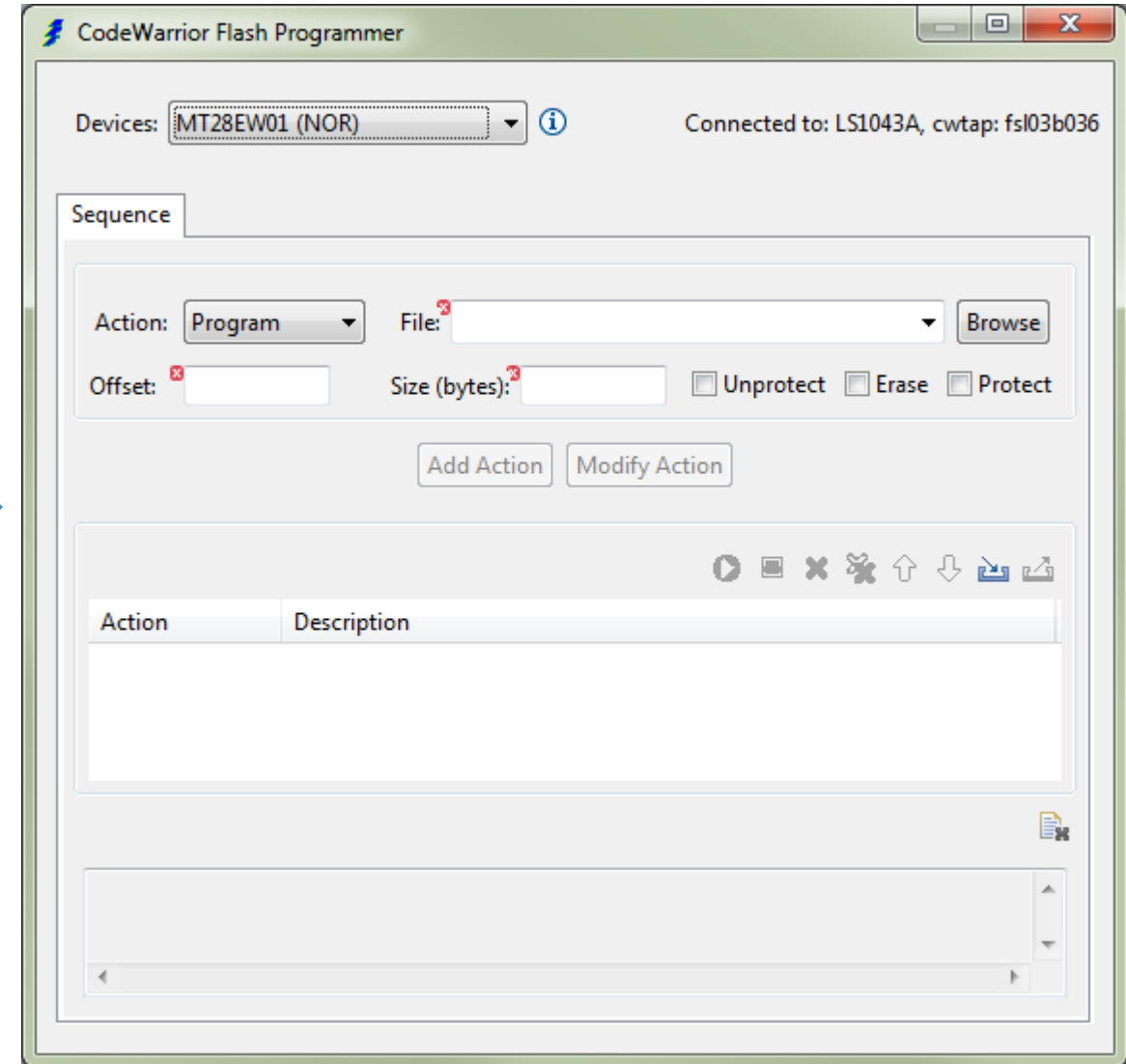
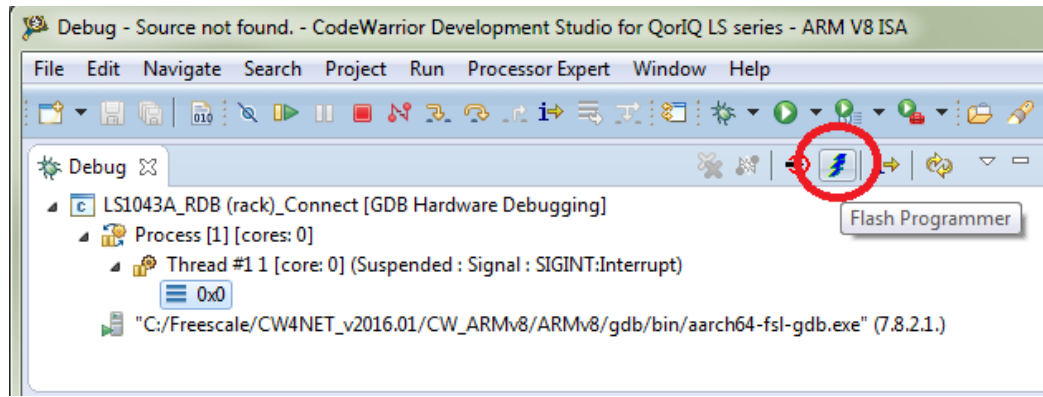
# Transferring images to the board: CodeWarrior

- CodeWarrior can be used to transfer images to a blank board
- Flash the following images for U-Boot:
  - U-Boot binary
  - RCW
  - FMan Microcode
- Details can be found in user guide on NXP.com or under [x]:\Freescale\CW4NET\_v2016.01\CW\_ARMv8\ARMv8\Help\PDF where x: is the volume under which CW is installed
- Use CodeWarrior tool to flash SDK images to current bank addresses shown on previous slide
- Launch a debug session using the Connect button in the Target Connections view



- After the debug session is up, click on the Flash Programmer button to bring up the Flash Programmer menu

# Transferring images to the board: CodeWarrior





# Transferring Images to the board: TFTP

- TFTP can be used to flash images to alternate bank from current bank

- Programming a new U-Boot

```
=>tftp 82000000 <u-boot_file_name>.bin  
=>protect off 64100000 +$filesize  
=>erase 64100000 +$filesize  
=>cp.b 82000000 64100000 $filesize  
=>protect on 64100000 +$filesize  
=>cpld reset altbank
```

- Programming a new RCW

```
=>tftp 82000000 <rcw_file_name>.bin  
=>protect off 64000000 +$filesize  
=>erase 64000000 +$filesize  
=>cp.b 82000000 64000000 $filesize  
=>protect on 64000000 +$filesize  
=>cpld reset altbank
```

- Programming a new FMan ucode

```
=>tftp 82000000 <fman_ucode_file_name>.bin  
=>protect off 64300000 +$filesize  
=>erase 64300000 +$filesize  
=>cp.b 82000000 64300000 $filesize  
=>protect on 64300000 +$filesize  
=>cpld reset altbank
```



# U-Boot: Ethernet and PCI Sanity Checks

```
=> mdio list
FSL_MDIO0:
1 - RealTek RTL8211F <--> FM1@DTSEC3
2 - RealTek RTL8211F <--> FM1@DTSEC4
4 - Vitesse VSC8514 <--> FM1@DTSEC1
5 - Vitesse VSC8514 <--> FM1@DTSEC2
6 - Vitesse VSC8514 <--> FM1@DTSEC5
7 - Vitesse VSC8514 <--> FM1@DTSEC6
FM_TGEC_MDIO:
1 - Aquantia AQR105 <--> FM1@TGEC1
```

## PCIe Information

```
=> pci 0
Scanning PCI devices on bus 0
BusDevFun  VendorId  DeviceId  Device Class      Sub-Class
-----
00.00.00   0x1957   0x8084    Bridge device      0x04
=> pci 1
Scanning PCI devices on bus 1
BusDevFun  VendorId  DeviceId  Device Class      Sub-Class
-----
01.00.00   0x8086   0x10d3    Network controller 0x00
=>
```

# FINAL PHASE: POST BOOT & BEYOND

Suggested sessions: FTF-DES-N1853



# U-boot environment settings and memory map

```
=> print
baudrate=115200
bootargs=console=ttyS0,115200 root=/dev/ram0 earlycon=uart8250,0x21c0500,115200
bootcmd=cp.b $kernel_start $kernel_load $kernel_size && bootm $kernel_load
bootdelay=3
console=ttyAMA0,38400n8
eth1addr=00:e0:0c:00:77:01
eth2addr=00:e0:0c:00:77:02
eth3addr=00:e0:0c:00:77:03
eth4addr=00:e0:0c:00:77:04
eth5addr=00:e0:0c:00:77:05
eth6addr=00:e0:0c:00:77:06
ethact=FM1@DTSEC1
ethaddr=00:e0:0c:00:77:00
ethprime=e1000#0
fman_ucode=60300000
gatewayip=192.168.1.1
hwconfig=fsl_ddr:bank_intlv=auto
ipaddr=192.168.1.100
kernel_addr=0x100000
kernel_load=0xa0000000
kernel_size=0x2800000
kernel_start=0x61100000
loadaddr=0x80100000
ramdisk_addr=0x800000
ramdisk_size=0x2000000
serverip=192.168.1.1
stderr=serial
stdin=serial
stdout=serial
```

| Start address | End address | Image   | Max size |
|---------------|-------------|---|----------|
| 0x60000000    | 0x6001FFFF  | RCW (current bank)  | 128KB    |
| 0x60100000    | 0x6017FFFF  | u-boot (current bank)   | 512KB    |
| 0x60300000    | 0x6031FFFF  | Fman ucode (current bank)                                       | 128KB    |
| 0x61100000    | 0x6203FFFF  | Linux.ulimage, Device Tree and Ramdisk (current bank) FIT Image | 15MB     |
| 0x64000000    | 0x6401FFFF  | RCW (alt bank)  | 128KB    |
| 0x64100000    | 0x6417FFFF  | u-boot (alt bank)   | 512KB    |
| 0x64300000    | 0x6431FFFF  | Fman ucode (alt bank)   | 128KB    |
| 0x65100000    | 0x6603FFFF  | Linux.ulimage, Device Tree and Ramdisk (alt bank) FIT Image     | 15MB     |

# Linux Images

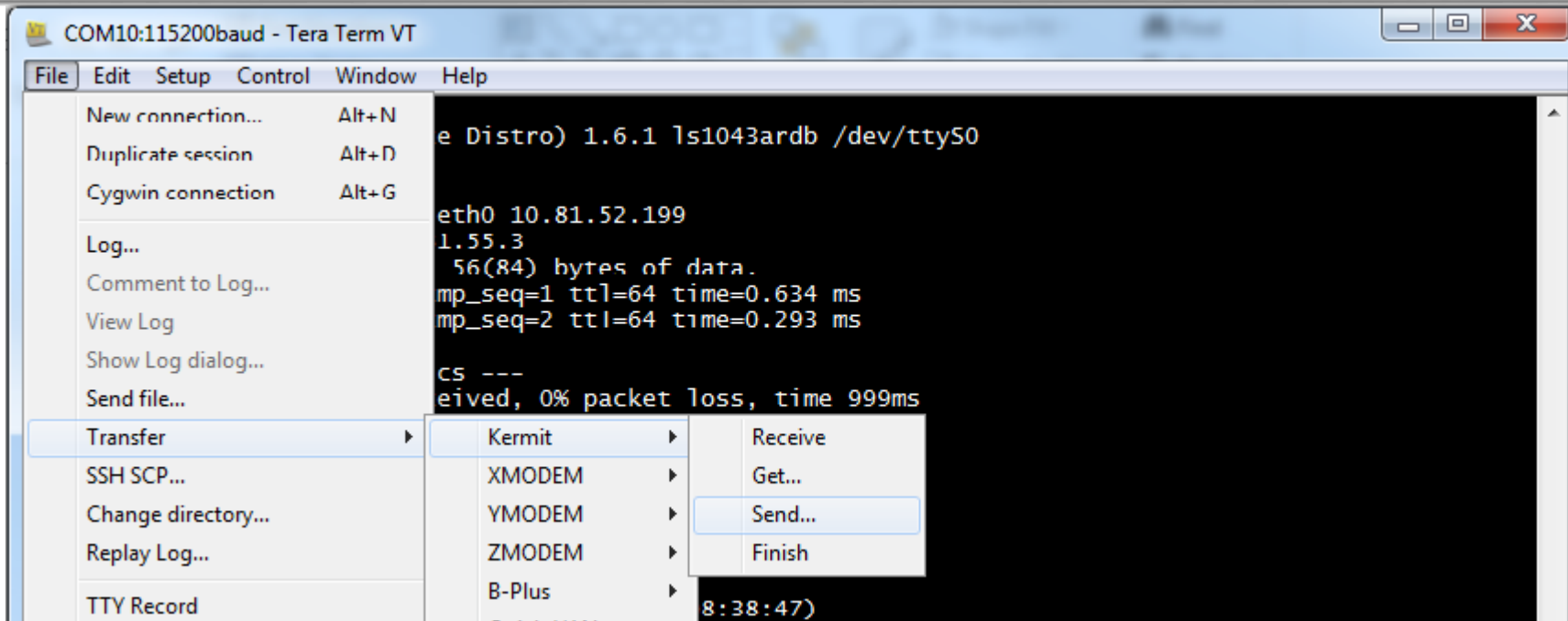
- Options for loading Linux images onto board
  - Use TFTP from PC
  - Use Serial Port from PC

# Using TFTP to Load Linux Images and Boot

- Set up TFTP server on your PC
- Make sure IP Address of PC is same as serverip set previously
- Ping serverip to make sure a live link is available
  - =>ping \$serverip
- TFTP itb image and flash it to the NOR flash vBank0 using following commands
  - =>tftp a0000000 kernel-ls1043ardb.itb
  - =>erase 61100000 +\$filesize
  - =>cp.b a0000000 61100000 \$filesize
- Use command: “boot” to bring up linux

# Using Serial Port to Load Linux Images

```
=> loadb
## Ready for binary (kermit) download to 0x80100000 at 115200 bps...
## Total Size      = 0x00000088 = 136 Bytes
## Start Addr      = 0x80100000
=> md 0x80100000
80100000: 55aa55aa 0001ee01 08000b08 0000000a    .U.U.....
80100010: 00000000 00000000 02005514 02400080    .....U....@.
80100020: 005002e0 002400c1 00000000 00000000    ..P...$.....
80100030: 00000000 00880300 00000000 00110000    .....
=>
```





SECURE CONNECTIONS  
FOR A SMARTER WORLD