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Revision history

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1. Introduction

The OM13518 dongle is an easy to use interface handler between the USB of a PC and the I²C-bus. The software control via a Graphical User Interface (GUI) allows a fast start to communicate with different circuits.

- USB-2 is used for data and the 5 V power supply.
- Three I²C-bus ports are wired in parallel.
- Cables to connect up the I²C-bus are enclosed.

2. Key features

2.1 USB-I²C interface module

The OM13518 dongle is a ready to run module. It creates a virtual COM-port via an USB connection. It provides three I²C-bus connections with 5 V option to power the application (max 450 mA).

- **Power consumption**: module/total: <50 mA/max 500 mA
- **I²C-bus clock frequency**: 245 Hz – 400 kHz
- **USB driver for Windows**: Windows XP, Windows 7, Windows 8
- **Size**: 50 mm × 40 mm × 15 mm

2.2 Software

The software control via a GUI allows a fast start to communicate to the different circuits.

Aside from the detailed GUI pages for the Real-Time Clocks, a UNIVERSAL INTERFACE allows to communicate with any I²C-bus device by entering directly the hex codes. Example: s A2 28 p

Where s stands for the I²C START and p for the I²C STOP condition.
3. Dongle

3.1 Circuit diagram

The dongle establishes the connection between the PC (USB port) and the I²C-bus interface.

![Simplified Block diagram of the OM13518](image)

3.2 Interfacing I²C-bus peripherals

The I²C-bus peripherals are connected directly with the I²C-bus. The 3 connectors Con1, Con2, and Con3 are connected in parallel and carry the four signals as also imprinted on the package:

- **+5 V**: Optional 5 V supply can be used. Total consumption of all 3 outputs must be kept below 450 mA.
- **SCL**: Serial CLock line
- **SDA**: Serial DAta line
- **GND**: Ground
In case that the periphery is connected to the +5V from the OM13518 no \( V_{DD} \) connection must be used.

**Fig 2. Interfacing to the \( \text{i}^2\text{c}-\text{bus} \)**

There is no need for external pull-up resistors, since 10 kΩ pull-ups are already built in the OM13518 dongle.

### 4. Installation

#### 4.1 Hardware and driver installation

**4.1.1 The box contains:**
- One dongle
- One USB cable
- Three \( \text{i}^2\text{C} \)-bus cables:
  - One with female connector dedicated for NXP-RTC evaluation boards
  - Two cables for custom use via solder connection
  - The signal assignment is imprinted on the interface module

**Fig 3. A) Dongle OM13518, B) connected to an evaluation board**
4.1.2 Driver

First install the USB software driver before connecting the interface module.

- Unpack the file: `cp210x_vcp_win_xp_s2k3_vista_7_8_v6_6_1.zip`
- Install the driver in administrator mode

4.1.3 Hardware

1. Connect the USB cable with the dongle and with the PC and let the device to install. Connect the I²C-bus cable to your application; turn on the power in case an external one is needed.
2. The red LED will light up to indicate that the OM13518 successfully started up.
3. Now the system is ready for starting the GUI software

4.2 GUI Installation

1. Unpack the file `NXP_USB-I2C-RTC_GUI_V02.zip`. The latest version can be downloaded from the OM13518 home page.
2. Run the exe file: `NXP_USB-I2C-RTC_GUI_V02.exe`
3. A start window will pop up
4. Choose the right com port in the drop down list
5. Press Connect: Status changes to **Connected** and turns green

![Start window of the GUI](image-url)
5. Features of the Graphical User Interface (GUI)

The GUI can be used as a universal I²C-bus interface for controlling any peripheral circuit. Alternatively some specific windows are available e.g. for the Real-Time Clocks PCF85263 and PCF85363.

5.1 Universal I²C-bus interface

The Universal I²C interface allows controlling any circuit by entering directly the I²C-bus instructions. It is part of the Tab USB-I²C Commands.

Procedure and details:

1. Universal I²C-bus interface control, type in the following format:
   - Writing data, e.g.: \texttt{s A2 28 04 p} press Send Command
     \(s = \text{START}, A2 = \text{slave address}, 28 \ 04 = \text{data}, p = \text{STOP}\)
   - Reading data, e.g.: \texttt{s A2 28 s A3 0A p}: press Send Command
     setting address pointer, then reading 10 bytes (0Ah)
2. The sent data will be reflected in the field Transmitted Data.
3. The read data bytes are listed in the field Received Data.
4. Configuration can be saved on the PC (see section 5.2.1).
5. Configuration can be reloaded to continue with the used presetting for further tasks (see section 5.2.1.2).
6. Tabs on the GUI of the RTCs: PCF85263, PCF85363, to follow
7. Hovering the mouse-pointer over a function button, tool tips will pop up for explanations.
8. Pressing ▼ will open the list of possible options to select from.

**Fig 6. Hovering the mouse-pointer and drop-down menus**

### 5.2 GUI pages for the RTC PCF85263 and PCF85363

The objective is to have a fast and straightforward control of all the functions of the RTC. The principle for controlling is explained on the window *Time, Alarms, Timestamps* in Fig 7.
5.2.1 Save and read back the configuration

5.2.1.1 All the setting can be saved

1. Work with the GUI until you have the IC configured as desired.
2. Save the desired configuration to a file as follows: USB-I2C-Commands tab, Save Configuration, select a directory and name (see Fig 8).
3. If the GUI succeeds in writing the file, it will produce a pop-up window and then just press OK (see Fig 9).

![Confirmation window](image-url)
File Format:
The file is written in standard XML format, which almost all Operating Systems can read (see Fig 10).

```
- <ConfigData>
  - <Registers>
    <RegName>tsm_cfg_byte_b0</RegName>
    <RegValue>0</RegValue>
  </Registers>
  - <Registers>
    <RegName>tsm_cfg_byte_b1</RegName>
    <RegValue>0</RegValue>
  </Registers>
  - <Registers>
    <RegName>tsm_cfg_byte_b2</RegName>
    <RegValue>0</RegValue>
  </Registers>
```

Fig 10. XML format example

5.2.1.2 Reload the settings
1. Read back a saved configuration file with Read Configuration (see Fig 11):

![Selecting the directory and file](image-url)
2. If the GUI manages to read in the files successfully, it will produce a pop-up window and then just press OK (see Fig 12).

![Confirmation window](image)

**Fig 12. Confirmation window**

### 5.3 Examples

#### 5.3.1 Setting the clock and reading it

1. Perform a Software reset: Reset tab, function SWR (see Fig 13).

![Reset of the software](image)

**Fig 13. Reset of the software**

2. Select menu Special Registers and press SWR.
3. Set the time and read back to verify that the clock is running (see Fig 7).
   - A valid time and date can be entered in the Set row, then press EXECUTE
   - The SET TIME programs the actual time based on your PC (see Fig 7 and Fig 14).
   - READ reads the current time and date of the RTC (see Fig 7 and Fig 14).
• **START** will continuously read the time at about once every second (see Fig 7 and Fig 14).

There are options to change from 24 hour to 12 hour mode, activate the 1/100s resolution and change the RTC from RTC mode (clock mode) to stop watch mode (see Fig 7 and Fig 14).

![Time control](image)

**Fig 14. Time control**

### 5.3.2 Blinking the LED at the interrupt output with the help of the watchdog

Procedure and details:

1. Perform a Software reset: Reset tab, function SWR (see Fig 15).

![Software reset](image)

**Fig 15. Software reset**
2. Enable \textit{INTA} for interrupt mode (see Fig 16).

![Fig 16. Enable the INTA for interrupt mode](image)

3. Enable \textit{INTA} for Watchdog (pulse at each time countdown occurs) (see Fig 17).

![Fig 17. Enable the INTA for Watchdog](image)
4. Enable the watchdog for a repeat every 2 seconds for example (see Fig 18).

![Fig 18. Enable the watchdog for a repeat every 2 seconds](image)

5. Observe the LED flashing every 2 seconds!!!

5.3.3 **Interactive quartz frequency offset correction:**

The quartz crystals come with a tolerance of typical ± 20 ppm. To correct the actual offset of the quartz in use, take the following steps:

1. Measure the frequency at CLKout pin, e.g. 32 768.51 Hz
2. Write the measured frequency in the entry field, it automatically calculates the offset and the needed correction value. 15.19 ppm or 7 correction pulses.
3. By activating **SET BYTE** the offset value is programmed in to the RTCs offset register.

**Note:** The offset calibration operates at the time counter level and will not result in any observable change in frequency.

![Fig 19. Offset correction](image)
5.3.4 Dedicated drop down menus are integrated for e.g.:
- Register overview: reading all the values at once
- Back-up battery control
- Timestamp
- Watch dog
- RAM
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